

**BỘ GIÁO DỤC VÀ ĐÀO TẠO**  
**TRƯỜNG ĐẠI HỌC SƯ PHẠM KỸ THUẬT TP.HCM**  
**KHOA ĐIỆN – ĐIỆN TỬ**  
**BỘ MÔN ĐIỆN TỬ CÔNG NGHIỆP**



**VI XỬ LÝ 2**

**ĐỀ TÀI: BÁO CÁO VI XỬ LÝ II**

**LỚP 061012**

***Người soạn: Nguyễn Duy Tường***



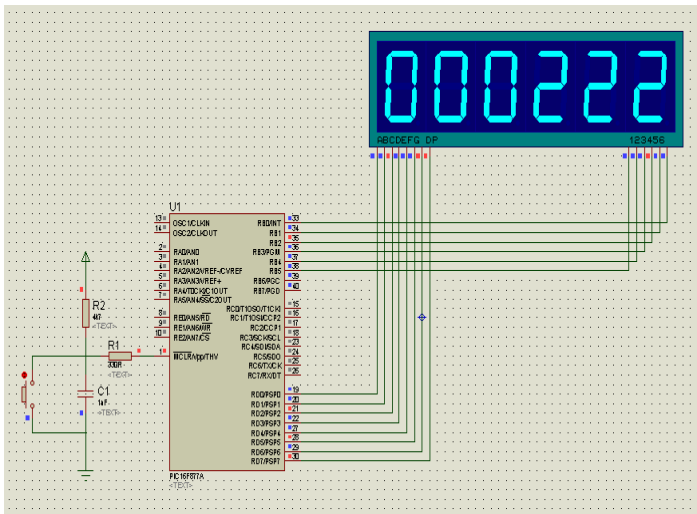
*Tp. Hồ Chí Minh 1/2010*

# MỤC LỤC

- Trang 3: DÙNG PIC 16F877A ĐIỀU KHIỂN 6 LED 7 ĐOẠN ĐẾM GIÂY, PHÚT, GIỜ, DÙNG NGÔN NGỮ ASSEMBLY.
- Trang 6: DÙNG PIC 16F877A ĐIỀU KHIỂN 6 LED 7 ĐOẠN ĐẾM GIÂY, PHÚT, GIỜ, DÙNG NGÔN NGỮ C.
- Trang 9: DÙNG PIC 16F877A ĐIỀU KHIỂN 3 LED 7 ĐOẠN LÀM MẠCH ĐẾM SẢN PHẨM, DÙNG NGÔN NGỮ ASSEMBLY – DÙNG TIMER0.
- Trang 11: DÙNG PIC 16F877A ĐIỀU KHIỂN 3 LED 7 ĐOẠN LÀM MẠCH ĐẾM SẢN PHẨM, DÙNG NGÔN NGỮ C – DÙNG TIMER1.
- Trang 13: DÙNG PIC 16F877A ĐIỀU KHIỂN 4 LED 7 ĐOẠN, 6 LED ĐƠN LÀM MẠCH ĐIỀU KHIỂN ĐÈN GIAO THÔNG. THỜI GIAN CHO ĐÈN XANH LÀ 20 GIÂY, VÀNG 5 GIÂY, ĐỎ 25 GIÂY, DÙNG NGÔN NGỮ ASSEMBLY – DÙNG TIMER1 LÀM BỘ ĐỊNH THỜI.
- Trang 18: DÙNG PIC 16F877A ĐIỀU KHIỂN 4 LED 7 ĐOẠN, 6 LED ĐƠN LÀM MẠCH ĐIỀU KHIỂN ĐÈN GIAO THÔNG. THỜI GIAN CHO ĐÈN XANH LÀ 20 GIÂY, VÀNG 5 GIÂY, ĐỎ 25 GIÂY, TIMER1, DÙNG NGÔN NGỮ C.
- Trang 22: DÙNG PIC 16F877A GIAO TIẾP LCD 16x2 LÀM MẠCH ĐẾM SẢN PHẨM, DÙNG NGÔN NGỮ ASSEMBLY DÙNG TIMER1.
- Trang 27: DÙNG PIC 16F877A GIAO TIẾP LCD 16x2 LÀM MẠCH ĐẾM SẢN PHẨM, DÙNG NGÔN NGỮ C – DÙNG TIMER0.
- Trang 30: DÙNG PIC 16F877A GIAO TIẾP VỚI 3 LED 7 ĐOẠN VÀ CẢM BIẾN NHIỆT ĐỘ LM35 NỐI NGÕ VÀO KÊNH THỨ 0, LẬP TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ ASSEMBLY.
- Trang 33: DÙNG PIC 16F877A GIAO TIẾP VỚI 3 LED 7 ĐOẠN VÀ CẢM BIẾN NHIỆT ĐỘ LM35 NỐI NGÕ VÀO KÊNH THỨ 0, LẬP TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ C.
- Trang 35: KHẢO SÁT TRUYỀN DỮ LIỆU SPI.
- Trang 37: KHẢO SÁT TRUYỀN DỮ LIỆU USART. ASSEMBLY & C
- Trang 43: DÙNG PIC 16F877A ĐIỀU KHIỂN 1 LCD 16x2 ĐỂ ĐO NHIỆT ĐỘ CỦA NGÕ VÀO KÊNH THỨ 0 DÙNG CẢM BIẾN LM35, DÙNG NGÔN NGỮ ASSEMBLY.
- Trang 48: DÙNG PIC 16F877A ĐIỀU KHIỂN 1 LCD 16x2 ĐỂ ĐO NHIỆT ĐỘ CỦA NGÕ VÀO KÊNH THỨ 0 DÙNG CẢM BIẾN LM35, DÙNG NGÔN NGỮ C.
- Trang 50: DÙNG PIC 16F877A GIAO TIẾP VỚI REALTIME DS13B07 VÀ 6 LED 7 ĐOẠN, VIẾT CHƯƠNG TRÌNH ĐỒNG HỒ SỐ DÙNG NGÔN NGỮ ASSEMBLY.
- Trang 55: DÙNG PIC 16F877A GIAO TIẾP VỚI REALTIME DS13B07 VÀ 6 LED 7 ĐOẠN, VIẾT CHƯƠNG TRÌNH ĐỒNG HỒ SỐ DÙNG NGÔN NGỮ C.
- Trang 59: DÙNG PIC 16F877A GIAO TIẾP VỚI DS18B20 (CẢM BIẾN NHIỆT VÀ CÓ LUÔN ADC – ONE WIRE) VÀ 3 LED 7 ĐOẠN, VIẾT CHƯƠNG TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ ASSEMBLY.
- Trang 64: DÙNG PIC 16F877A GIAO TIẾP VỚI DS18B20 (CẢM BIẾN NHIỆT VÀ CÓ LUÔN ADC – ONE WIRE) VÀ 3 LED 7 ĐOẠN, VIẾT CHƯƠNG TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ C.
- Trang 66: DÙNG PIC 16F877A GIAO TIẾP VỚI DS18B20 (CẢM BIẾN NHIỆT VÀ CÓ LUÔN ADC – ONE WIRE) VÀ LCD 16x2, VIẾT CHƯƠNG TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ ASSEMBLY
- Trang 70: DÙNG PIC 16F877A GIAO TIẾP VỚI 74HC595

# BÁO CÁO: VI XU LY 2

## BÀI 1 : THIẾT KẾ ĐỒNG HỒ SỐ DÙNG PIC 16F877A ĐÈM GIỜ, PHÚT ,GIÂY DÙNG NGÔN NGỮ ASSEMBLY



; BAO CAO VI XU LY 2

;Ten chương trình: dong ho so dung VDK Pic 16F877A

;\*\*\*\*\*

TITLE " dong ho so dung PIC 16F877A"

PROCESSOR P16F877A

INCLUDE <P16F877A.inc>

\_\_CONFIG\_CP\_OFF & \_PWRTE\_ON & \_WDT\_OFF &

\_HS\_OSC & \_LVP\_OFF

;\*\*\*\*\*

;chương trình

;

;----- khai bao bien-----

CBLOCK 0x020

COUNT1

COUNT2

COUNT3

GIAY\_DV

GIAY\_CHUC

PHUT\_DV

PHUT\_CHUC

GIO\_DV

GIO\_CHUC

BIEN\_GIAY\_DV

BIEN\_GIAY\_CHUC

BIEN\_PHUT\_DV

BIEN\_PHUT\_CHUC

BIEN\_GIO\_DV

BIEN\_GIO\_CHUC

ENDC

;\*\*\*\*\*

ORG 0x000

CLRF STATUS

MOVLW 0x00

MOVWF PCLATH

GOTO START

;\*\*\*\*\*

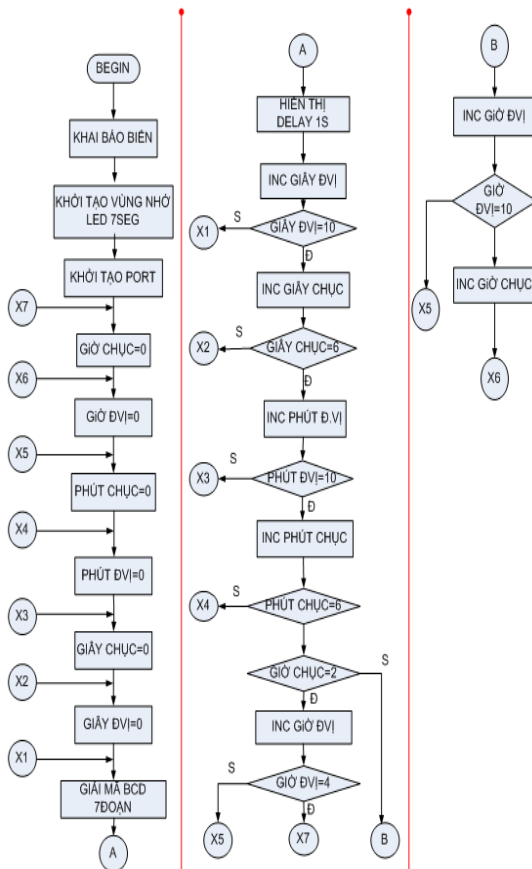
;

; KHOI TAO

\*\*\*\*\*

;KHOI TAO PORT B DIEU KHIEN 6 TRANSISTOR QUET HANG

;KHOI TAO PORT D KET NOI VOI 8 CHAN CUA LED 7 DOAN



```

START      ORG 0x006
BCF        STATUS,RP1
BSF        STATUS,RP0      ; LUA CHON BANK 1
CLRF       TRISB           ; PORT B XUAT DATA
CLRF       TRISD           ; PORT D XUAT DATA
BCF        STATUS,RP0      ; TRO VE BANK 0

```

```

;*****
;

```

### ;chuongtrinhchinh

```

;*****
;

```

```

;=====KHOI TAO GIA TRI BAN DAU=====

```

```

X7  MOVLW  0x00
    MOVWF  GIO_CHUC  ;CHO GIO PHUT GIAY = 0
X6  MOVLW  0x00
    MOVWF  GIO_DV
X5  MOVLW  0x00
    MOVWF  PHUT_CHUC
X4  MOVLW  0x00
    MOVWF  PHUT_DV
X3  MOVLW  0x00
    MOVWF  GIAY_CHUC
X2  MOVLW  0x00
    MOVWF  GIAY_DV

```

```

;=====

```

```

X1  CALL   BCD_7DOAN
    CALL   DELAY_HIEN_THI

```

```

;=====

```

```

INCF     GIAY_DV      ;TANG GIAY_DV
MOVF     GIAY_DV,0    ;NAP GIAY_DV VAO T G W
XORLW    D'10'       ;SO SANH GIAY_DV VOI 10,Z=1
BTFS    STATUS,Z     ;kiem tra bit Z va nhay neu
Z=1(bo qua lenh GOTO) co nghia la giay don vi=10
GOTO     X1

```

```

INCF     GIAY_CHUC    ;TANG GIAY_CHUC
MOVF     GIAY_CHUC,0  ;NAP GIAY_CHUC VAO TG W
XORLW    D'6'         ;SO SANH GIAY_CHUC VOI 6,Z=1
NEU GIAY_CHUC=6,NGUOC LAI Z=0
BTFS    STATUS,Z     ;KIEM TRA Z,NHAY KHI Z=1
GOTO     X2          ;VE X2 NEU Z=0

```

```

INCF     PHUT_DV      ;TANG PHUT_DV
MOVF     PHUT_DV,0    ;NAP PHUT_DV VAO TG W
XORLW    D'10'       ;SO SANH PHUT_DV VOI 10,Z=1
NEU GIAY_CHUC=10,NGUOC LAI Z=0
BTFS    STATUS,Z     ;KIEM TRA Z,NHAY KHI Z=1

```

```

GOTO     X3          ;VE X3 NEU Z=0

```

```

INCF     PHUT_CHUC    ;TANG PHUT_CHUC
MOVF     PHUT_CHUC,0  ;NAP PHUT_CHUC VAO TG W
XORLW    D'6'         ;SO SANH PHUT_CHUC VOI
6,Z=1 NEU GIAY_CHUC=6,NGUOC LAI Z=0
BTFS    STATUS,Z     ;KIEM TRA Z,NHAY KHI Z=1
GOTO     X4          ;VE X4 NEU Z=0

```

```

;=====

```

```

MOVF     GIO_CHUC,0
XORLW    D'2'
BTFS    STATUS,Z
GOTO     X10
GOTO     X11

```

```

X10  INCF     GIO_DV
    MOVF     GIO_DV,0
    XORLW    D'10'
    BTFS    STATUS,Z
    GOTO     X5
    INCF     GIO_CHUC
    GOTO     X6
X11  INCF     GIO_DV
    MOVF     GIO_DV,0
    XORLW    D'4'
    BTFS    STATUS,Z
    GOTO     X5
    GOTO     X7

```

```

;=====

```

### BCD\_7DOAN

```

MOVF     GIAY_DV,0    ;MOV (GIAY_DV) VAO W
CALL     TABLE
MOVWF    BIEN_GIAY_DV ;MOV (GIAY_DV) VAO
BIEN_GIAY_DV
MOVF     GIAY_CHUC,0 ;MOV (GIAY_CHUC)
VAO W
CALL     TABLE
MOVWF    BIEN_GIAY_CHUC ;MOV (GIAY_CHUC)
VAO BIEN_GIAY_CHUC

```

```

MOVF     PHUT_DV,0    ;MOV (PHUT_DV) VAO W
CALL     TABLE
MOVWF    BIEN_PHUT_DV ;MOV (PHUT_DV)VAO BIEN
PHUT_DV

```

```

MOVF     PHUT_CHUC,0 ;MOV (PHUT_CHUC)
VAO W
CALL     TABLE
MOVWF    BIEN_PHUT_CHUC ;MOV (PHUT_CHUC)
VAO BIEN_PHUT_CHUC

```

```

MOVF      GIO_DV,0           ;MOV (GIO_DV) VAO W
CALL      TABLE
MOVWF     BIEN_GIO_DV       ;MOV (GIO_DV) VAO BIEN_GIO_DV

MOVF      GIO_CHUC,0        ;MOV (GIO_CHUC) VAO W
CALL      TABLE
MOVWF     BIEN_GIO_CHUC     ;MOV (GIO_CHUC) VAO
BIEN_GIO_CHUC

RETURN

;=====
DELAY_HIEN_THI
MOVLW     0x2               ;NAP 01 VAO W
MOVWF     COUNT1           ;MOV 01 VAO COUNT1
DEL1
MOVLW     0x18              ;NAP 1 VAO W
MOVWF     COUNT2           ;MOV 1 VAO COUNT2
DEL2
CALL      HIEN_THI
DECFSZ    COUNT2           ;GIAM COUNT2,KHI BANG 0 THI
NHAY XUONG GIAM COUNT1
GOTO DEL2
DECFSZ    COUNT1           ;GIAM COUNT1,KHI BANG 0 THI
BO QUA LENH KE
GOTO     DEL1
RETURN

;=====
HIEN_THI
MOVF      BIEN_GIAY_DV,0    ;HIEN THI GIAY-DONVI
MOVWF     PORTD
MOVLW     0x1
MOVWF     PORTB
CALL      DELAY

;=====
MOVLW     0X00              ;CHONG LEM
MOVWF     PORTB
MOVLW     0xff
MOVWF     PORTD

;=====
MOVF      BIEN_GIAY_CHUC,0  ;HIEN THI GIAY_CHUC
MOVWF     PORTD
MOVLW     0x2
MOVWF     PORTB
CALL      DELAY

MOVLW     0X00
MOVWF     PORTB
MOVLW     0xff
MOVWF     PORTD

;=====
MOVF      BIEN_PHUT_DV,0    ;HIEN THI PHUT-DON VI
MOVWF     PORTD
MOVLW     0x4
MOVWF     PORTB
CALL      DELAY

MOVLW     0X00
MOVWF     PORTB
MOVLW     0XFF
MOVWF     PORTD

MOVF      BIEN_PHUT_CHUC,0  ;HIEN THI PHUT_CHUC
MOVWF     PORTD
MOVLW     0x8
MOVWF     PORTB
CALL      DELAY

MOVLW     0X00
MOVWF     PORTB
MOVLW     0XFF
MOVWF     PORTD

MOVF      BIEN_GIO_DV,0     ;HIEN THI GIO_DONVI
MOVWF     PORTD
MOVLW     0x10
MOVWF     PORTB
CALL      DELAY

MOVLW     0X00
MOVWF     PORTB
MOVLW     0XFF
MOVWF     PORTD

MOVF      BIEN_GIO_CHUC,0   ;HIEN THI GIO_CHUC
MOVWF     PORTD
MOVLW     0x20
MOVWF     PORTB
CALL      DELAY

MOVLW     0X00
MOVWF     PORTB
MOVLW     0XFF
MOVWF     PORTD

RETURN

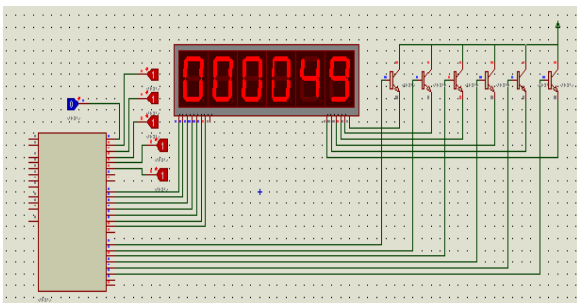
;=====
DELAY
MOVLW     0xFF
MOVWF     COUNT3
DELAY1
DECFSZ    COUNT3

```

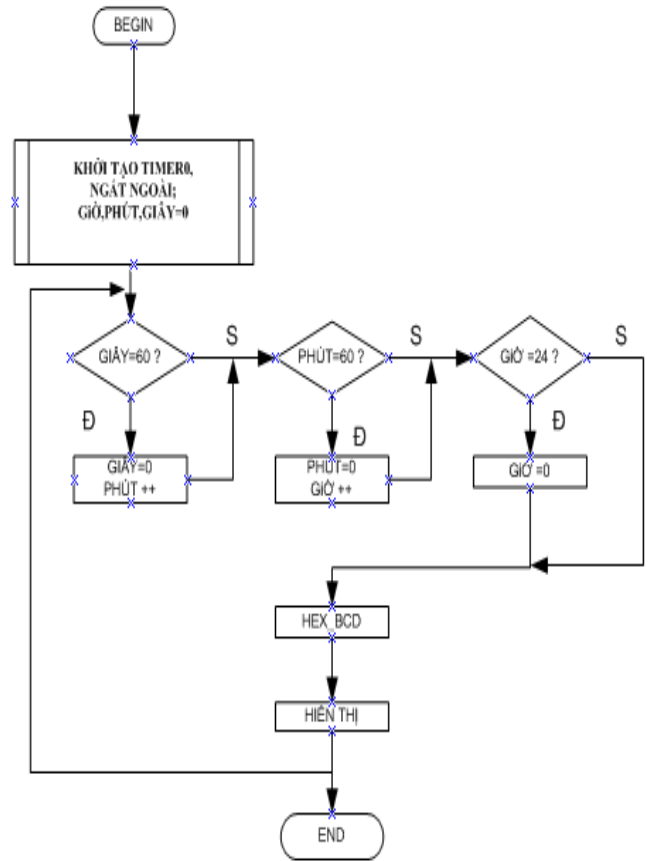
```
GOTO     DELAY1  
RETURN
```

```
=====  
TABLE  
ADDWF PCL,1  
DT 0xC0, 0xF9, 0xA4, 0xB0, 0x99, 0x92, 0x82, 0xF8,  
0x80, 0x90  
END
```

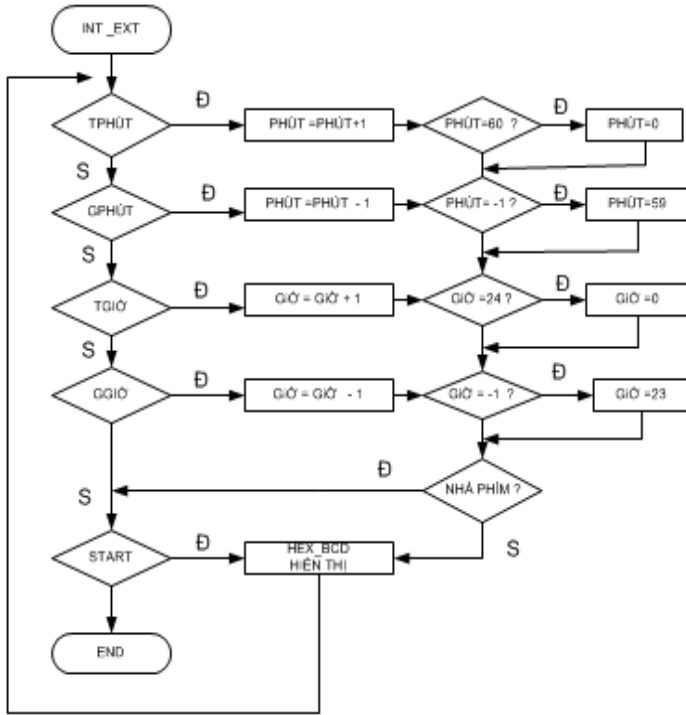
**Bài 2: Dùng PIC 16F877a điều khiển 6 led 7  
đoạn đếm giờ ,phút ,giây. Dùng C**



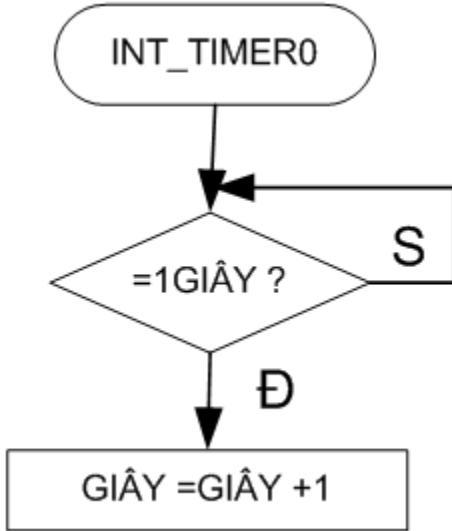
chương trình chính



Chương trình ngắt



Ngắt timer 0



**CHƯƠNG TRÌNH**

```

#include <16F877A.h>
#include <khaibaotghi_16f877a.h>
    
```

```

#fuses NOWDT,PUT,XT,NOPROTECT,HS,NOLVP
#use delay(clock=1000000)
#use fast_io(b)
#use fast_io(d)
#use fast_io(c)
#bit start=portb.1
#bit tphuc=portb.2
#bit gphuc=portb.3
#bit tgio=portb.4
#bit ggio=portb.5
int16 count;
int8
giay,phuc,gio,dvgiay,chgiay,dvphuc,chphuc,dvgio,chgio,i;
const unsigned char
dig[]={ 0xc0,0xf9,0xa4,0xb0,0x99,0x92,0x82,0xf8,0x80,0x9
0}
    
```

**//ma 7 doan**

**void hex\_bcd()**

```

{ chgiay=giay/10;
  dvgiay=giay%10;
  chphuc=phuc/10;
  dvphuc=phuc%10;
  chgio=gio/10;
  dvgio=gio%10;}
    
```

**void nhienthi()**

```

{ i=0;
  while(i<5)
  { output_high(pin_d0);
    portc=dig[dvgiay];
    delay_ms(1);
    output_low(pin_d0);
    output_high(pin_d1);
    portc=dig[chgiay];
    delay_ms(1);
    output_low(pin_d1);
    
```

```

    output_high(pin_d2);
    portc=dig[dvphuc];
    delay_ms(1);
    output_low(pin_d2);
    
```

```

    output_high(pin_d3);
    portc=dig[chphuc];
    
```

```

delay_ms(1);
output_low(pin_d3);

output_high(pin_d4);
portc=dig[dvgio];
delay_ms(1);
output_low(pin_d4);

output_high(pin_d5);
portc=dig[chgio];
delay_ms(1);
output_low(pin_d5);
i=i+1; }}
#int_ext
void ngat_ngoai()
{ while (true)
  { if (tphuc==0)
    { phuc=phuc+1;
      goto loop;
    }
    if (gphuc==0)
    { phuc=phuc-1;
      goto loop;
    }
    if (tgio==0)
    { gio=gio+1;
      goto loop;
    }
    if (ggio==0)
    { gio=gio-1;
      goto loop; }
    goto lap1;

loop:
  if (phuc==60)
  { phuc=0; }
  if (phuc==-1)
  { phuc=59;}
  if (gio==24)
  { gio=0; }
  if (gio==-1)
  { gio=23;}
lap: nhienthi();
  if (tphuc==0||gphuc==0||tgio==0||ggio==0)

```

```

    { goto lap;}
lap1:
  if (start==0)
  { break; }
  hex_bcd();
  nhienthi(); }}
//Chuong trinh ngat TMR0
#int_timer0
void interrupt_timer0()
{ set_timer0(6);
  ++count;
  if(count ==500)
  { count=0;
    giay=giay+1; }}

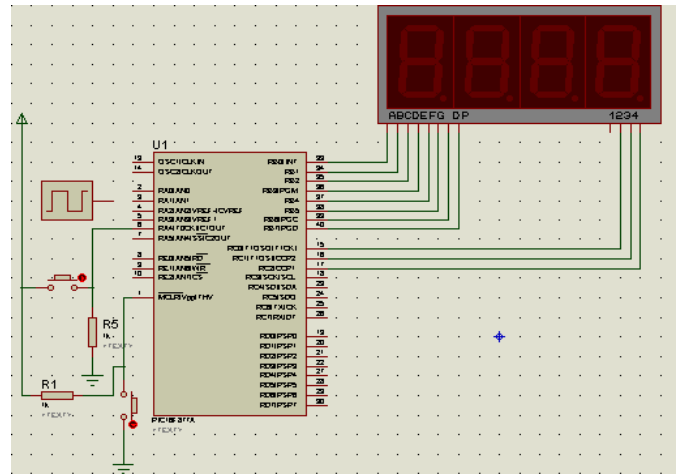
void hienthi()
{ i=0;
  while(i<5)
  { output_high(pin_d0);
    portc=dig[dvgiay];
    delay_ms(1);
    output_low(pin_d0);
    output_high(pin_d1);
    portc=dig[chgiay];
    delay_ms(1);
    output_low(pin_d1);
    output_high(pin_d2);
    portc=dig[dvphuc];
    delay_ms(1);
    output_low(pin_d2);
    output_high(pin_d3);
    portc=dig[chphuc];
    delay_ms(1);
    output_low(pin_d3);
    output_high(pin_d4);
    portc=dig[dvgio];
    delay_ms(1);
    output_low(pin_d4);
    output_high(pin_d5);
    portc=dig[chgio];
    delay_ms(1);
    output_low(pin_d5);
    i=i+1; }}
//Chuong trinh chinh

```

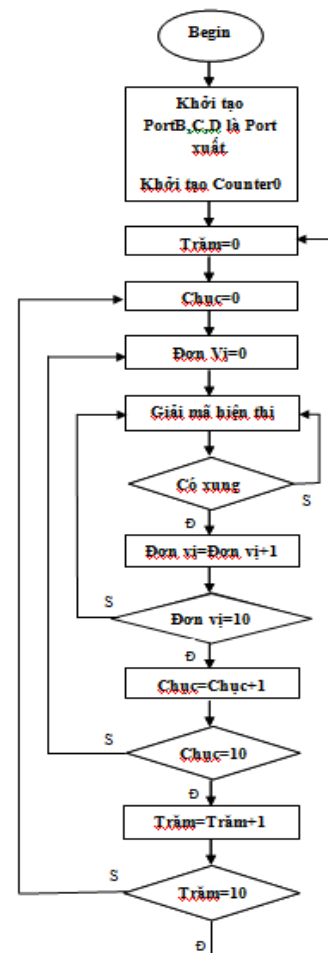


```

void main(void)
{
    trisb=1;
    trisd=0;
    trisc=0;
    intcon=0xb0;//ngat ngoai va ngat t0
    enable_interrupts(int_timer0);//chopheptmr0
    setup_timer_0(RTCC_INTERNAL|RTCC_DIV_2);
    enable_interrupts(global);
    giay =0;
    phuc=0;
    gio=0;
    while(true){
        if(giay==60)
            { giay=0;
              phuc=phuc+1; }
        if (phuc==60)
            { phuc=0;
              gio=gio+1;}
        if (gio==24)
            { gio=0;}
        hex_bcd();
        hienthi();}
    }
    
```



**LƯU ĐỒ**



**BÀI 3: SỬ DỤNG VI ĐIỀU KHIỂN PIC16F877A ĐỂ ĐẾM SẢN PHẨM SỬ DỤNG TIMER0.SỬ DỤNG NGÔN NGỮ ASSEMBLY**

**CHƯƠNG TRÌNH**

```

title "dem san pham"
processor p16f877a
include <P16f877a.inc>
__CONFIG _WDT_OFF

```

```

;=====
;Chuong trinh chinh
;=====

```

```

;-----khai bao bien-----

```

```

dvi    equ    0x20
chuc   equ    0x21
tram   equ    0x22
tam    equ    0x23
bien1  equ    0x24
bien2  equ    0x25
bien3  equ    0x26
dem    equ    0x27

```

```

;-----
org 0x000
goto start

```

```

;-----khoi tao Port va Timer0-----

```

```

start org 0x005
banksel TRISB
clrf    TRISB
clrf    TRISC
movlw   b'00101000'
movwf   OPTION_REG
banksel PORTB

```

```

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

```

```

clrf    TMR0
movlw   0x00
movwf   tam
lb4 movlw 0x00
movwf   tram
lb3 movlw 0x00
movwf   chuc
lb2 movlw 0x00
movwf   dvi
lb1 call  giimahienthi
movf    TMR0,0
xorwf   tam,0
btfsc   STATUS,Z
goto    lb1
movf    TMR0,0
movwf   tam

```

```

incf    dvi
movf    dvi,0
xorlw   d'10'
btfss   STATUS,Z
goto    lb1
incf    chuc
movf    chuc,0
xorlw   d'10'
btfss   STATUS,Z
goto    lb2
incf    tram
movf    tram,0
xorlw   d'10'
btfss   STATUS,Z
goto    lb3
goto    lb4

```

```

;-----chuong trinh con giai ma hien thi-----

```

```

;giimahienthi

```

```

movf    dvi,0
call    table
movwf   PORTB
movlw   b'00000100'
movwf   PORTC
call    delay
clrf    PORTC
call    delay
movf    chuc,0
call    table
movwf   PORTB
movlw   b'00000010'
movwf   PORTC
call    delay
clrf    PORTC
call    delay
movf    tram,0
call    table
movwf   PORTB
movlw   b'00000001'
movwf   PORTC
call    delay
clrf    PORTC
call    delay

```

```

return

```



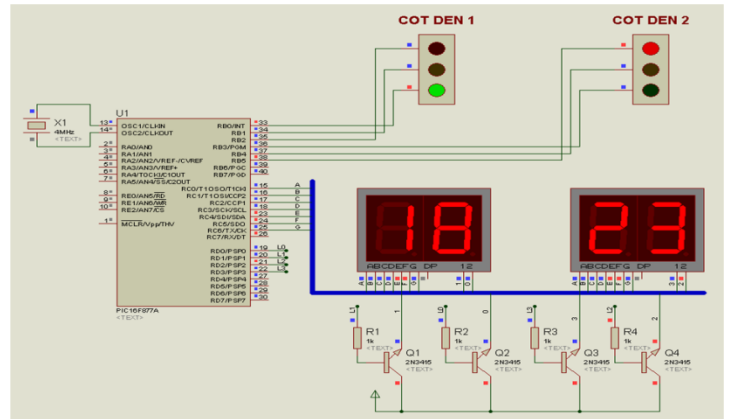
```

#include <16F877A.h>
#include <KhaiBaoTGhi_16F877A.h>
#fuses NOWDT,PUT,HS,NOPROTECT,NOLVP
#use delay(clock=2000000)
#use fast_io(b)
#use fast_io(d)
#byte dem=TMR1L
int8 tram,chuc=0,dv=0,ht=0;
const unsigned char
dig[]={0xc0,0xf9,0xa4,0xb0,0x99,0x92,0x82,0xf8,0x8
0,0x90};
//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
void khoitao()
{
trisb=0x0; //khai tao portb & portd la ngo ra
trisd=0x0; //
T1CON=0X06; //chon bo chia 1:1,bo dao dong bat dong bo
dem=0;tram=0;
}
//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
void hienthi()
{
switc(ht)
{
case 0: portb=dig[dv];
portd=0x01;
delay_us(20);
portb=0xff;
break;
case 1: portb=dig[chuc];
portd=0x02;
delay_us(20);
portb=0xff;
break;
case 2: portb=dig[tram];
portd=0x04;
delay_us(20);
portb=0xff;
}
ht++;
if (ht==3) ht=0;
}

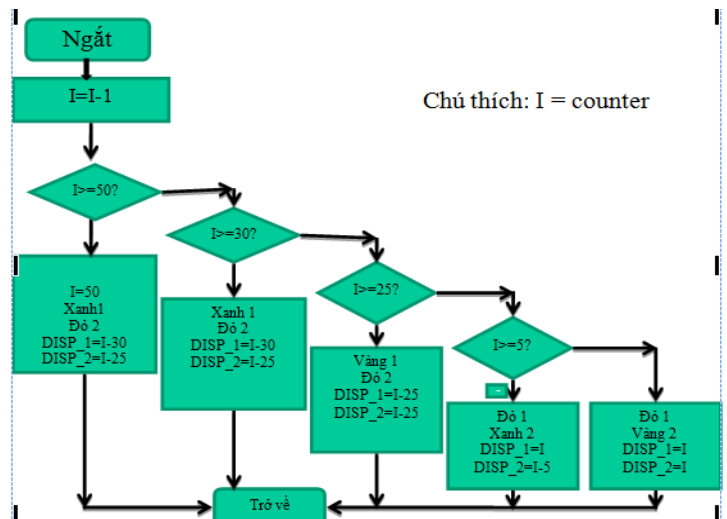
//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
void main()
{
khoitao();
bit_set(T1CON,0);
while(1)
{
if (dem==100)
{
bit_clear(T1CON,0); //xoa bit TMR1ON de thay doi gia tri TMR1L
dem=0;
tram=tram+1;
if (tram==10)
tram=0;
bit_set(T1CON,0);
}
chuc=dem/10;
dv=dem%10;
hienthi();
}
}

```

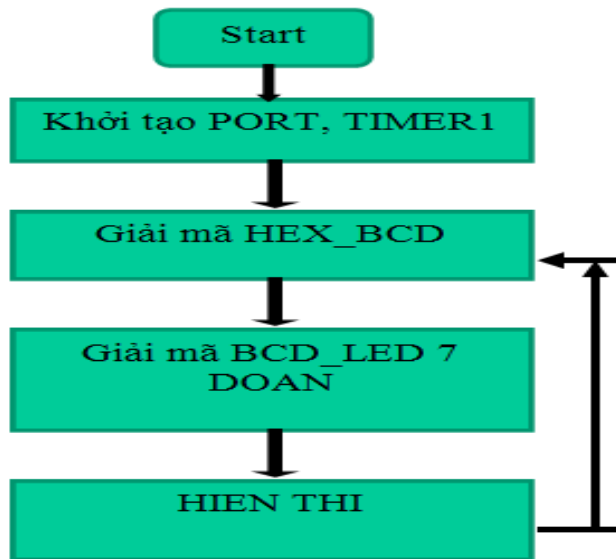
**BÀI 5:** Dùng PIC16F877A điều khiển đèn giao thông, thời gian đèn xanh là 20 giây, đỏ là 25 giây, vàng 5 giây, dùng ngôn ngữ assembly. Dùng timer 1 làm bộ định thời.



**I. Lưu đồ giải thuật**  
**a. Chương trình ngắt**



**b. Chương trình chính**



**CHƯƠNG TRÌNH**

```

processor P16f877a
include <P16f877a.inc>
_CONFIG _CP_OFF & _WDT_OFF & _BODEN_OFF
& _PWRTE_ON & _RC_OSC & _WRT_OFF &
_LVP_ON & _CPD_OFF
;=====
; KHAI BAO HANG VA BIEN
;=====
;Dinh nghĩa các giá trị sử dụng hiển thị trạng thái
;đèn giao thông trên hai cột
DENGT EQU PORTB
XANH_1 EQU 0
VANG_1 EQU 1
DO_1 EQU 2
XANH_2 EQU 3
VANG_2 EQU 4
DO_2 EQU 5
;Khai báo các hàng sử dụng điều khiển thời gian hiển thị
DATA_LED EQU PORTC
CONTROL_LED EQU PORTD
LED_DV_1 EQU 0x01
LED_CHUC_1 EQU 0x02
LED_DV_2 EQU 0x04
LED_CHUC_2 EQU 0x08
;Hàng số kiểm tra du 1 giây
DIV_1S EQU 0
  
```

```

;----KHAI BAO BIEN-----
cblock 0x20
STATUS_TEMP
W_TEMP

TGCOT_1 ;Gia tri thoi gian dua ra 2 cot den
TGCOT_2

DV_COT1 ;Gia tri BCD cua so giay
CHUC_COT1
DV_COT2
CHUC_COT2

temp_1 ;Bien tam su dung trong chuong
temp_2 ;trinh chuyen doi HEX sang BCD

MA_CHUC_1 ;Bien luu tru ma 7 doan cua cac led
MA_DV_1
MA_CHUC_2
MA_DV_2

btam1 ;Bien tam su dung trong
btam2 ;chuong trinh phuc vu ngat
counter

THANHGHI_TAM ;Thanh ghi dekiem tra ngat
lan 2

dem ;Bien dung cho
chuong trinh delay
endc

;-----
;Tao MACRO luu va phuc hoi cac
;thanh ghi quan trọng
PUSH MACRO
MOVWF W_TEMP
SWAPF STATUS,W
MOVWF STATUS_TEMP
ENDM

POP MACRO
SWAPF STATUS_TEMP,W
MOVWF STATUS
SWAPF W_TEMP,F
SWAPF W_TEMP,W
  
```

```

        ENDM
;Ket thuc MACRO
;=====
;      CHUONG TRINH NGAT
;=====
NGAT org    0x04
        PUSH
        BANKSEL    PIR1
        BTFSS PIR1, TMR1IF    ;Kiem tra co ngat
        GOTO exit_int        ;Neu khong phai
ngat do timer1 thi thoat
        BCF    PIR1, TMR1IF    ;Xoa co ngat
        BANKSEL    TMR1H    ;Khoi tao lai gia tri timer
        MOVLW    high d'3036'
        MOVWF    TMR1H
        MOVLW    low d'3036'
        MOVWF    TMR1L

        BTFSS THANGHI_TAM, DIV_1S
        GOTO notfull_1s
;Chuong trinh phuc vu ngat thuc
;hien cac trang thai cua den giao thong
;va gia tri thoi gian de dua ra hien thi
        BCF    THANGHI_TAM, DIV_1S
        BANKSEL    DENGTT
        CLRF    DENGTT

        DECF    counter, 1
        MOVLW    0x00
        XORWF    counter, W
        BTFSS STATUS, Z
        GOTO X1_D2
;-----
        MOVLW    d'50'
        MOVWF    counter
        BSF    DENGTT, XANH_1
        BSF    DENGTT, DO_2
        MOVLW    d'30'
        MOVWF    btam1
        MOVLW    d'25'
        MOVWF    btam2
        CALL    laythoigian
        GOTO exit_int
;-----

```

```

X1_D2
        MOVLW    d'30'
        SUBWF    counter, 0
        BTFSS STATUS, C
        GOTO V1_D2
        BANKSEL    DENGTT
        BSF    DENGTT, XANH_1
        BSF    DENGTT, DO_2
        MOVLW    d'30'
        MOVWF    btam1
        MOVLW    d'25'
        MOVWF    btam2
        CALL    laythoigian
        GOTO exit_int
;-----
V1_D2
        MOVLW    d'25'
        SUBWF    counter, W
        BTFSS STATUS, C
        GOTO D1_X2
        BANKSEL    DENGTT
        BSF    DENGTT, VANG_1
        BSF    DENGTT, DO_2
        MOVLW    d'25'
        MOVWF    btam1
        MOVLW    d'25'
        MOVWF    btam2
        CALL    laythoigian
        GOTO exit_int
;-----
D1_X2
        MOVLW    d'5'
        SUBWF    counter, W
        BTFSS STATUS, C
        GOTO D1_V2
        BANKSEL    DENGTT
        BSF    DENGTT, DO_1
        BSF    DENGTT, XANH_2
        MOVLW    d'0'
        MOVWF    btam1
        MOVLW    d'5'
        MOVWF    btam2
        CALL    laythoigian
        GOTO exit_int

```

```

;-----
D1_V2
    BANKSEL    DENG1
    BSF        DENG1, DO_1
    BSF        DENG1, VANG_2
    MOVLW     d'0'
    MOVWF     btam1
    MOVLW     d'0'
    MOVWF     btam2
    CALL      laythoigian

notfull_1s
    BSF      THANHGI_TAM, DIV_1S
exit_int
    POP
    RETFIE
;=====KET THUC CHUONG TRINH NGAT=====

;-----
;    CHUONG TRINH LAY THOI GIAN
;-----
laythoigian
    MOVF      btam1, W
    SUBWF     counter, W
    MOVWF     TGCOT_1

    MOVF      btam2, W
    SUBWF     counter, W
    MOVWF     TGCOT_2
    RETURN

;=====
;    CHUONG TRINH CHINH
;=====
org          0x000
            goto    main

;CHUONG TRINH BAT DAU O DAY
Chuongtrinhchinh
org          0x090
main
    BANKSEL   TRISC
    CLRF     TRISB
    CLRF     TRISC
    CLRF     TRISD

;-----
;    BCF      STATUS, RP0 ;chon bank 0
;    BCF      STATUS, RP1
;    MOVLW   d'50'
;    MOVWF   counter
;    CALL    khoitaotimer1
loop
;    CALL    hex_bcd_1 ;Giai ma TGCOT_1 sang BCD
;    CALL    hex_bcd_2 ;Giai ma TGCOT_2 sang BCD
;    CALL    bcd_7doan
;    CALL    hienthi
;    GOTO    loop

;=====
;    KHOI TAO TIMER 1
;=====
khoitaotimer1
    CLRF     T1CON
    CLRF     INTCON
    CLRF     TMR1H
    CLRF     TMR1L
    BSF      STATUS, RP0 ;chon bank 1
    CLRF     PIE1
    BSF      PIE1,TMR1IE ;cho phep ngat timer 1
    BCF      STATUS, RP0 ;chon bank 0
    CLRF     PIR1 ;xoa cac co ngat

    MOVLW   0xC0 ;cho phep ngat toan cuc va
    MOVWF   INTCON ;ngat ngoai vi
    MOVLW   0x30
    MOVWF   T1CON ;0011 0000: Timer1 su
dung Fosc/4,;PSA 1:8
    BANKSEL TMR1H
    MOVLW   high d'3036'
    MOVWF   TMR1H
    MOVLW   low d'3036'
    MOVWF   TMR1L
    BSF     T1CON, TMR1ON
    RETURN

;=====KET THUC KHOI TAO TIMER 1=====
;CHUONG TRINH CHUYEN DOI HEX SANG BCD==
;=====
;CHUYEN DOI O COT 1
hex_bcd_1
    BCF      STATUS, RP0

```



```

    CLRF DV_COT1
    CLRF CHUC_COT1
    MOVF TGCOT_1, W
    MOVWF temp_1
BCD1
    MOVLW .10
    SUBWF temp_1, W
    BTFSS STATUS, C
    GOTO BCD2
    INCF CHUC_COT1
    MOVLW .10
    SUBWF temp_1, F
    ;temp_1 = temp_1 - 10
    GOTO BCD1
BCD2
    MOVF temp_1, W
    MOVWF DV_COT1
    RETURN
;CHUYEN DOI O COT 2
hex_bcd_2
    BCF STATUS, RP0
    CLRF DV_COT2
    CLRF CHUC_COT2
    MOVF TGCOT_2, W
    MOVWF temp_2
BCD3
    MOVLW .10
    SUBWF temp_2, W
    BTFSS STATUS, C
    GOTO BCD4
    INCF CHUC_COT2
    MOVLW .10
    SUBWF temp_2, F
    ;temp_2 = temp_2 - 10
    GOTO BCD3
BCD4
    MOVF temp_2, W
    MOVWF DV_COT2
    RETURN
;=====KET THUC HEX SANG BCD=====
;=====
;=CHUONG TRINH CHUYEN DOI BCD SANG LED 7
DOAN=
;=====

```

```

bcd_7doan
;Lay ma 7 doan cho led hien thi hang chuc cot 1
    MOVF CHUC_COT1, 0
    CALL table
    MOVWF MA_CHUC_1
;Lay ma 7 doan cho led hien thi hang don vi cot 1
    MOVF DV_COT1, 0
    CALL table
    MOVWF MA_DV_1
;Lay ma 7 doan cho led hien thi hang chuc cot 2
    MOVF CHUC_COT2, 0
    CALL table
    MOVWF MA_CHUC_2
;Lay ma 7 doan cho led hien thi hang don vi cot 2
    MOVF DV_COT2, 0
    CALL table
    MOVWF MA_DV_2
    RETURN

```

```

;-----
;BANG LAY MA LED 7 DOAN
table ADDWF PCL, F
    RETLW 0XC0 ;0
    RETLW 0XF9 ;1
    RETLW 0XA4 ;2
    RETLW 0XB0 ;3
    RETLW 0X99 ;4
    RETLW 0X92 ;5
    RETLW 0X82 ;6
    RETLW 0XF8 ;7
    RETLW 0X80 ;8
    RETLW 0X90 ;9

```

```

;-----
;==KET THUC BCD SANG 7 DOAN==
;=====
;CHUONG TRINH QUET LED 7 DOAN HIEN THI==
;=====
hienthi
    MOVF MA_DV_1, 0
    MOVWF DATA_LED
    MOVLW LED_DV_1
    MOVWF CONTROL_LED
    CALL delay
    CLRF CONTROL_LED

```

```
CALL delay

MOVF MA_CHUC_1, 0
MOVWF DATA_LED
MOVLW LED_CHUC_1
MOVWF CONTROL_LED
CALL delay
CLRF CONTROL_LED
CALL delay
```

```
MOVF MA_DV_2, 0
MOVWF DATA_LED
MOVLW LED_DV_2
MOVWF CONTROL_LED
CALL delay
CLRF CONTROL_LED
CALL delay
```

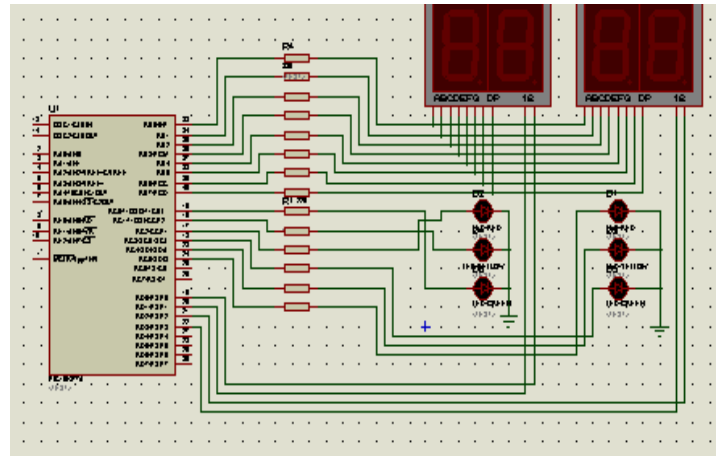
```
MOVF MA_CHUC_2, 0
MOVWF DATA_LED
MOVLW LED_CHUC_2
MOVWF CONTROL_LED
CALL delay
CLRF CONTROL_LED
CALL delay
RETURN
```

```
;;;KET THUC HIEN THI=====
;-----
; CHUONG TRINH DELAY
;-----
delay
    MOVLW    0xFF
    MOVWF   dem
del    DECFSZ  dem
      GOTO  del
      RETURN

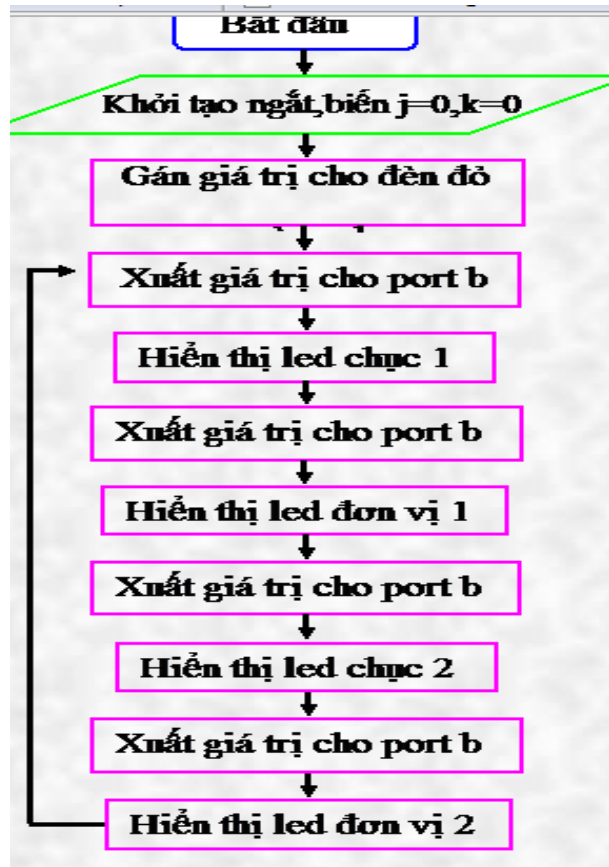
    END
;=====KET THUC CHUONG TRINH=====
```

**BÀI 6: Thiết kế đèn giao thông dùng PIC16F877A điều khiển 4 Led 7 đoạn, 6 Led đơn. Thời gian đèn đỏ 25 giây, đèn xanh 20 giây, đèn vàng 5 giây, Timer 1 và dùng ngôn ngữ C**

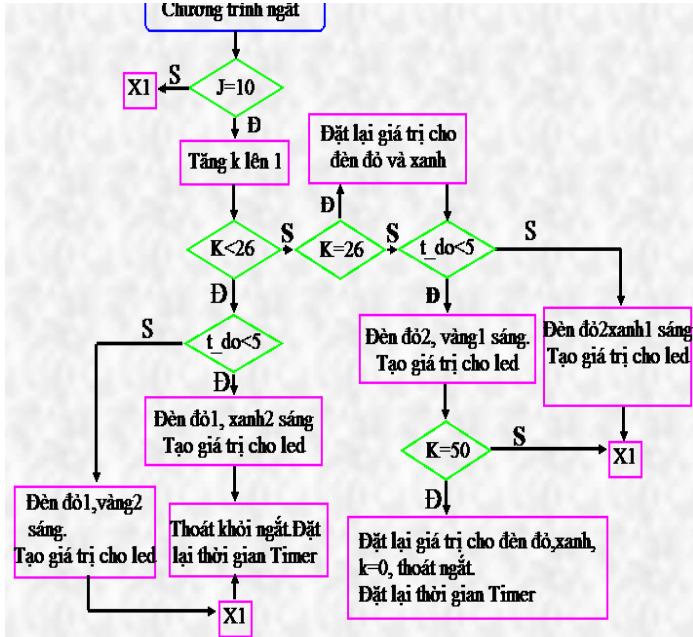
**THEO PHƯƠNG PHÁP QUÉT LED**



**CHƯƠNG TRÌNH CHÍNH**



**CHƯƠNG TRÌNH NGẮT:**



**CHƯƠNG TRÌNH:**

```
#include <16f877a.h>
#include <KhaiBaoTGhi_16F877A.h>
#fuses nowdt, put, hs, noprotect, nolvp
#use delay (clock=20000000)
#use fast_io(b)
#use fast_io(d)
int8 j,k,chuc1,chuc2,dvi1,dvi2;
int16 t_do,a,t_xanh,b;
const unsigned char
dig[]={0xc0,0xf9,0xa4,0xb0,0x99,0x92,0x82,0xf8,0x80,0x9
0};
#INT_TIMER1
VOID NGAT() // bat dau chuong trinh ngat
{ J++;
  IF(J==10) // khi j=10 thi thoi gian dung 1s
  { k=k+1; // bien k dung de xac dinh thoi gian cho cot 1
    if((k<26)&&(k>0))
    { a=t_do;
      t_do=t_do-1;
      b=t_xanh;
      t_xanh=t_xanh-1;
      if(a<5) // thoi gian hien thi cho led vang
      { portc=0x22; // Den v2 va d1 sang
```

```
      b=a;
    }
  }
  else
  portc=0x21; // den x2 va den d1 sang
  }
  if((k<26)&&(k>24)) // khi du 25s thi chuyen sang
cot 2
  { t_do=24;
    t_xanh=19;
  }
  if(k>25) // bat dau hien thi cho cot 2
  { b=t_do;
    t_do=t_do-1;
    a=t_xanh;
    t_xanh=t_xanh-1;
    if (b<5) // khi den xanh du 20s thi den vang
    bat dau sang
    { portc=0x14; // den do 2 va den vang 1 sang
      a=b;
    }
  }
  else
  portc=0x0c; // den do 2 va den xanh 1 sang
  }
  chuc1=a/10;
  dvi1=a%10;
  chuc2=b/10;
  dvi2=b%10;

  if(k>49) // khi cot 2 xong 25s thi chuyen ve cot 1
  { k=0; // khoi tao lai gia tri dem ban dau
    t_do=24;
    t_xanh=19;
  }
  SET_TIMER1(3035); // cai lai thoi gian cho timer1
  j=0;
  }
  SET_TIMER1(3035); // cai lai thoi gian cho timer1
  }

void main() // bat dau chuong trinh chinh
{ set_tris_b(0x00); // khoi tao cho port b,c,d la ngo ra
  set_tris_d(0x00);
  set_tris_c(0x00);
  j=0; // khoi tao cho bien dem timer1
```

```

k=0;           //khởi tạo cho biến đếm của tung cot
t_do=24;      //gán giá trị ban đầu cho đèn đỏ và xanh
t_xanh=19;
SET_TIMER1(3035); //đặt số đếm cho timer1
T1CON=0x35;     //khởi tạo giá trị cho timer
enable_interrupts(INT_TIMER1); //trở thi ngắt
enable_interrupts(global); //cho phép ngắt timer1
WHILE(TRUE)
{ portb=dig[chuc1]; //đưa giá trị chuc1 ra portb
  portd=0xf8;      //chỉ led ở vị trí chuc1 là sáng
  delay_ms(8);    //dùng để nhìn thấy được led sáng
  portd=0xf0;     //chờ lem

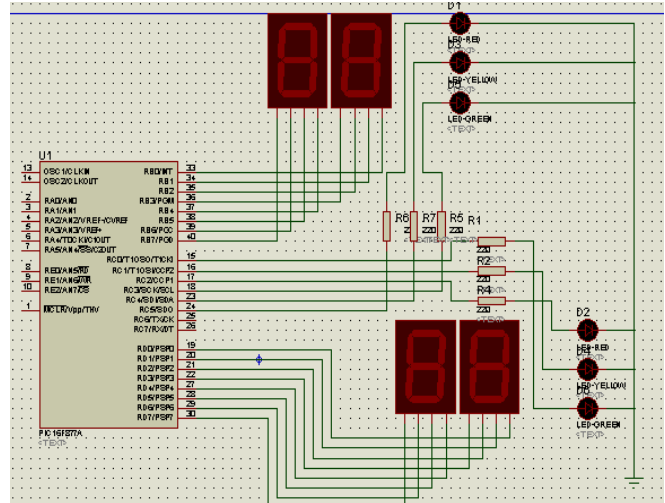
  portb=dig[dvi1]; //đưa giá trị dvi1 ra portb
  portd=0xf4;      //chỉ led ở vị trí dvi1 là sáng
  delay_ms(8);
  portd=0xf0;

  portb=dig[chuc2]; //đưa giá trị chuc2 ra portb
  portd=0xf2;      //chỉ led ở vị trí chuc2 là sáng
  delay_ms(8);
  portd=0xf0;

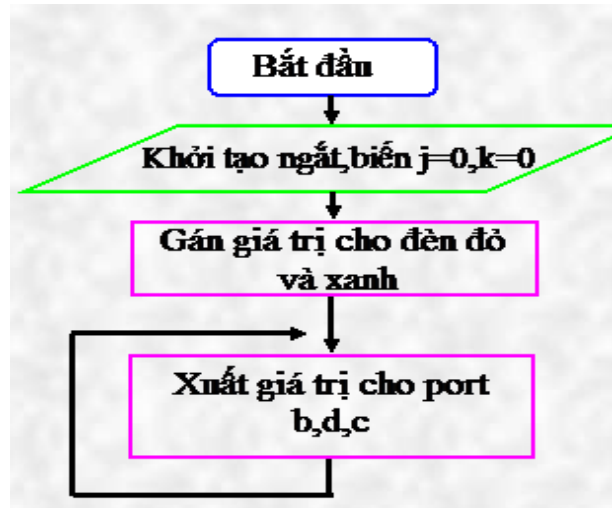
  portb=dig[dvi2]; //đưa giá trị dvi2 ra portb
  portd=0xf1;      //chỉ led ở vị trí dvi2 là sáng
  delay_ms(8);
  portd=0xf0;
}
}

```

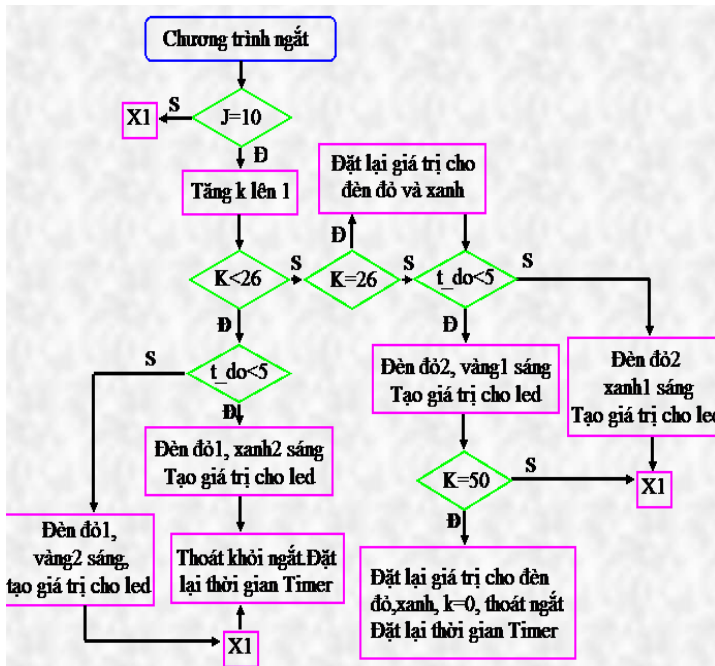
## BÀI 6: THEO PHƯƠNG PHÁP GIẢI MÃ



### LƯU ĐỒ: CHƯƠNG TRÌNH CHÍNH



## CHƯƠNG TRÌNH NGẮT



### CHƯƠNG TRÌNH:

```
#include <16f877a.h>
#include <KhaiBaoTGhi_16F877A.h>
#fuses nowdt, put, hs, noprotect, nolvp
#use delay (clock=20000000)
#use fast_io(b)
#use fast_io(d)
int8 j,k,chuc1,xuat1,chuc2,dvi1,dvi2,xuat2;
int16 t_do,a,t_xanh,b;
#INT_TIMER1
VOID NGAT() // bat dau chương trình ngắt
{ J++;
  IF(J==10) // khi j=10 thì thời gian dùng 1s
  { k=k+1; // biến k dùng để xác định thời gian cho cột 1
    if((k<26)&&(k>0))
    { a=t_do;
      t_do=t_do-1;
      b=t_xanh;
      t_xanh=t_xanh-1;
      if(a<5) // thời gian hiển thị cho led vàng
      { portc=0x22; // đèn vàng 2 và đèn 1 sáng
        b=a;
      }
      else
      portc=0x21; // đèn xanh 2 và đèn đỏ 1 sáng
    }
  }
}
```

```
if((k<26)&&(k>24)) // khi đủ 25s thì chuyển sang cột 2
{ t_do=24;
  t_xanh=19;
}
if(k>25) // bắt đầu hiển thị cho cột 2
{ b=t_do;
  t_do=t_do-1;
  a=t_xanh;
  t_xanh=t_xanh-1;
  if (b<5) // khi đèn đếm 20s thì đèn v bắt đầu sáng
  { portc=0x14; // đèn đỏ 2 và đèn vàng 1 sáng
    a=b;
  }
  else
  portc=0x0c; // đèn đỏ 2 và đèn xanh 1 sáng
}
chuc1=a/10;
dvi1=a%10;
chuc2=b/10;
dvi2=b%10;
chuc1=chuc1<<4;
xuat1=chuc1|dvi1;
chuc2=chuc2<<4;
xuat2=chuc2|dvi2;

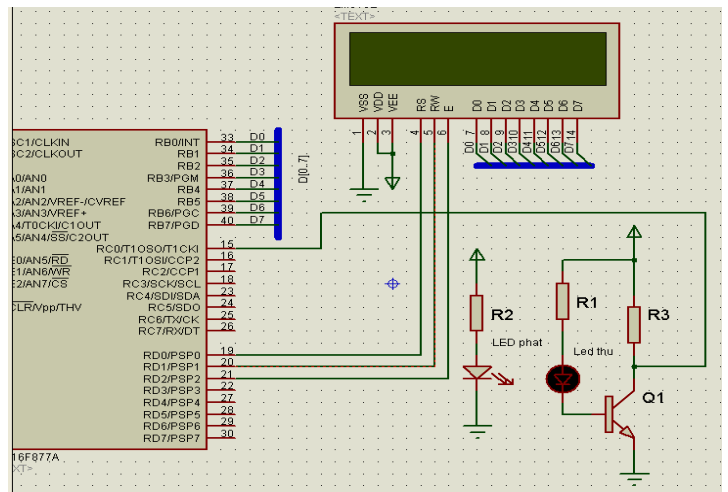
if(k>49) // khi cột 2 xong 25s thì chuyển về cột 1
{ k=0; // khởi tạo lại giá trị đếm ban đầu
  t_do=24;
  t_xanh=19;
}
SET_TIMER1(3035); // cài lại thời gian cho timer1
j=0;
}
SET_TIMER1(3035); // cài lại thời gian cho timer1
}

void main() // bắt đầu chương trình chính
{ set_tris_b(0x00); // khởi tạo cho port b,c,d là ngõ ra
  set_tris_d(0x00);
  set_tris_c(0x00);
  j=0; // khởi tạo cho biến đếm timer1
  k=0; // khởi tạo cho biến đếm của từng cột
  t_do=24; // gán giá trị ban đầu cho đèn d và x
```

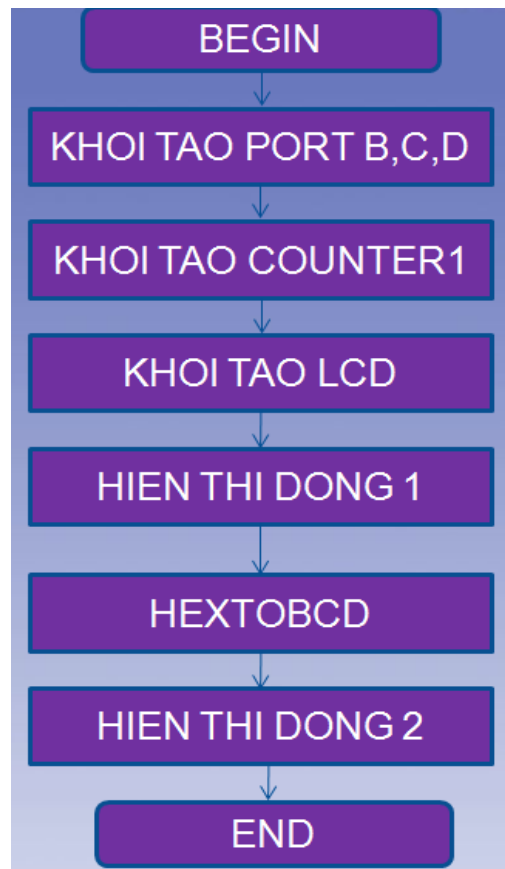
```

t_xanh=19;
SET_TIMER1(3035); //dat so dem cho timer1
TICON=0x35; //khai tao gia tri cho timer
enable_interrupts(INT_TIMER1); //tran thi ngat
enable_interrupts(global); //cho phep ngat timer1
WHILE(TRUE)
{ portb=xuat1; //dua gia tri ra port b,d
  portd=xuat2; //de hien thi
}
}
    
```

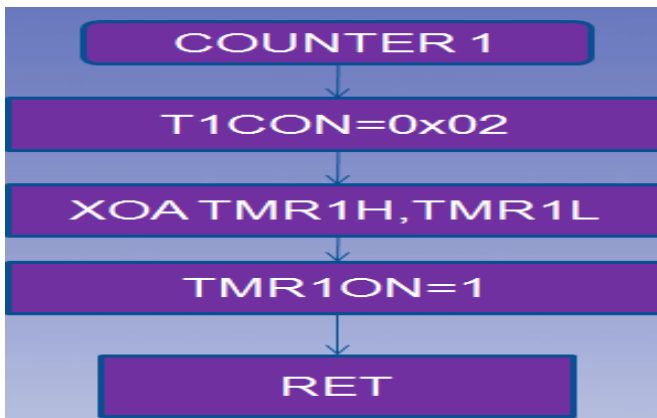
### BÀI 7: MẠCH ĐẾM SẢN PHẨM HIỂN THỊ TRÊN LCD.DÙNG NGÔN NGỮ ASSEMBLY



### LƯU ĐỒ CHÍNH



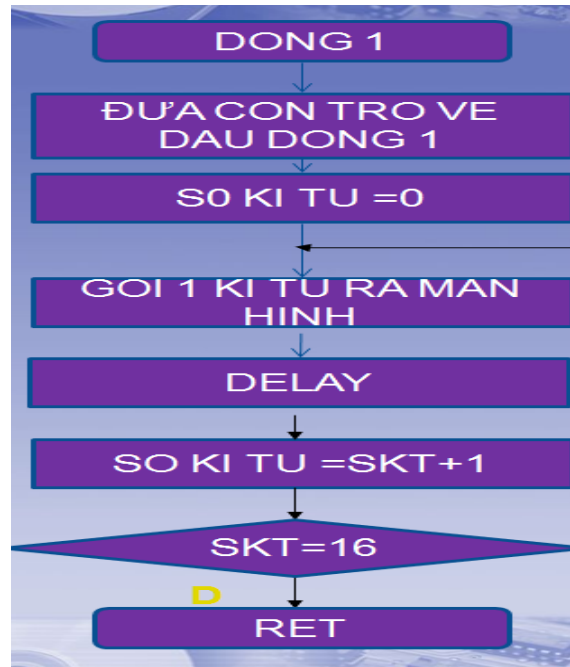
KHỞI TẠO COUNTER



KHỞI TẠO LCD



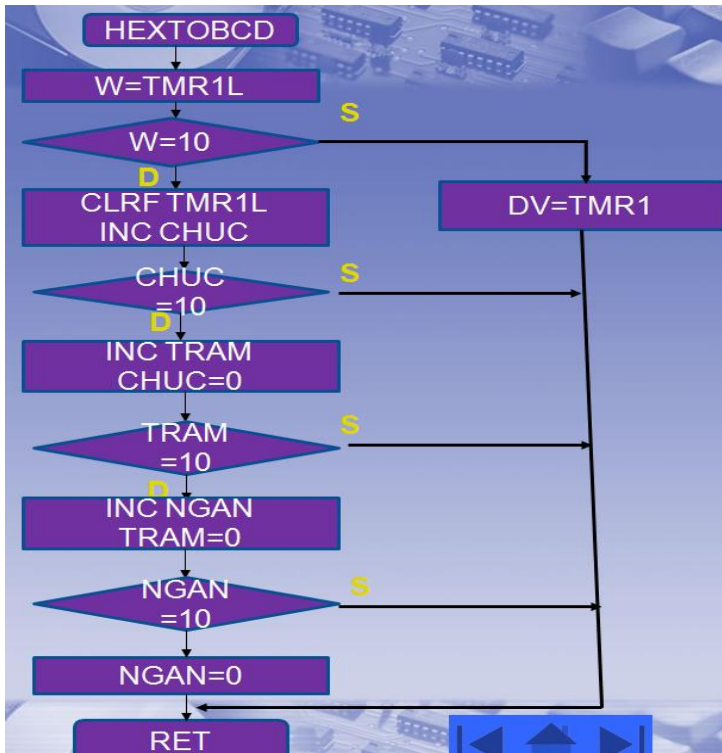
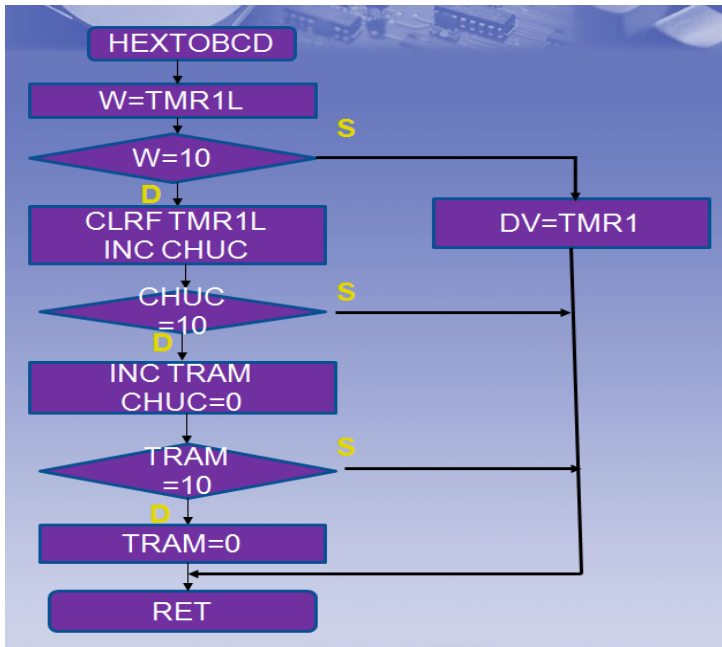
HIỂN THỊ DÒNG 1:



HIỂN THỊ DÒNG 2:



GIẢI MÃ HEX => BCD:



**CHƯƠNG TRÌNH:**

```

title "DIEM SAN PHAM HIEN THI LCD"
processor p16f877a
include <p16f877a.inc>
_CONFIG
    _CP_OFF&_WDT_OFF&_LVP_OFF&_PWRTE_
ON&_HS_OSC&_BODEN_OFF&_CPD_OFF
;*****

```

**;KHOI TAO CAC BIEN**

```

;*****
COUNT1 EQU 0x20
COUNT2 EQU 0x21
COUNT3 EQU 0x22
COUNT EQU 0x23
A EQU 0x24
TAM EQU 0x25
TR EQU 0x26
CH EQU 0x27
DV EQU 0x28
NG EQU 0x29
;*****

```

```

ORG 0x000
CLRf STATUS
MOVLW 0x00
MOVWF PCLATH
GOTO START
;*****

```

**;KHOI TAO PORTD,PORTB**

```

;*****
ORG 0x005
START BCF STATUS,RP1
BSF STATUS,RP0
CLRf TRISB
CLRf TRISD
;*****

```

**;VONG LAP CHUONG TRINH CHINH**

```

;*****
MAIN
CALL KTCOUNTER1
CALL KHOITAOLCD
MOVLW D'0'
MOVWF NG

```



```

MOV LW      D'0'          CALL      DELAY40mS
MOV WF      TR          RETURN
MOV LW      D'0'          ;*****
MOV WF      CH          HEXTOBCD
MOV LW      D'0'
MOV WF      DV          MOVF      TMR1L,0
CALL        DONG1       ; copy noi dung TMR1L vao w
                                MOVWF     TAM
LOOP        CALL        HEXTOBCD ; copy noi dung w vao TAM
                                CALL        DONG2       MOV LW      D'10'
                                GOTO        LOOP        ;w=10
;*****
KTCOUNTER1
                                XORWF     TAM,0
                                BTFSS     STATUS,Z
                                BCF        STATUS,RP1 ;nhay neu z=1<=> kq=0
                                BCF        STATUS,RP0
                                GOTO        X1
;CHON BANK 0
                                MOV LW     B'00000010'
                                CLRF      TMR1L
;KHOI TAO COUNTER
                                INCF     CH
                                MOVWF     T1CON      MOV LW     D'10'
                                CLRF      TMR1H      XORWF     CH,0
;XOA 8 BIT CAO
                                BTFSS     STATUS,Z
                                CLRF      TMR1L      ;nhay neu z=1<=> kp=0 (CH=10)
;XOA 8 BIT THAP
                                GOTO      X2
                                BSF       T1CON,TMR1ON
;cho couter bt dau dem khi co xung
                                INCF     TR
RETURN      CLRF     CH
;*****
KHOITAOLCD
                                MOV LW     0X38
                                BTFSS     STATUS,Z
;Khoi tao hang 2 matrix 5x8.
                                GOTO      X1
                                MOVWF     A
                                CALL      GHIMADK
                                CALL      DELAY40mS
                                INCF     NG
                                CLRF     TR
                                MOV LW     D'10'
;Bat man hinh LCD.
                                XORWF     NG,0
                                BTFSS     STATUS,Z
                                GOTO      X2
                                MOVWF     A
                                CALL      GHIMADK
                                CALL      DELAY40mS
                                CLRF     NG
                                GOTO      X2
                                MOV LW     0X01
                                MOVF     TMR1L,0
;Xoa man hinh va dua con tro ve dau dong thu 1.
                                MOVWF     DV
                                MOVWF     A
                                MOVWF     A
                                CALL      GHIMADK
                                RETURN
                                X1
                                X2

```

```

;*****
GHIMADK      MOVF      A,0          MOVF      NG,0
;dk LCD hoạt động      MOVWF     A
                        MOVWF     PORTB      MOVWF     B'00110000' ;giai ma ra
                        BCF        PORTD,0    LCD
                        BCF        PORTD,1
                        BSF        PORTD,2
                        BCF        PORTD,2      ADDWF     A,1
                        CALL       GHIDATA
                        CALL       DELAY

RETURN
;*****
DONG1
                        MOVLF     0X01      LCD
;Xoa man hinh va dua con tro ve dau dong thu 1.
                        MOVWF     A
                        CALL      GHIMADK
                        CALL      DELAY
                        MOVLF     0X80
;hien thi dong 1" SO san pham la"
                        MOVWF     A
                        CALL      GHIMADK      LCD
                        CALL      DELAY
                        MOVF      CH,0
                        MOVWF     A
                        MOVLF     B'00110000' ;giai ma ra
                        ADDWF     A,1
                        CALL      GHIDATA
                        CALL      DELAY
DONG11
                        CLRf      COUNT
                        MOVF      COUNT,0
                        CALL      TABLE
                        MOVWF     A
                        CALL      GHIDATA
                        CALL      DELAY
                        INCf      COUNT,0
                        XORLW     D'16'
                        BTFSS     STATUS,Z
                        GOTO      LB1          RETURN
                        RETURN
;*****
LB1      INCf      COUNT,1      GHIDATA
                        GOTO      DONG11     MOVF      A,0
;*****
DONG2
                        MOVLF     0XC5
;DUA CON TRO HANG 5 CUA DONG 2
                        MOVWF     A
                        CALL      GHIMADK     ;RS
                        CALL      DELAY       ;RW
;*****
                        MOVWF     PORTB
                        BSF        PORTD,0
                        BCF        PORTD,1
                        BSF        PORTD,2
                        ;E

```

```
BCF PORTD,2
RETURN
```

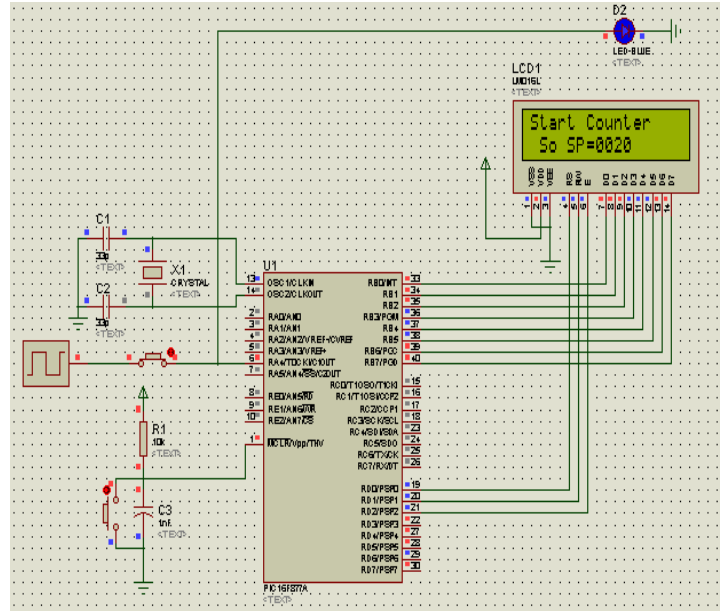
```
*****
;
DELAY40mS    MOVLW    D'255'
                ;delay 40ms(tan so 20MHz)
                MOVWF    COUNT1
DEL1         MOVLW    0xFF
                MOVWF    COUNT2
DEL2         DECFSZ   COUNT2
                GOTO     DEL2
                DECFSZ   COUNT1
                GOTO     DEL1
                RETURN
*****
```

```
DELAY        MOVLW    D'255'
                MOVWF    COUNT3
LB           DECFSZ   COUNT3
                GOTO     LB
                RETURN
*****
```

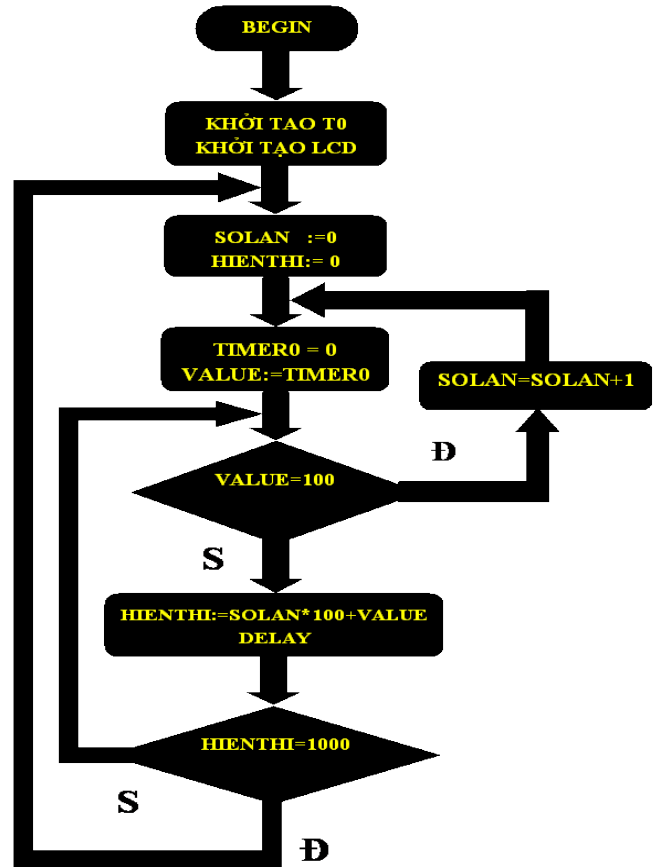
```
TABLE        ADDWF    PCL,1
                DT      " SO SAN PHAM LA:"
                END
*****
```

\*\*\*\*\*  
;KET THUC CHUONG TRINH  
\*\*\*\*\*

### BÀI 8: MẠCH ĐẾM SẢN PHẨM HIỂN THỊ TRÊN LCD.DÙNG NGÔN NGỮ C



#### LƯU ĐỒ



**LƯU ĐỒ XUẤT LCD:**

ghi du lieu



**Chương trình đếm sản phẩm dùng PIC 16F877A**

```

//=====
// Title : Dem san pham dung Timer 0 hien thi LCD 16x2
// Writer : Nhom 8 _ 061170
// Hardware : PIC 16F877A
// Compiler : CCS C
//=====

#include <16F877A.h>
#include <def_16f877a.h>
#include delay( clock=20000000 )

//-----Define signals-----

#define RS RD0 //Ket noi chan RS của LCD voi chan RD0 của PIC
#define RW RD1 //Ket noi chan RW của LCD voi chan RD1 của PIC
#define E RD2 //Ket noi chan E của LCD voi chan RD2 của PIC
#define LCD PORTB //Ket noi LCD voi chan RB0-RB7 của PIC

void cmd_lcd( int8 command ) ;
void data_lcd( int8 data ) ;
Void convert(int16 value) ;

int8 value ;
int8 donvi,chuc,tram,ngan ; int 8, int 16

int16 solan,hienthi ;

//=====
//----- Sub-Program -----
//=====

//Chương trình con gui command toi LCD
void cmd_lcd( int8 command )
{
RS = 0 ; //Bus se ket noi voi thanh ghi lenh IR de nhan lenh
RW = 0 ; //LCD o che do ghi ghi du lieu len lcd
LCD = command ;

E = 1 ; //Tao ra xung high-to-low o che do ghi
E = 0 ;

delay_ms( 10 ) ;
}

//Chương trình con gui du lieu hien thi len LCD
void data_lcd( int8 data ) ghi dl vào thanh ghi DR để hiển thị
lên LCD
{
RS = 1 ; //Bus se ket noi voi thanh ghi du lieu DR
RW = 0 ; //LCD o che do ghi
  
```

```
LCD = data ;
```

```
E = 1 ; //Tao ra xung high-to-low o che do ghi
E = 0 ;
```

```
delay_ms( 10 ) ;
}
```

### //Chương trình con chuyển đổi giá trị thành ký tự hiển thị LCD

```
Void convert(int16 hienthi)
```

```
{
Int16 temp ;
temp = hienthi ; // Gan bien temp cho gia tri trong thanh ghi TMR0
ngan = temp / 1000 + 0x30 ;
```

```
temp = temp % 1000 ;
```

```
tram = temp / 100 + 0x30 ;
temp = temp % 100 ;
```

```
chuc = temp / 10 + 0x30 ;
donvi = temp % 10 + 0x30 ;
}
```

```
//=====
//-----Main program-----
//=====
```

```
Void main()
```

```
{
//=====
// Khoi tao Timer0
//=====
```

```
Set_timer0(0) ;
//setup_timer_0(RTCC_EXT_L_TO_H) ;
```

### //Chon bit canh len trên chân RA4

```
T0CS = 1 ; //Cho phép nhận xung ở chân T0CKI
T0SE = 0 ; //Cho phép xung vào chân T0CKI tích cực canh len
```

```
TMR0IE = 0 ; //Không cho phép ngắt T0
delay_ms(10) ;
```

```
//=====
// Khoi tao LCD
//=====
```

```
TRISB = 0 ; PORT B, D LA XUAT
TRISD = 0 ;
```

```
delay_ms( 15 ) ; //Cho cho den khi nguon cua LCD dat 4.5v
cmd_lcd( 0x0C ) ;
```

### //LCD hiển thị, không hiển thị con trỏ, con trỏ không nhấp nháy.

```
cmd_lcd( 0x38 ) ; //LCD su dung Bus 8bit, hien thi 2 hang function
cmd_lcd( 0x01 ) ; //Xoa man hinh LCD clear display
cmd_lcd( 0x06 ) ; //Noi dung khong dich chuyen entry mode set
```

```
//#####
cmd_lcd( 0x01 ) ; clear display: dua con tro ve goc trai
cmd_lcd( 0x80 ) ; dau hang 1 //Con tro o dau dong 1
printf(data_lcd, "Group 8 - Hello!");
```

```
delay_ms( 1000 ) ;
```

```
cmd_lcd( 0x01 ) ; con tro ve dau dong
cmd_lcd( 0x80 ) ;
printf(data_lcd, "Member:");
```

```
delay_ms( 1000 ) ;
```

```
cmd_lcd( 0x01 ) ;
cmd_lcd( 0x80 ) ;
printf(data_lcd, "Xuan Len");
```

```
delay_ms( 1000 ) ;
```

```
cmd_lcd( 0x01 ) ;
cmd_lcd( 0x80 ) ;
printf(data_lcd, "Huynh Nhu");
```

```
delay_ms( 1000 ) ;
```

```
cmd_lcd( 0x01 ) ;
cmd_lcd( 0x80 ) ;
printf(data_lcd, "Thanh Thuy");
```

```
delay_ms( 1000 ) ;
```

```
cmd_lcd( 0x01 ) ;
cmd_lcd( 0x80 ) ;
printf(data_lcd, "Minh Quang");
```

```
delay_ms( 1000 ) ;
cmd_lcd( 0x01 ) ;
```

```

cmd_lcd( 0x80 ) ;
printf(data_lcd,"The Bao");

delay_ms( 1000 ) ;

cmd_lcd( 0x01 ) ;
cmd_lcd( 0x80 ) ;
printf(data_lcd,"Start Counter");

delay_ms( 500 ) ;

cmd_lcd( 0xC0 ) ;          //Contro o dau dong 2
printf(data_lcd," So SP= " );

Set_timer0(0) ;          //Gia tri cua TMR0 = 0

While (1)
{
cmd_lcd( 0xC0 + 0x07 ) ; //Cho con tro nhay toi vi tri can hien thi
value = get_timer0() ;   //Dua gia tri trong TMR0 vao bien Value

if(value == 100)
{ solan++                ;
  set_timer0(0)          ;
  value=0                ;
}

hienthi=solan*100+value;

if(hienthi==1000)
{
solan=0                ;
Set_timer0(0)          ;

hienthi=0              ;
}

convert(hienthi)      ;

data_lcd(ngan)        ;

data_lcd(tram)         ;

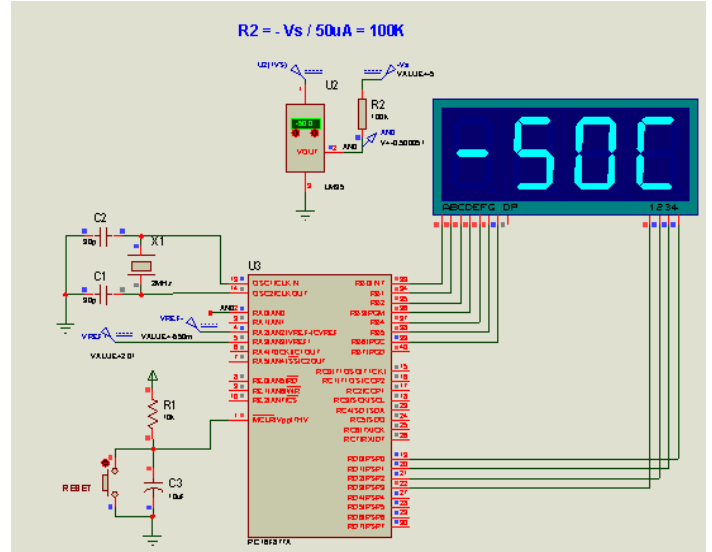
data_lcd(chuc)         ;

data_lcd(donvi)       ;

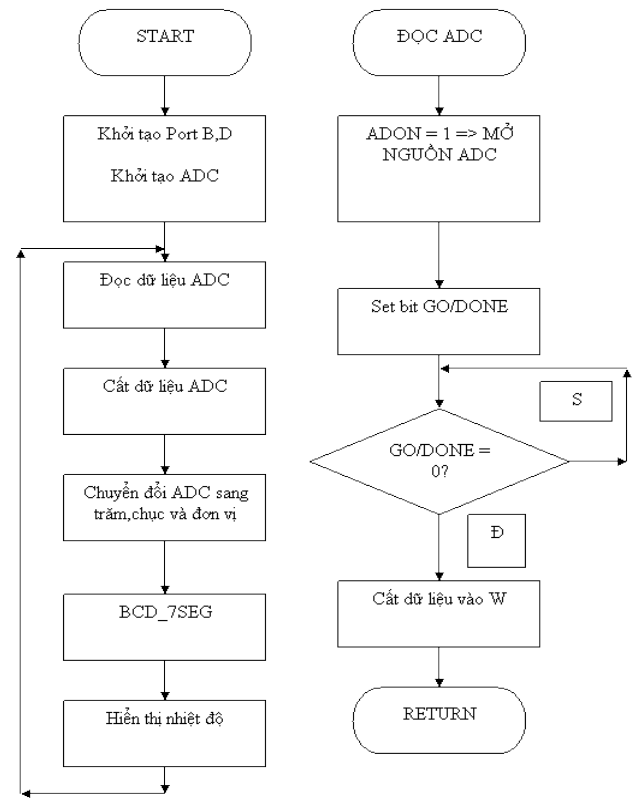
}
}

```

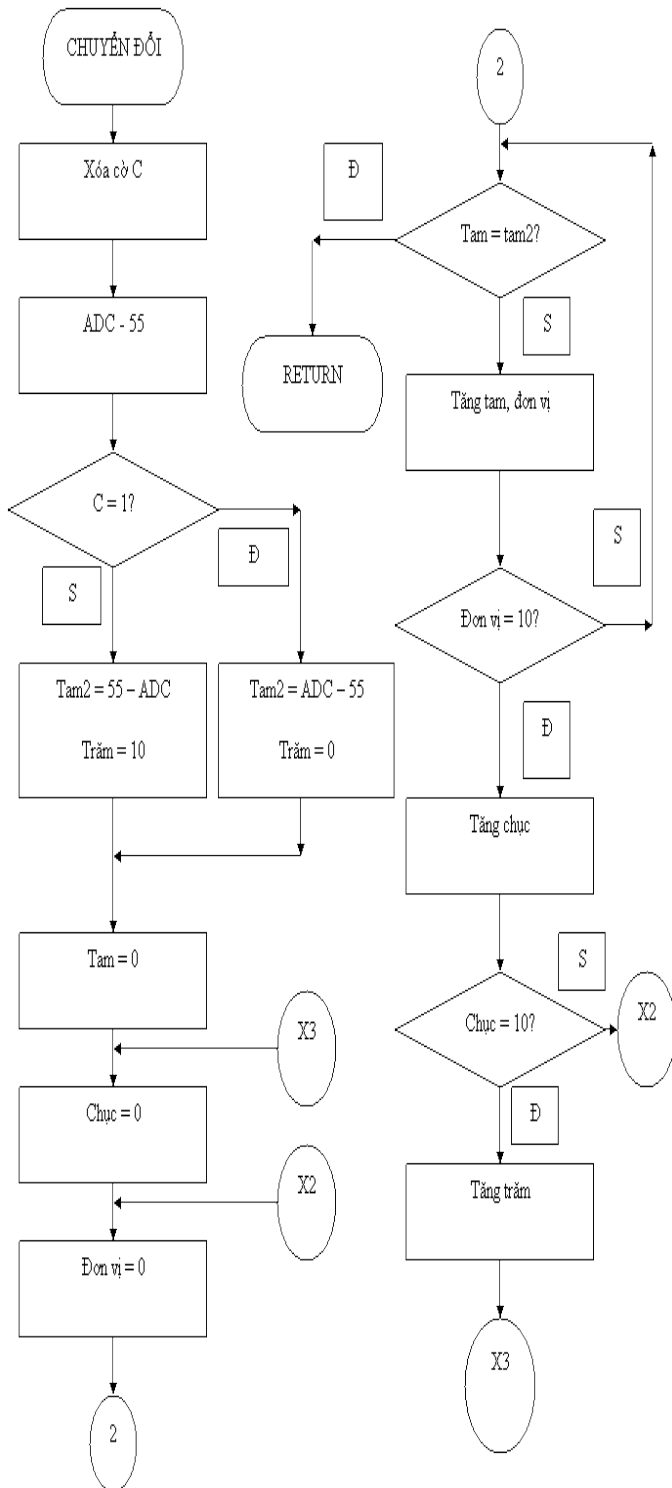
## BÀI 9: ĐO NHIỆT ĐỘ DÙNG CẢM BIẾN LM35 VỚI PIC 16F877A DÙNG NGÔN NGỮ ASSEMBLY



### LƯU ĐỒ



CHƯƠNG TRÌNH



title "chương trình hiển thị nhiệt độ"

```

processor p16f877a
include <p16f877a.inc>
__CONFIG
_CP_OFF&_PWRTE_ON&_WDT_OFF&_HS_OSC&_LV
P_OFF
    
```

+++++  
; các biến được sử dụng  
+++++

```

cblock 0x020
count1
count2
count3
tram
chuc
dvi
tam
tam2
bien1
bien2
bien3
so55
dem
kqADC
endc
    
```

```

;----- CT -----
org 0x005
goto start
    
```

```

;----- khởi tạo port b,d -----
start
    
```

```

bcf STATUS,RP1
bsf STATUS,RP0 ; chọn bank 1
clrf TRISB
clrf TRISD ; làm ngõ xuất dữ liệu
    
```

```

;----- khởi tạo ngõ vào ADC -----
ADC
    
```

```

movlw 0x0F
movwf ADCON1 ;chọn AN2=Vref- va AN3=Vref+
bcf STATUS,RP0 ; tro ve bank 0
    
```

```

;----- MAIN -----
main
    
```

```

movlw 0x01
call docADC
movwf kqADC
call chuyen
    
```

```

    call bcd_7seg
    call delhthi
    goto main
;----- doc ADC dung bit GO/DONE -----
docADC
movwf ADCON0
movlw 0x14
movwf dem
delay12
decfsz dem,1
goto delay12
bsf ADCON0,2
gone btfsz ADCON0,2
goto gone
movf ADRESL,0
return
;----- chuyen doi -----
chuyen bcf STATUS,C
movlw 0x37
subwf kqADC,0
Btfss STATUS,C ;neu phep tru kq duong C=1 va nguoc lai
goto x4 ;ADC < 55 nhay den x4 de tao dau "-"
movwf tam2
Movlw 0x00
Movwf tam
Movlw 0x00
Movwf tram
goto X3
x4
Movlw 0x00
Movwf tam
movlw 0x37
movwf so55
movf kqADC,0
subwf so55,0
movwf tam2
movlw 0x0a
movwf tram
X3
Movlw 0x00
Movwf chuc
X2 Movlw 0x00
Movwf dvi
X1 Movf tam,0
Xorwf tam2,0
Btfss STATUS,Z
Goto X5
Goto X6
X5 Incf tam,1
Incf dvi,1
Movf dvi,0
Xorlw 0x0A
Btfss STATUS,Z
Goto X1
Incf chuc,1
Movf chuc,0
Xorlw 0x0A
Btfss STATUS,Z
Goto X2
Incf tram,1
Movf tram,0
Xorlw 0x0A
Btfss STATUS,Z
Goto X3
X6 return
;----- bcd_7seg -----
bcd_7seg
movf dvi,0
call table
movwf bien1
movf chuc,0
call table
movwf bien2
movf tram,0
call table
movwf bien3
;----- del_hthi -----
delhthi
movlw 0x01
movwf count1
del1
movlw 0x10
movwf count2
del2
call hthi
decfsz count2,1
goto del2
ecfsz count1,1
goto del1
return
;----- hien thi -----
hthi

```



```

Movlw 0xC6
Movwf PORTB
  Movlw 0x01
  Movwf PORTD
  Call delay
  Movlw 0xff
  Movwf PORTB

```

```

movf bien1,0
movwf PORTB
movlw 0x02
movwf PORTD
call delay
movlw 0xff
movwf PORTB

```

```

movf bien2,0
movwf PORTB
movlw 0x04
movwf PORTD
call delay
movlw 0xff
movwf PORTB

```

```

movf bien3,0
movwf PORTB
movlw 0x08
movwf PORTD
call delay
movlw 0xff
movwf PORTB
return

```

```

;----- delay -----
delay

```

```

  movlw 0x20
  movwf count3
  del3

  decfsz count3
  goto del3
  return

```

```

;----- table -----

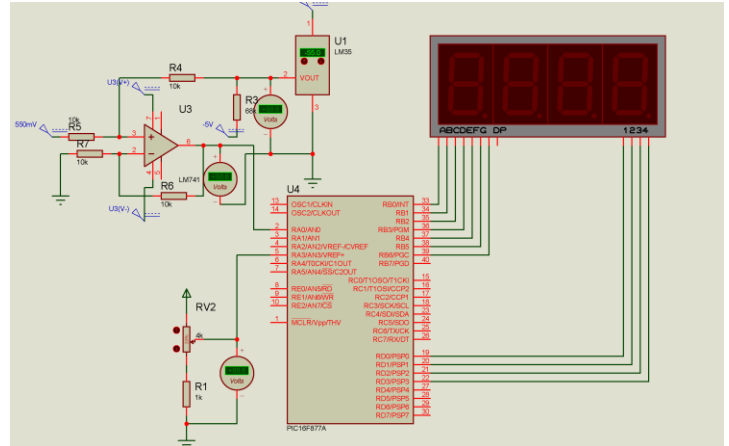
```

```

table
  addwf PCL,1
  DT
  0xc0,0xf9,0xa4,0xb0,0x99,0x92,0x82,0xf8,0x80,0x90,0xbf
end

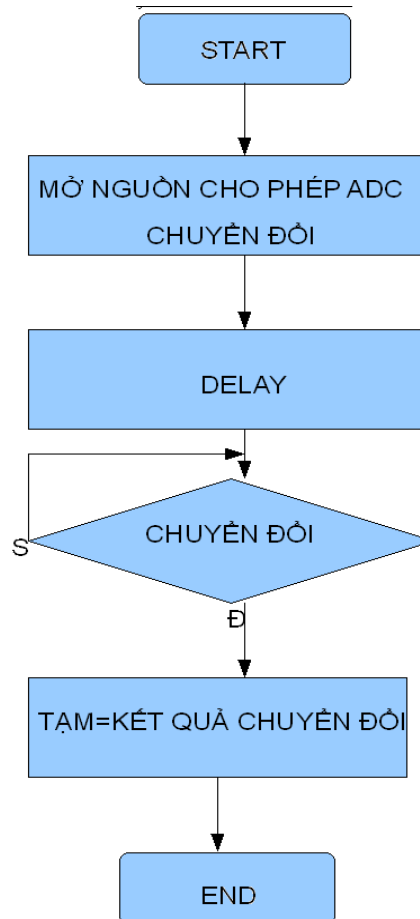
```

## BÀI 10: DÙNG PIC16F877A GIAO TIẾP VỚI LED 7 ĐOẠN VÀ CẢM BIẾN NHIỆT ĐỘ LM35 NỐI NGÕ VÀO KÊNH THỨ 0. LẬP TRÌNH ĐO NHIỆT ĐỘ DÙNG NGÔN NGỮ C.



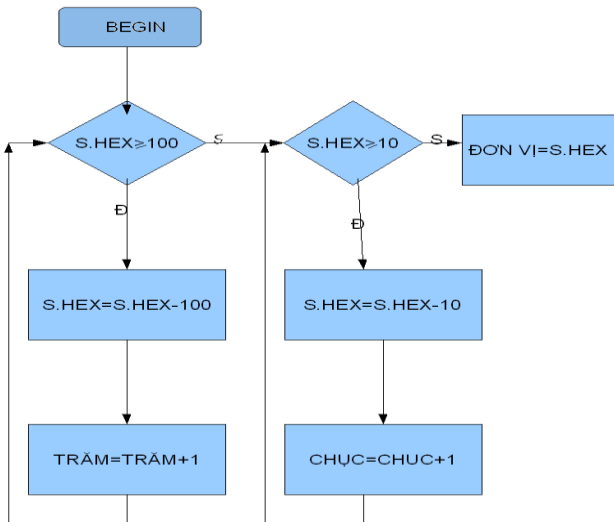
**LƯU ĐỒ:**

**LƯU ĐỒ REAL ADC**

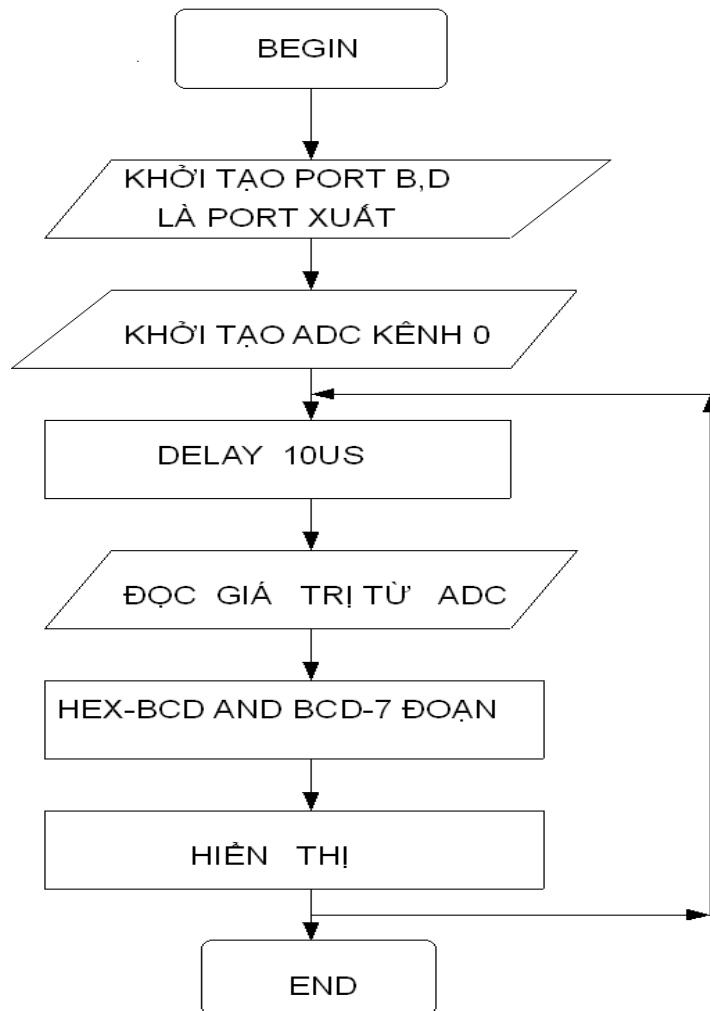


**LƯU ĐỒ HEX TO BCD:**

**CHƯƠNG TRÌNH**



**LƯU ĐỒ CHƯƠNG TRÌNH CHÍNH:**



```
#include <16F877a.h>
```

```
#include <KhaiBaoTGhi_16F877A.h>
#fuses NOWDT,PUT,HS,NOPROTECT,NOLVP
#use delay(clock=20000000)
```

```
#device ADC=8
#use fast_io(d)
#use fast_io(b)
int8 i,tram,chuc,donvi;
signed int16 tam,doc;
const unsigned char
tra[]={0xc0,0xf9,0xa4,0xb0,0x99,0x92,0x82,0xf8,0x80,0x9
0,0xbf,0xff,0xc6};
```

```
void hex_bcd() //chuyen doi so hex sang so bcd
```

```
{
    tram=tam/100;
    tam=tam%100;
    chuc=tam/10;
    donvi=tam%10;
}
```

```
void hienthi()
```

```
{
    i=0;
    while(i<200)
    {
        portb=tra[chuc]; //xuat hang chuc ra port
        portd=0x02;
        delay_us(5);
        portd=0x00;
```

```
        portb=tra[donvi]; //xuat hang don vi
        portd=0x04;
        delay_us(5);
        portd=0x00;
```

```
        portb=tra[12]; //xuat do c
        portd=0x08;
        delay_us(5);
        portd=0x00;
```

```
        if (doc<55)
        {
            portb=tra[10]; //xuat dau am port
            portd=0x01;
            delay_us(5);
```

```

portd=0x00;
}

else if (doc<155)

{

portb=tra[11]; //xoa so 0 vo nghia
portd=0x01 ;

}

else
{
portb=tra[tram]; //xuat hang tram
portd=0x01;
delay_us(5);
portd=0x00;
}

i++;
}
}

```

**void main()**

```

{

set_tris_d(0x00); //thiet lap xuat cho port d
set_tris_b(0x00); //thiet lap xuat cho port b

```

```

setup_adc(adc_clock_internal); //thoi gian lay mau bang xung
clock IC(2-6us)

```

```

setup_adc_ports(an0_an1_vss_vref); //A0 A1 VRef+=A3,VRef=-0

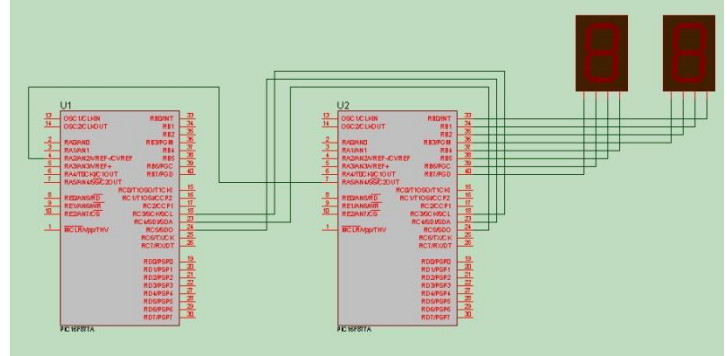
```

```

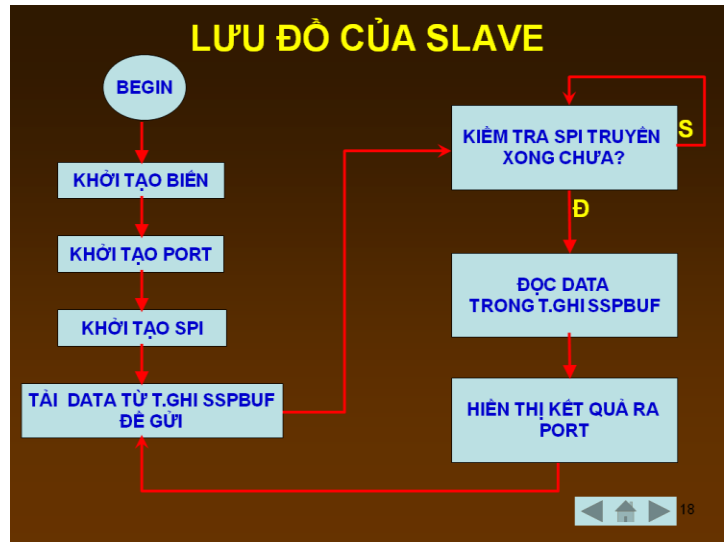
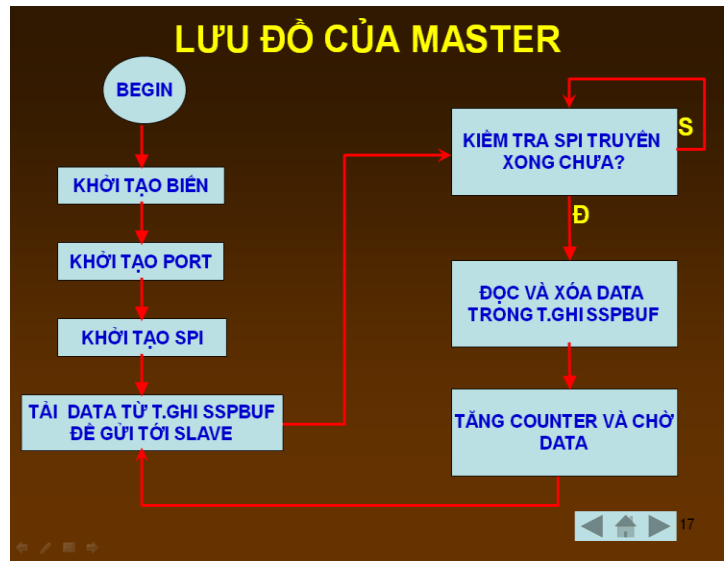
set_adc_channel(0); //chon chan 0 doc tin hieu analog
delay_us(10); //delay 10us roi moi dung ham read_ADC dam bao ket
qua dung
while(1)
{
doc=read_adc();
tam=abs(doc-55);
hex_bcd();
hienthi();}
}

```

**BÀI 11: KHẢO SÁT TRUYỀN DỮ LIỆU SPI CỦA PIC16F877A .SỬ DỤNG NGÔN NGỮ ASSEMBLY**



**LƯU ĐỒ**



**CHƯƠNG TRÌNH****CHƯƠNG TRÌNH CỦA MASTER**

```
list p=16F877A
#include "p16F877A.inc"
__CONFIG_CP_OFF & _DEBUG_OFF & _WRT_OFF &
_CPD_OFF & _LVP_OFF & _BODEN_OFF &
_PWRTE_ON & _WDT_OFF & _XT_OSC
Ctr0 EQU 0x20 ; Bien dem – gui du lieu den spi
Dly0 EQU 0x21 ; Bien delay 0
Dly1 EQU 0x22 ; Bien delay 1
#define SS PORTA,2 ; Gan chan chon slave (RA2)
ORG 0x000 ;

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
; Khoi tao ho tro SPI
BANKSEL TRISA ; Chon bank 1
movlw 0x00 ; Khoi tao port A
movwf TRISA ; Xuat port A
movlw 0x06 ; Tat che do A/D (tuong tu)(trg 92)
movwf ADCON1 ; cho phep port A su dung nhu la port
xuat nhap so

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
; Khoi tao SPI
BANKSEL TRISC ; Chon bank 1
movlw b'00010000' ; SCK chan ra xung (Master),SDI chan nhan
data
movwf TRISC ; SDO chan ra data
movlw b'01000000' ; du lieu dc lay mau tai thoi diem giua xung
clock
movwf SSPSTAT ; du lieu dc lay mau tai thoi diem giua
xung clock
BANKSEL SSPCON ; Chon bank 0
movlw b'00110001' ; 0001 SPI master mode,tan so xung
clock bang
;Fosc /16
movwf SSPCON ; bat che do SSP
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
Send_DT bcf SS ; Ngo ra cho phep lua chon chip (muc
thap)
movf Ctr0,W ; lay gia tri cua bien dem gan vao t.ghi W
movwf SSPBUF ; W => SSPBUF
BANKSEL SSPSTAT ; Chon bank 1
```

**Char1** btfss SSPSTAT,BF ; kiem tra da truyen xong chua?

Goto Char1 ; nhay lai kiem tra tai nhan char1 neu chua truyen xong

BANKSEL SSPBUF ; Chon bank 0

movf SSPBUF,W ; doc data tu t.ghi SSPBUF =>W  
; du lieu nay ko dc dung

bsf SS ; ngat ngo ra lua chon slave (muc cao la xoa)

incf Ctr0,F ; tang bien dem

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**Delay** movlw 0xF0 ;  
movwf Dly1 ;  
movlw 0x0F ;  
movwf Dly0

**DlyLoop** decfsz Dly0,F ;  
Goto DlyLoop ;  
Decfsz Dly1,F ;

**goto** DlyLoop ;

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

goto Send\_DT ; quay lai gui data tiep theo (byte)

**END**

**CHƯƠNG TRÌNH CỦA SLAVE**

```
list p=16F877A
```

```
#include "p16F877A.inc"
```

```
__CONFIG_CP_OFF & _DEBUG_OFF &
_WRT_OFF & _CPD_OFF & _LVP_OFF &
_BODEN_OFF & _PWRTE_ON & _WDT_OFF &
_XT_OSC
```

```
ORG 0 ;
```

```
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
```

**; Khoi tao ho tro SPI**

```
BANKSEL TRISA ; Chon bank 1
```

```
movlw D'5' ; (trg 74)
```

```
movwf TRISA ; cho phep chan SS nhan du lieu
```

```
movlw 0x06 ; Tat che do A/D
```

```
movwf ADCON1 ; cho phep port A su dung nhu la
```

```
port xuat nhap so
```

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**; khai tao port ngo ra**

**BANKSEL TRISB ;**

*movlw 0x00 ; khai tao port B la port xuất*

*movwf TRISB ;*

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**; khai tao SPI**

**BANKSEL TRISC ; Chon bank 1**

*movlw B'00011000' ; SCK la ngo vao xung clock*

*(Slave), SDI ngo vao ; du lieu*

*movwf TRISC ; SDO la ngo ra du lieu (b.gom cac ngo con lai cua port C)*

*movlw B'01000000' ; du lieu dc lay mau tai thoi diem giua xung clock*

*movwf SSPSTAT ; du lieu dc lay mau tai thoi diem giua xung clock*

**BANKSEL SSPCON ; Chon bank 0**

*movlw B'00110100' ; 0100 Mode 1,1 SPI Slave Mode,*

*movwf SSPCON ; bat che do SSP*

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**KT** *movlw SSPSTAT ; Kiem tra gian tiep*

*movwf FSR ; W=>FSR (trg 63)*

*btfs INDF,BF ;kiem tra bit BF trong t.ghi INDF (trg 63)*

*goto KT ;*

*RX\_Data*

**BANKSEL SSPBUF ; chon bank 0**

*movf SSPBUF,W ; SSPBUF=>W*

**BANKSEL PORTB ; chon bank 0**

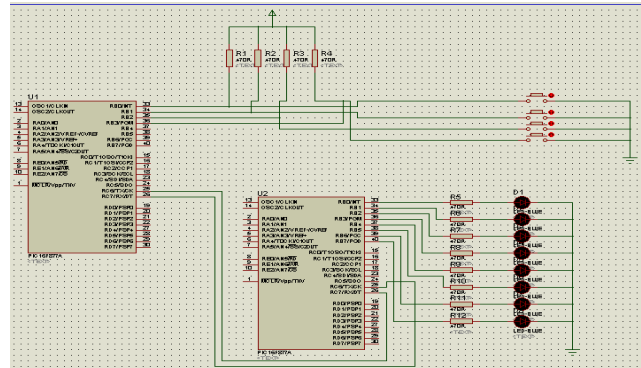
*movwf PORTB ; Xuất du lieu ra port B*

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

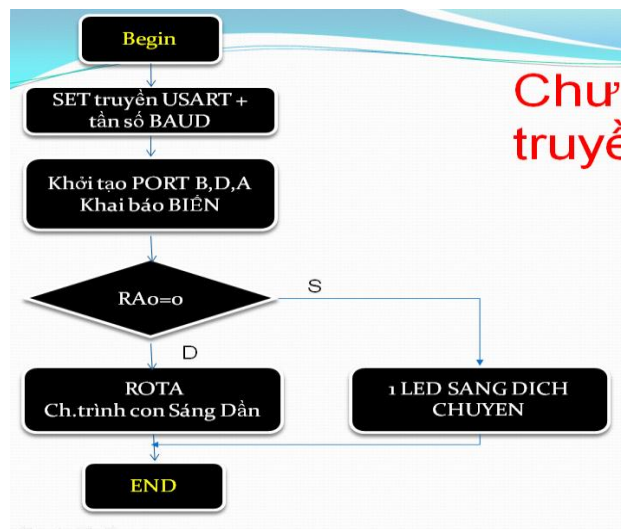
*goto KT ; quay lai nhan byte tiep theo*

**END**

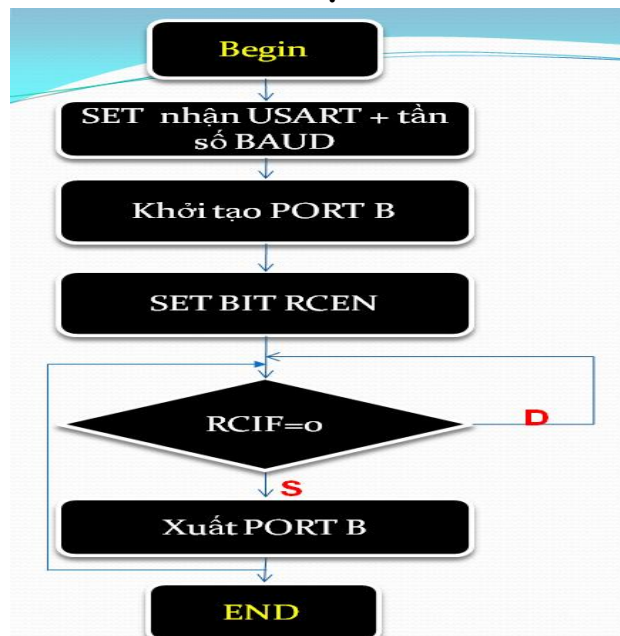
## BÀI 12: TRUYỀN DỮ LIỆU USART SỬ DỤNG ASSEMBLY

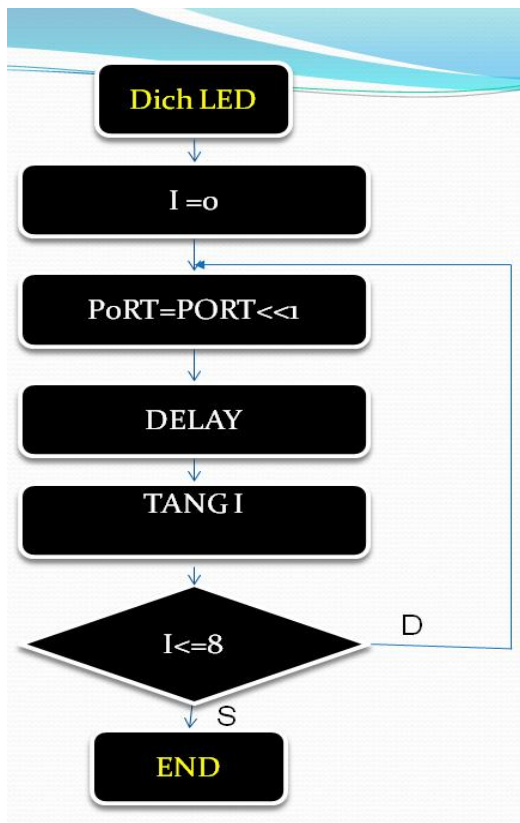
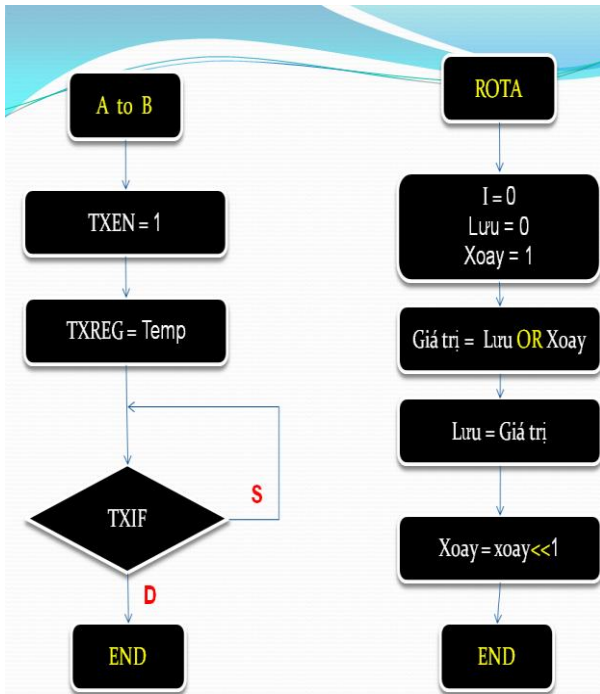


### CHƯƠNG TRÌNH TRUYỀN PIC A



### CHƯƠNG TRÌNH NHẬN PIC B





## CHƯƠNG TRÌNH

### CHƯƠNG TRÌNH TRUYỀN

```

title "TRUYEN USART"
processor          p16f877a
include           <p16f877a.inc>
__CONFIG
    _CP_OFF&_WDT_OFF&_LVP_OFF&_PWRTE_
ON&_HS_OSC&_BODEN_OFF&_CPD_OFF
;*****
;KHAIBAO CAC HANG SO
;*****
SW1 EQU 0
SW2 EQU 1
SW3 EQU 2
SW4 EQU 3
LED1 EQU 4
LED2 EQU 5
LED3 EQU 6
LED4 EQU 7
;*****
;KHAIBAO BIEN
;*****
COUNT EQU 0x20
COUNT1 EQU 0x21
COUNTa EQU 0x22
COUNTb EQU 0x23
;*****
;CHUONG TRINH CHINH
;*****
ORG 0x000
GOTO Start

Start
    bcf STATUS,RP1
    bsf STATUS,RP0 ; Chon bank 1
    clrf PORTB
    clrf PORTD
    bsf STATUS,RP0 ;chon bank 0
    movlw B'00001111'
    movwf TRISB
    movlw 0x00
    movwf TRISD
    bsf STATUS,RP0 ; Chon bank 1
    call khoitaousart
  
```

```

    bcf     STATUS,RP0 ; Chon bank 0
Loop1
    clrf   COUNT
    call   CHECK_KEY
Loop2
    movf   COUNT,W
    btfsc  PORTB,LED1
    call   TABLE1

    btfsc  PORTB,LED2
    call   TABLE2

    btfsc  PORTB,LED3
    call   TABLE3

    btfsc  PORTB,LED4
    call   TABLE4
    movwf  PORTD
    call   transmitAtoB
    call   DELAY
    incf   COUNT,0
    xorlw  D'8'
    btfsc  STATUS,Z
    goto   Loop1

    incf   COUNT,1
    goto   Loop2
;*****
;SANG TU PHAI SANG TRAI
;*****
TABLE1
    addwf  PCL,F
    retlw  b'10000000'
    retlw  b'11000000'
    retlw  b'11100000'
    retlw  b'11110000'
    retlw  b'11111000'
    retlw  b'11111100'
    retlw  b'11111110'
    retlw  b'11111111'
;*****
;SANG TU GIUA RA 2 BEN
;*****
TABLE2
    addwf  PCL,F
    retlw  b'00011000'
    retlw  b'00100100'
    retlw  b'01000010'
    retlw  b'10000001'
    retlw  b'01000010'
    retlw  b'00100100'
    retlw  b'00011000'
    retlw  b'00100100'
;*****
;SANG XEN KE 2 DIEM
;*****
TABLE3
    addwf  PCL,F
    retlw  b'10000000'
    retlw  b'11000000'
    retlw  b'01100000'
    retlw  b'00110000'
    retlw  b'10011000'
    retlw  b'11001100'
    retlw  b'01100110'
    retlw  b'11011011'
;*****
;SANG DAN TU TRAI SANG PHAI
;*****
TABLE4
    addwf  PCL,F
    retlw  b'00000001'
    retlw  b'00000011'
    retlw  b'00000111'
    retlw  b'00001111'
    retlw  b'00011111'
    retlw  b'00111111'
    retlw  b'01111111'
    retlw  b'11111111'
;*****
;CHECK_KEY
;*****
CHECK_KEY
    btfss  PORTB,SW1
    call   SWITCH1

```

```

    btfss PORTB,SW2
    call SWITCH2

    btfss PORTB,SW3
    call SWITCH3

    btfss PORTB,SW4
    call SWITCH4
    return
;*****
;CHECK_SWITCH
;*****
SWITCH1
    clrf PORTB
    bsf PORTB,LED1
    return
SWITCH2
    clrf PORTB
    bsf PORTB,LED2
    return
SWITCH3
    clrf PORTB
    bsf PORTB,LED3
    return
SWITCH4
    clrf PORTB
    bsf PORTB,LED4
    return
;*****
;DELAY
;*****
DELAY
    movlw D'300'
    movwf COUNT1
D1
    movlw 0xC7
    movwf COUNTa
    movlw 0x01
    movwf COUNTb
DELAY_0
    decfsz COUNTa,1
    goto $+2
    decfsz COUNTb,1
    goto DELAY_0

    decfsz COUNT1,1
    goto D1
    return
;*****
;KhoiTaoUSART:
;*****
khoitaousart
    movlw D'129' ;Gia tri toc do baud ung voi
    9600, BRGH = 1, xtal 20 MHz
;    bcf STATUS,RP1
;    bsf STATUS,RP0 ;Chon bank cho SPBRG

    movwf SPBRG ;Dat toc do baud = 9600
    movlw 0x24 ;Che do: high-speed, cho
    phep xuat TXEN=1, truyen bat dong bo
    movwf TXSTA ;TXSTA cung bank voi
    SPBRG

    movlw 0x90 ;Che do: nhan lien tuc, 8-
    bit, dung cac chan TX/RX
    BCF STATUS,RP0 ; Chon bank RCSTA
    bank0

    movwf RCSTA
    return
;*****
;chuongtrinhTRUYENA_B:
;*****
transmitAtoB
    MOVWF TXREG
    btfsc PIR1,10
    GOTO transmitAtoB
    RETURN
;*****
END

CHƯƠNG TRÌNH NHẬN

title "NHAN USART"
processor p16f877a
include <p16f877a.inc>
__CONFIG
    _CP_OFF&_WDT_OFF&_LVP_OFF&_PWRTE_
    ON&_HS_OSC&_BODEN_OFF&_CPD_OFF

```



\*\*\*\*\*

**;CHUONG TRINH CHINH**

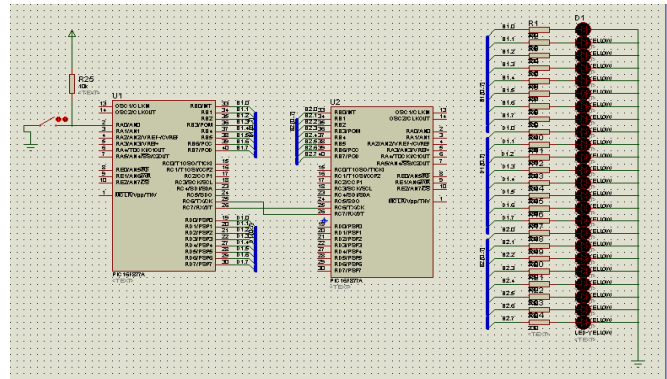
\*\*\*\*\*

```

ORG 0x000
GOTO Start

Start
    bcf STATUS,RP1
    bsf STATUS,RP0 ; Chon bank 1
    clrf PORTB
    bsf STATUS,RP0 ;chon bank 0
    movlw B'00000000'
    movwf TRISB
    bsf STATUS,RP0 ; Chon bank 1
    call khoitaousart
loop   call transmitAtoB
        MOVWF PORTB
        goto loop
*****
;KhoiTaoUSART
*****
khoitaousart
    movlw D'129' ;Gia tri toc do baud ung voi
9600, BRGH = 1, xtal 20 MHz
    movwf SPBRG ;Dat toc do baud = 9600
    movlw 0x04 ;Che do: high-speed, truyen
bat dong bo
    movwf TXSTA ;TXSTA cung bank voi
SPBRG
    movlw 0x90 ;Che do: nhan lien tuc, 8-
bit, dung cac chan TX/RX
    BCF STATUS,RP0 ; Chon bank RCSTA bank0
    movwf RCSTA
    return
*****
;chuongtrinhTRUYENA_B
*****
transmitAtoB
    btfsc PIR1,20
    GOTO transmitAtoB
    MOVF RCREG,w
    RETURN
*****
end
    
```

**BÀI 12 SỬ DỤNG C:**



**TRUYỀN:**

```

#include<16f877a.h>
#include<KhaiBaoTGhi_16F877A.H>
#fuses NOWDT,PUT,HS,NOPROTECT,NOLVP
#use delay(clock=2000000)
#use rs232(baud=9600,xmit=pin_C6,rcv=pin_C7) //khai
bao toc do baud su dung chuan rs232
#use fast_io(b) //khai bao dung port b
#use fast_io(d)
#use fast_io(a) //kb dung port d
#locate b_B=0x22
int8 i,giatri,luu,xoay;
//=====
//chuong trinh con
//=====
void A_to_B()
{
    TXEN=1; //cho phep truyen du lieu TXSTA<5>
    TXREG=b_B; // load data vao TG dem truyen
    while(~TXIF) // cho den khi load xong PIR1<4>
}
void rota()
{
    giatri=luu|xoay; // luu or xoay
    luu=giatri;
    xoay=xoay<<1;
}
//=====
//chuong trinh chinh
//=====
void main ()
    
```

```

{
  set_tris_b(0x00); // set portB out
  set_tris_d(0x00); // set port D out
  set_tris_a(0x01);
  while(1)
  {
    if(ra0==0)
    {
      i=0;
      luu=0;
      xoay=1;
      portb=0;
      portd=0;
      b_B=0;
      A_TO_B(); //goi b_B qua portb cua PIC 2
      delay_ms(100);
      for(i=1;i<=8;i++)
      {
        rota();
        portb=giatri;
        delay_ms(100);
      }

      i=0;
      luu=0;
      xoay=1;
      for(i=1;i<=8;i++)
      {
        rota();
        portd=giatri;
        delay_ms(100);
      }
      i=0;
      luu=0;
      xoay=1;
      for(i=1;i<=8;i++)
      {
        rota();
        b_B=giatri;
        A_TO_B();
        delay_ms(100);
      }
    }
  }
else
  {
    i=0;
    portb=0x00;
    portd=0x00;
    b_B=0x00;
    A_TO_B(); //goi b_B qua portb cua PIC 2
    delay_ms(100);
    portb=0x01;
    delay_ms(100);
    for(i=1;i<=8;i++)
    {
      delay_ms(100);
      portb=portb<<1;
    }
    portb=0x00;
    i=0;
    portd=0x01;
    for(i=1;i<=8;i++)
    {
      delay_ms(100);
      portd=portd<<1;
    }
    portd=0x00;
    i=0;
    b_B=0x01;
    for(i=1;i<=8;i++)
    {
      A_TO_B();
      delay_ms(100);
      b_B=b_B<<1;
    }
  }
}
}
}
}
}

NHẬN:
#include<16f877a.h>
#include<KhaiBaoTGhi_16F877A.H>
#fuses NOWDT,PUT,HS,NOPROTECT,NOLVP
#use delay(clock=20000000)
#use rs232(baud=9600,xmit=pin_C6,rcv=pin_C7) //khai
bao toc do baud
#use fast_io(b)

```

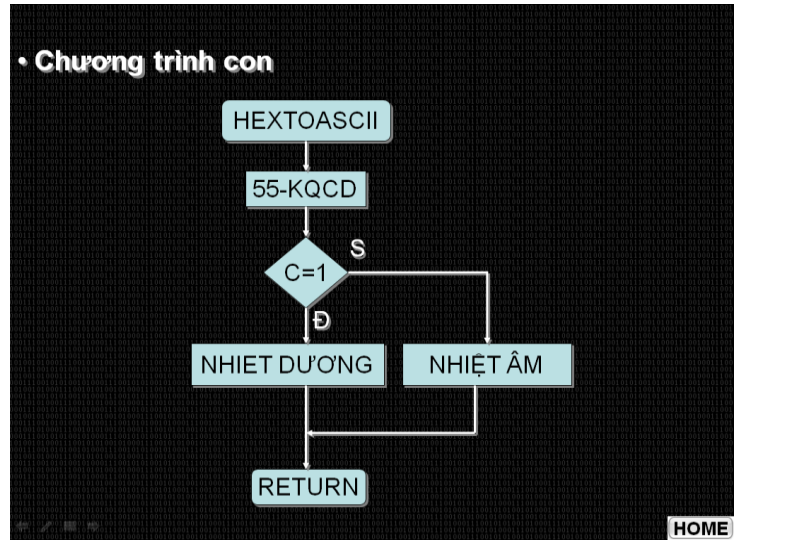
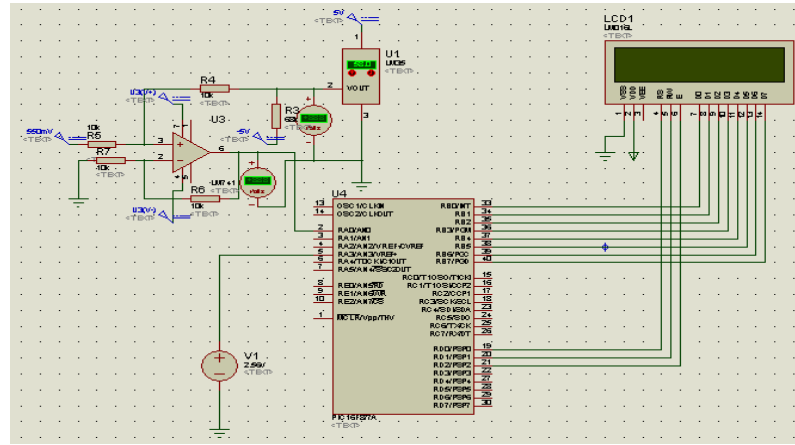
**BÀI 13: Sử dụng Pic 16F877A để đo nhiệt độ với LM35, hiển thị LCD, ngõ vào kênh AN0.SỬ DỤNG ASSEMBLY**

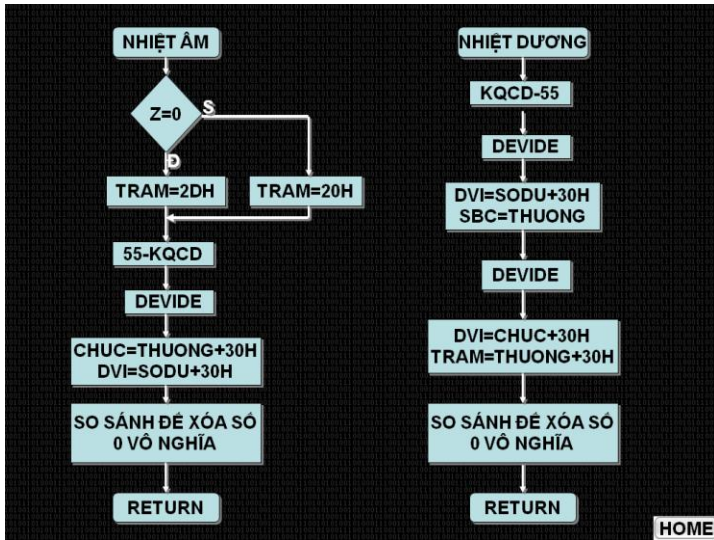
```

=====
// chương trình chính
=====

main()
{
    set_tris_b(0x00);
    RCEN=1; //cho phép nhận dữ liệu
    while(1)
    {
        while(~RCIF)
        {
        }
        portb= rcreg;
        rcreg=0;
    }
}

```





**CHƯƠNG TRÌNH:**

; Ten chương trình :Mach do nhiet do dung cam bien LM35  
 hien thi LCD  
 ; Mo ta phan cung : Dung PIC16f877aA - thach anh 20MHz  
 ; :cam bien nhiet LM35 mac vao kenh AN0 cua port0  
 ; :LCD giao tiep 8 bit.  
 ; :RS, RW, E mac vao E mac vao 3 chan RD0, RD1 RD2

```

=====
TITLE "Mach Do Nhiet Dung Cam Bien LM35 Hien Thi
LCD.asm"
PROCESSOR P16F877A
INCLUDE <P16F877A.inc>
__CONFIG __CP_OFF & __PWRTE_ON & __XT_OSC &
_WDT_OFF & __HS_OSC & __LVP_OFF
=====
    
```

- CBLOCK 0x30
- COUNT
- TRAM
- CHUC
- DVI
- KQCD
- SOBICHIA
- SOCHIA
- SODU
- THUONG
- COUNT1
- COUNT2
- COUNT3
- COUNT4

```

A
TAM
ENDC
=====
ORG 0X0000
GOTO START
START
BANKSEL TRISB
CLRF TRISB ;PORTB XUAT LED
CLRF TRISD
CALL KTADC
CALL KTLCD
MAIN
CALL CHUYENDOI
CALL HEXTOASCII
CALL DONG1
CALL DONG2
GOTO MAIN
;*****
KTADC
BANKSEL ADCON1
MOVLW 0X01
;NGO VAO ANALOG,RIGHT JUSTIFY,Fosc/2
MOVWF ADCON1
BANKSEL ADCON0
MOVLW 0XC1 ;CHON RA0 LAM NGO
VAO,ADON=1,BAT ADC
MOVWF ADCON0
CALL DELAY1
;CHO 1 KHOANG THOI GIAN TRUOC KHI BAT DAU
;*****
;KIEM TRA KET QUA
CHUYENDOI
BSF ADCON0,GO
;SET BIT "GO",BAT DAU CONVERT
BTFSC ADCON0,GO
;KIEM TRA BIT "DONE" CUA ADCON0
GOTO $-1;NEU BANG 1 THI CHO TIEP TUC
MOVF ADRESL,W
MOVWF KQCD

RETURN
;*****
DELAY1
MOVLW D'10'
    
```

```

MOVWF COUNT
BACK
MOVLW D'4'
MOVWF COUNT1
DECFSZ COUNT1,F
GOTO $-1
DECFSZ COUNT,F
GOTO BACK
RETURN

```

\*\*\*\*\*

**;chuong trinh con chuyen ma hex sang MA LCD**

-----

### HEXTOASCII

```

MOVF KQCD,0
SUBLW D'55' ;so sanh
ket qua voi 55
BTFSS STATUS,C ;so sanh voi co c
GOTO NHIETDUONG ;co
C=0, tuc phep toan co kq <0
GOTO NHIETAM ;co C=1,
tuc phep toan co kq >0

```

**NHIETAM** ;giai ma nhiet do am tu -55 den -1 do C

```

BTFSC STATUS,Z
GOTO Y1
MOVLW B'00101101'
MOVWF TRAM ;ma asscii
cua dau '-'
GOTO Y2
Y1 MOVLW B'00100000'
MOVWF TRAM
Y2 MOVLW D'55'
MOVWF TAM
MOVF KQCD,0
SUBWF TAM,0
MOVWF SOBICHIA
MOVLW D'10'
MOVWF SOCHIA
CALL DIVIDE
MOVF SODU,0
ADDLW B'00110000'
MOVWF DVI
MOVF THUONG,0
ADDLW B'00110000'
MOVWF CHUC

```

```

MOVF CHUC,0;kiem tra hang chuc de xoa so 0 vo
nghia

```

```

XORLW B'00110000' ;so sanh voi so 0
BTFSS STATUS,Z
GOTO EXIT ;thoat chuong trinh con neu chuc

```

khac 0

```

MOVLW B'00100000' ;neu chuc la 0 thi
hien thi khoang trang
MOVWF CHUC
GOTO EXIT

```

### NHIETDUONG

```

MOVLW D'55'
SUBWF KQCD,0
MOVWF SOBICHIA;sobichia = kqcd - 55
MOVLW D'10'
MOVWF SOCHIA
CALL DIVIDE
MOVF SODU,0
ADDLW B'00110000'
MOVWF DVI
MOVF THUONG,0
MOVWF SOBICHIA
CALL DIVIDE
MOVF SODU,0
ADDLW B'00110000'
MOVWF CHUC
MOVF THUONG,0
ADDLW B'00110000'
MOVWF TRAM
MOVF TRAM,0 ;kiem tra hang
tram de xoa so 0 vo nghia
XORLW B'00110000' ;so sanh voi so 0
BTFSS STATUS,Z
GOTO EXIT ;thoat chuong trinh con neu tram
khac 0
MOVLW B'00100000' ;neu tram
la 0 thi hien thi khoang trang
MOVWF TRAM
MOVF CHUC,0 ;kiem tra hang chuc de xoa
so 0 vo nghia
XORLW B'00110000' ;so sanh voi so 0
BTFSS STATUS,Z
GOTO EXIT ;thoat chuong trinh
con neu chuc khac 0

```

```

    MOVLW    B'00100000'
    ;neu chuc la 0 thi hien thi khoang trang
    MOVWF    CHUC
    GOTO EXIT
EXIT
    RETURN
;-----
;chuong trinh con divide
;-----
DIVIDE
    CLRF    THUONG
    MOVF    SOBICHIA,0
    MOVWF    SODU
X    MOVF    SOCHIA,    0
    SUBWF    SODU,0          ;W=sodu-
sochia, c=1 neu kq>=0 va nguoc lai
    BTFSS    STATUS,    C    ;bo qua lenh ke neu
c=1, kq duong
    GOTO EXIT1              ;thoat khoi chuong
trinh con neu kq am
    INCF    THUONG,1 ;tang thuong so len 1
    MOVWF    SODU
    GOTO X
EXIT1
    RETURN
;-----
;chuong trinh con khoi tao LCD
;-----
KTLCD
    MOVLW    0x38;Set 8 bit mode, hien thi 2
hang, kieu ki tu 5x8
    MOVWF    A
    CALL    GHIMADK
    CALL    DELAY40MS
    MOVWF    A
    CALL    GHIMADK
    CALL    DELAY40MS
    MOVLW    0X0C ;display on/off control
    MOVWF    A
    CALL    GHIMADK
    CALL    DELAY40MS
    MOVLW    0X01 ;tat hien thi,con tro doi ve
goc trai
    MOVWF    A

```

```

    CALL    GHIMADK
    CALL    DELAY40MS
    RETURN
GHIMADK
    MOVF    A,0
    MOVWF    PORTB
    BCF     PORTD,0
    BCF     PORTD,1
    BSF     PORTD,2
    BCF     PORTD,2
    RETURN
;-----
;chuong trinh con ghi nhiet do ra dong 1
;-----
DONG1
    MOVLW    0x80 ;ve dau dong thu nhat
    MOVWF    A
    CALL    GHIMADK
    CALL    DELAY
    CLRF    COUNT4
LABEL1
    MOVF    COUNT4,    0
    CALL    TABLE1
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    INCF    COUNT4,0
    XORLW    D'10'
    BTFSC    STATUS,    Z
    GOTO L1
    INCF    COUNT4,1
    GOTO LABEL1
L1
    MOVF    TRAM,0
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    MOVF    CHUC, 0
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    MOVF    DVI, 0
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY

```

```

    CLRF COUNT4
LABEL2
    MOVLW    B'11011111'
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    MOVF    COUNT4,    0
    CALL    TABLE2
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    RETURN

```

```

;-----
;chuong trinh con hien thi chu dong 2
;-----

```

```

DONG2
    MOVLW    0xc1
    MOVWF    A
    CALL    GHIMADK
    CALL    DELAY
    CLRF    COUNT4
LABEL3
    MOVF    COUNT4,    0
    CALL    TABLE3
    MOVWF    A
    CALL    GHIDL
    CALL    DELAY
    INCF    COUNT4,0
    XORLW    D'7'
    BTFSC    STATUS,    Z
    GOTO    EX1
    INCF    COUNT4,1
    GOTO    LABEL3
EX1    RETURN

```

```

;-----
;bang ma ki tu cua tabel
;-----

```

```

TABLE1
    ADDWF    PCL,    1
    DT      "NHIET DO: "
TABLE2
    ADDWF    PCL,    1
    DT      "C"

```

```

TABLE3
    ADDWF    PCL,    1
    DT      "NHOM 13"

```

```

;-----
;chuong trinh con ghi ki tu ra LCD
;-----

```

```

GHIDL
    MOVF    A,0
    MOVWF    PORTB
    BSF     PORTD,0
    BCF     PORTD,1
    BSF     PORTD,2
    BCF     PORTD,2
    RETURN

```

```

;-----
;cac chuong trinh con delay
;-----

```

```

DELAY    MOVLW    D'255'
          MOVWF    COUNT3
DELA1    DECFSZ    COUNT3
          GOTO    DELA1
          RETURN

```

```

DELAY40MS
    MOVLW    D'255'
    MOVLW    COUNT1
DE1    MOVLW    0XFF
        MOVWF    COUNT2
DE2    DECFSZ    COUNT2
        GOTO    DE2
        DECFSZ    COUNT1
        GOTO    DE1
        RETURN

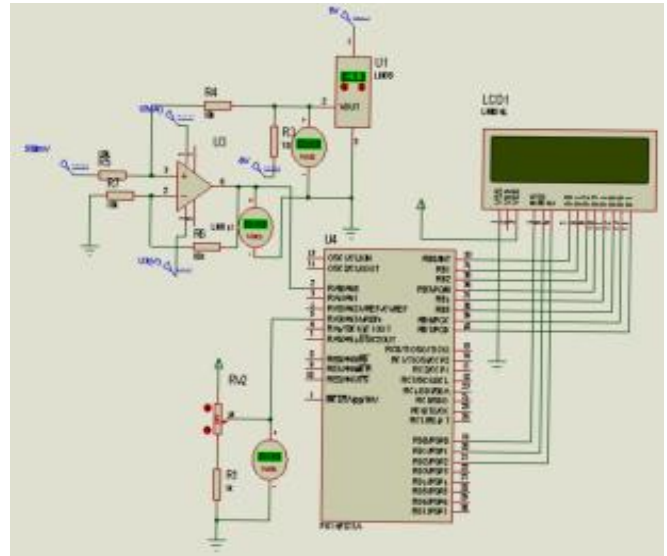
```

```

END

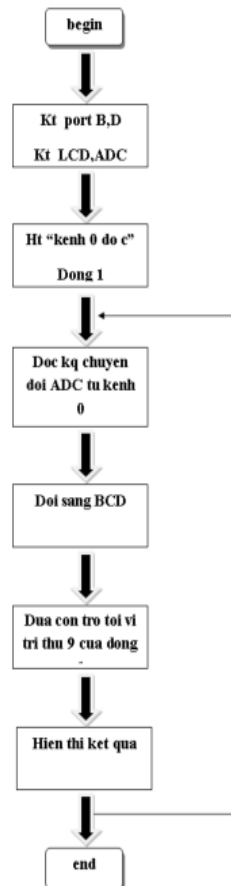
```

## BÀI 14: Đo nhiệt độ dùng LM35 kết nối với pic hiển thị trên LCD dùng kênh 0.SỬ DỤNG C



### LƯU ĐỒ

#### Lưu ct chính đồ

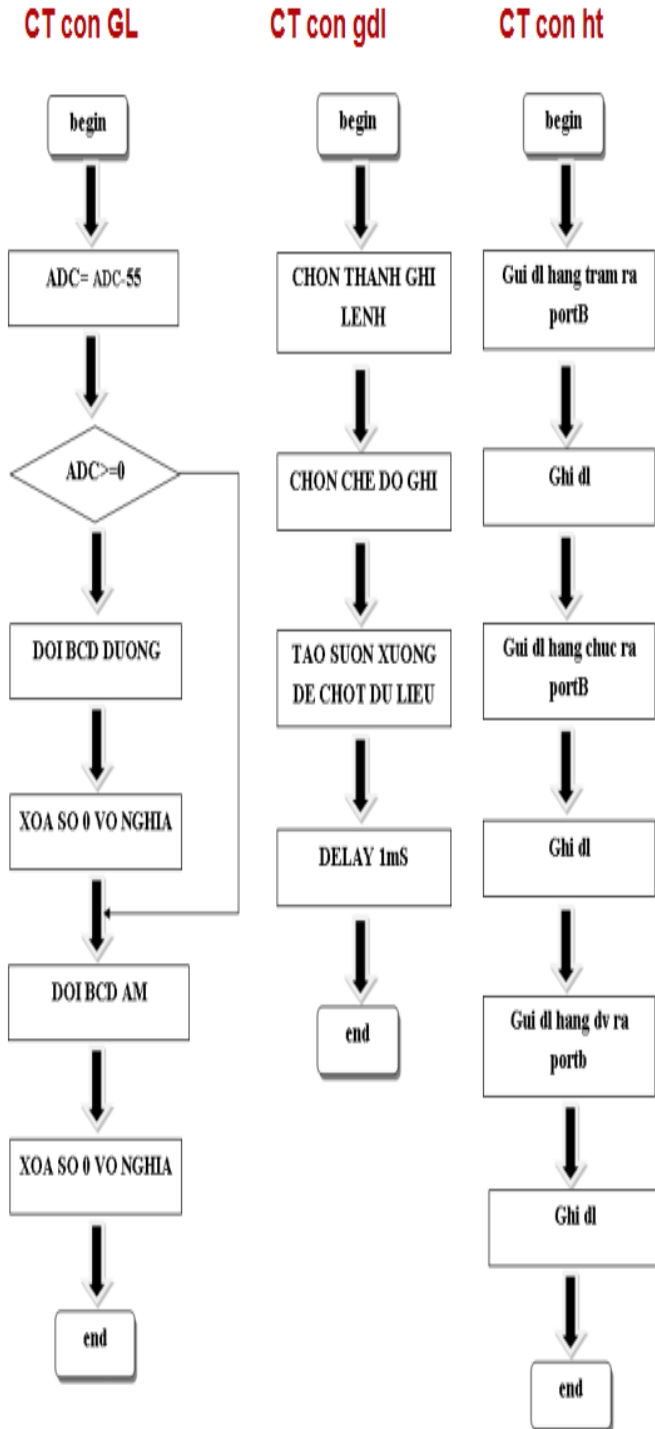


#### Hex-Bcd





## CHƯƠNG TRÌNH



```

#include <16f877a.h>
#include "def_877a.h"
#fuses nowdt,noprotect,nolvp,put,hs
#use delay(clock=20000000)
#define RS rD0
#define RW rD1
#define E rD2
#define LCD PORTB
signed int16 ADC0,tam;
int i=0;
int dv=0;
int chuc=0;
int tram=0;
const unsigned char mht[]={ '0','1','2','3','4','5','6','7','8','9','-','.' };
const unsigned char nd0[]="kenh 0: do C";
  
```

**void gl(void)**

```

{
    RS = 0;
    RW=0;
    E=1;
    E=0;
    delay_ms(1);
}
  
```

**void gdl(void)**

```

{
    Rw=0;
    Rs=1;
    E=1;
    E=0;
    DELAY_MS(1);
}
  
```

**void hex\_bcd(signed int16 adc )**

```

{
    ADC = ADC-55;
    if(ADC>=0)
    {
        dv=ADC%10;
        tam=ADC/10;
        chuc=tam%10;
        tram=tam/10;
    }
}
  
```

```

    if(tram==0)
    {
        tram=13;
        if(chuc==0) chuc=13;
    }
else
{
    ADC=abs(ADC);
    tram=10;
    chuc=ADC/10;
    dv=ADC%10;
    if(chuc==0) chuc=13;
}
}

void ht()
{
    LCD=mht[tram];
    gdl();
    LCD=mht[chuc];
    gdl();
    LCD=mht[dv];
    gdl();
}

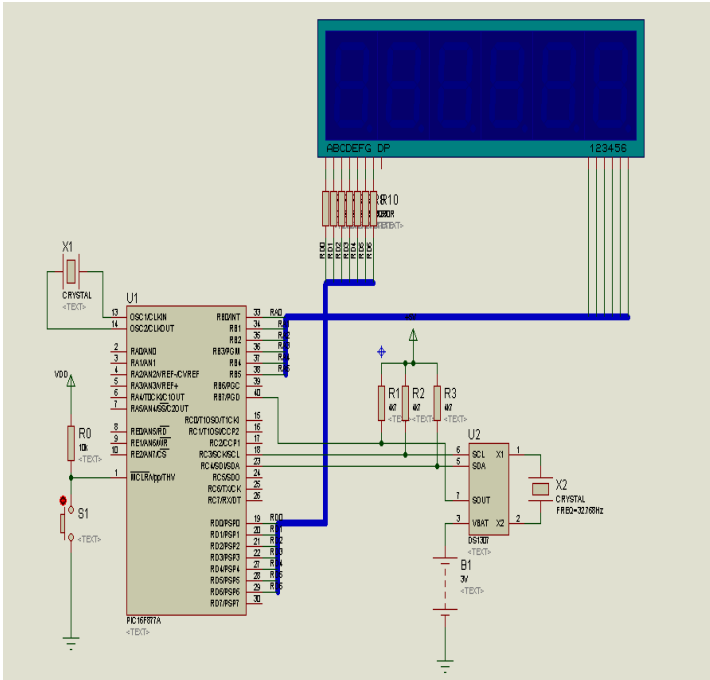
void kt_lcd()
{
    LCD = 0x38;
    gl();
    LCD =0x38;
    gl();
    LCD=0x0C;
    gl();
}

void main()
{
    trisb=0;
    trisd=0;
    setup_adc(ADC_CLOCK_INTERNAL);
    setup_adc_ports(an0_an1_vss_vref);

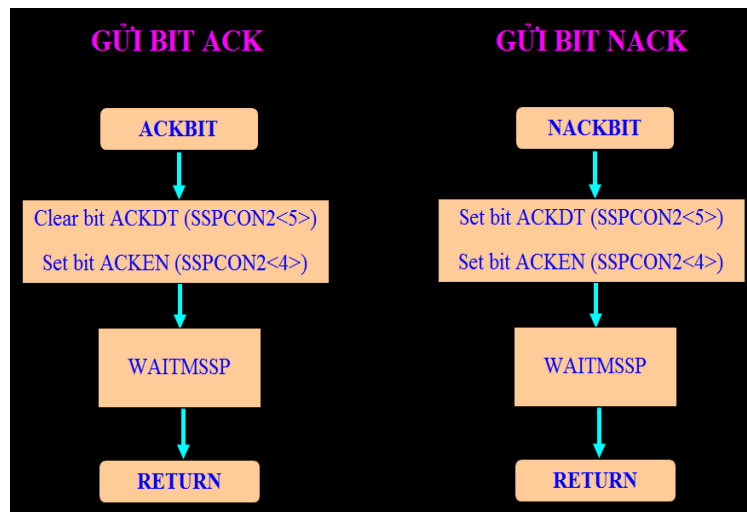
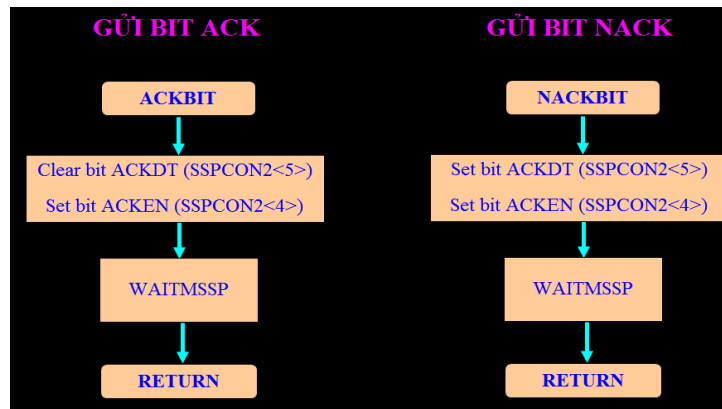
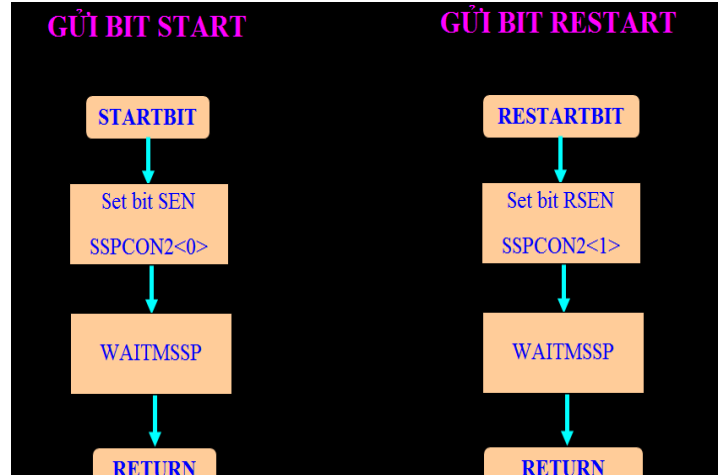
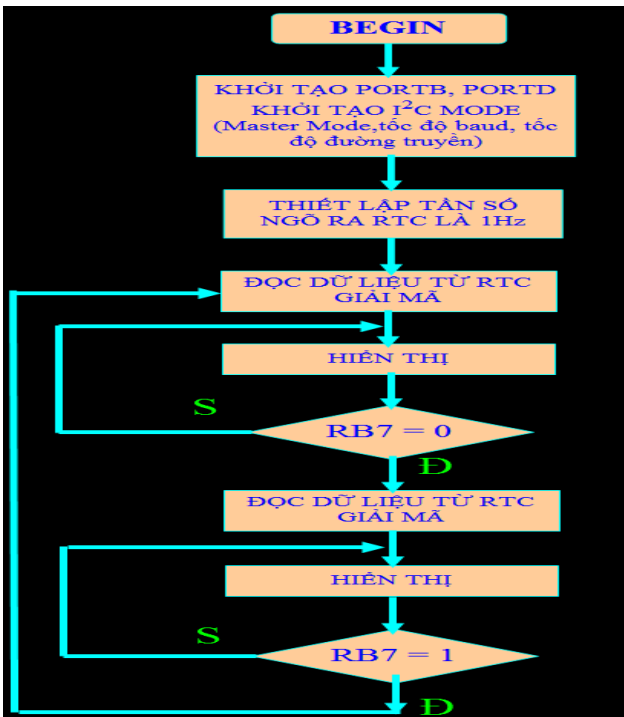
    kt_LCD();
    LCD=0x80;
    gl();
    while(i<=15)
    {
        LCD=nd0[i];
        gdl();
        i++;
    }
    i=0;
    while(1)
    {
        set_ADC_channel(0);
        delay_us(10);
        ADC0=read_ADC();
        hex_bcd(adc0);
        LCD=0x88;
        gl();
        ht();
    }
}

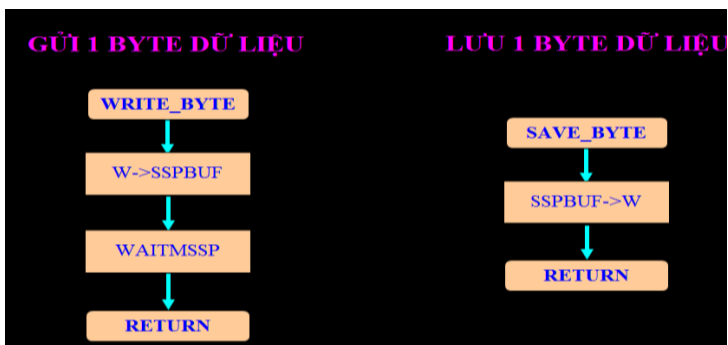
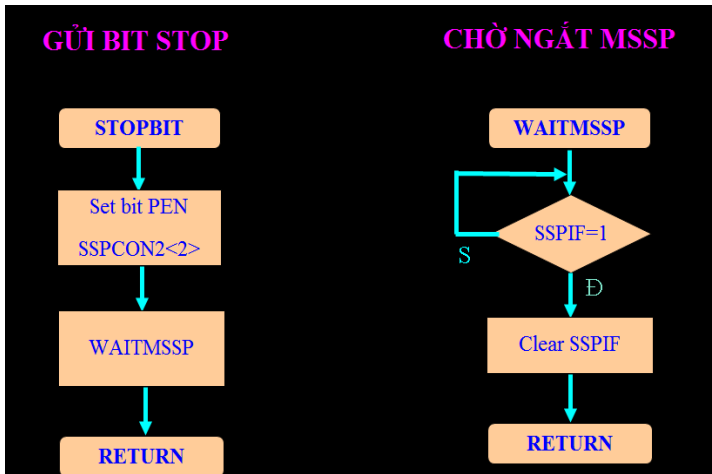
```

**BÀI 15: DÙNG PIC 16F877A GIAO TIẾP VỚI REALTIME DS13B07 VÀ 6 LED 7 ĐOẠN VIẾT CT ĐỒNG HỒ SỐ DÙNG NGÔN NGỮ ASSEMBLY**



**CHƯƠNG TRÌNH CHÍNH**





## CHƯƠNG TRÌNH

title "GIAO TIEP RTC DS1307 HIEN THI THOI GIAN THUC"

processor p16f877a

include <P16f877a.inc>

\_\_CONFIG \_CP\_OFF & \_PWRTE\_ON & \_WDT\_OFF & \_HS\_OSC & \_LVP\_OFF

=====

-----**KHAI BAO BIEN**-----

CBLOCK 0X20

RAM\_SEC

RAM\_MIN

RAM\_HOU

RAM\_SEC1

RAM\_MIN1

RAM\_HOU1

RAM\_SEC2

RAM\_MIN2

RAM\_HOU2

TEMP ; BIEN DUNG CHO CT DELAY

ENDC

=====

ORG 0X00

GOTO MAIN

**MAIN**

**;KHOI TAO PORTD**

BCF STATUS,RP1

BSF STATUS,RP0

CLRF TRISD ;THIET LAP PORTD LA NGO

*RA DE DUA DU LIEU DEN LED*

MOVLW 0X80 ;RB0->RB6 LA NGO

*RA DE QUET LED*

MOVWF TRISB ;CHAN RB7 LA NGO

*VAO CHO TIN HIEU DIEU KHIEN*

BCF STATUS,RP0

*;KHOI TAO I2C MASTER MODE*

BANKSEL SSPCON ;chon MSSP che do

*MASTER MODE*

MOVLW B'00101000'; Thiet lap MSSP cho chan

*PORTC o che do I2C*

MOVWF SSPCON

BANKSEL SSPSTAT ; Thiet lap che do

*Chuan cua toc do BAUD(100KHz)*

MOVLW B'10000000'

```

MOVWF SSPSTAT
BANKSEL SSPADD      ;
SSPADD=F(osc)/(tocadoBaud)
MOVLW 0X28          ; Tinh toan gia tri
cho thiet lap toc do 0X28=4MHz/100KHz
MOVWF SSPADD
;=====
;=====
;THIET LAP TAN SO NGO RA CUA DS1307 LA 1Hz
CALL STARTBIT      ; GUI BIT START

MOVLW 0XD0          ; GUI
DIA CHI CHO PHEP RTC NHAN
CALL WRITE_BYTE
MOVLW 0x07          ; GUI DIA CHI TG DIEU
KHIEEN NGO RA SQW/OUT CUA RTC
CALL WRITE_BYTE
MOVLW 0X10          ; DU
LIEU CHON TAN SO NGO RA SQW/OUT CUA RTC LA
1Hz
CALL WRITE_BYTE
CALL STOPBIT
;=====
;=====
START
CALL READ_RTC
CALL GIAIMA
CALL HIEN THI
BTFSS PORTB,7
GOTO $-2
CALL READ_RTC
CALL GIAIMA
CALL HIEN THI
BTFSC PORTB,7
GOTO $-2
GOTO START
;=====
;=====
READ_RTC
CALL STARTBIT
MOVLW 0XD0          ; GUI DIA
CHI CHO PHEP RTC NHAN
CALL WRITE_BYTE
MOVLW 0x00          ; gui dia chi o nho GIAY

```

```

CALL WRITE_BYTE
CALL RESTARTBIT ; GUI BIT RESTART
MOVLW 0xD1; GUI DIA CHI CHO PHEP RTC GUI
CALL WRITE_BYTE
;-----
; Qua trinh doc du lieu tu RTC
CALL READ_I2C      ; Doc du lieu SECOND
CALL ACKBIT
CALL SAVE_BYTE
MOVWF RAM_SEC      ; Luu du lieu GIAY
CALL READ_I2C      ; Doc du lieu MINUTE
CALL ACKBIT
CALL SAVE_BYTE
MOVWF RAM_MIN      ; Luu du lieu PHUT
CALL READ_I2C
CALL NACKBIT
CALL SAVE_BYTE
MOVWF RAM_HOU      ; Luu du lieu HOU
CALL STOPBIT
RETURN
;=====
WRITE_BYTE
BANKSEL SSPBUF
MOVWF SSPBUF
CALL WAITMSSP
RETURN
READ_I2C
BSF STATUS,RP0
BTFSC SSPSTAT,2    ; kiem tra bit R/W, xem
qua trinh Transmit da ket thuc chua
GOTO $-1
BANKSEL SSPCON2
BSF SSPCON2,RCEN   ; cho phep RECEIVE
Mode (I2C )
CALL WAITMSSP      ; Doi cho den khi I2C
thuc hien xong TUC LA NHAN DU LIEU XONG
RETURN
SAVE_BYTE
BANKSEL SSPBUF
MOVF SSPBUF,W
RETURN
;=====
STARTBIT
BANKSEL SSPCON2
BSF SSPCON2,SEN    ; gui bit START

```

```

CALL WAITMSSP
RETURN
RESTARTBIT
BANKSEL SSPCON2
BSF SSPCON2,RSEN ; gui bit RESTART
CALL WAITMSSP
RETURN
ACKBIT
BANKSEL SSPCON2
BCF SSPCON2,ACKDT ; Chon gui ACK
BSF SSPCON2,ACKEN ; Gui
CALL WAITMSSP
RETURN
NACKBIT
BANKSEL SSPCON2
BSF SSPCON2,ACKDT ; Chon gui NACK
BSF SSPCON2,ACKEN ; Gui di
CALL WAITMSSP
RETURN
STOPBIT
BANKSEL SSPCON2
BSF SSPCON2,PEN ; gui bit STOP
CALL WAITMSSP
RETURN
WAITMSSP
BANKSEL PIR1
BTFSS PIR1,SSPIF ; Kiem tra trang thai co
GOTO $-1 ; Chua hoan thanh
BCF PIR1,SSPIF ; Da hoan thanh cong
viec, luc nay co the chuyen sang hoat dong moi
RETURN

```

```

;=====
=====

```

GIAIMA

;HEX TO BCD

```

MOVLW 0X0F
ANDWF RAM_SEC,0 ;LAY 4BIT
THAP
MOVWF RAM_SEC1
SWAPF RAM_SEC,0
ANDLW 0X0F
MOVWF RAM_SEC2
MOVLW 0X0F
ANDWF RAM_MIN,0 ;LAY 4BIT THAP

```

```

MOVWF RAM_MIN1
SWAPF RAM_MIN,0
ANDLW 0X0F
MOVWF RAM_MIN2

MOVLW 0X0F
ANDWF RAM_HOU,0 ;LAY 4BIT THAP
MOVWF RAM_HOU1
SWAPF RAM_HOU,0
ANDLW 0X0F
MOVWF RAM_HOU2;LAY MA 7 DOAN
MOVF RAM_SEC1,0
CALL TABLE
MOVWF RAM_SEC1
MOVF RAM_SEC2,0
CALL TABLE
MOVWF RAM_SEC2
MOVF RAM_MIN1,0
CALL TABLE
MOVWF RAM_MIN1
MOVF RAM_MIN2,0
CALL TABLE
MOVWF RAM_MIN2
MOVF RAM_HOU1,0
CALL TABLE
MOVWF RAM_HOU1
MOVF RAM_HOU2,0
CALL TABLE
MOVWF RAM_HOU2
RETURN

```

```

;=====
HIENTHI

```

;-----**HIEN THI GIAY 1**

```

MOVF RAM_SEC1,0
MOVWF PORTD
BSF PORTB,5
CALL DELAY
BCF PORTB,5
CALL DELAY

```

;-----**HIEN THI GIAY 2**

```

MOVF RAM_SEC2,0
MOVWF PORTD
BSF PORTB,4
CALL DELAY

```

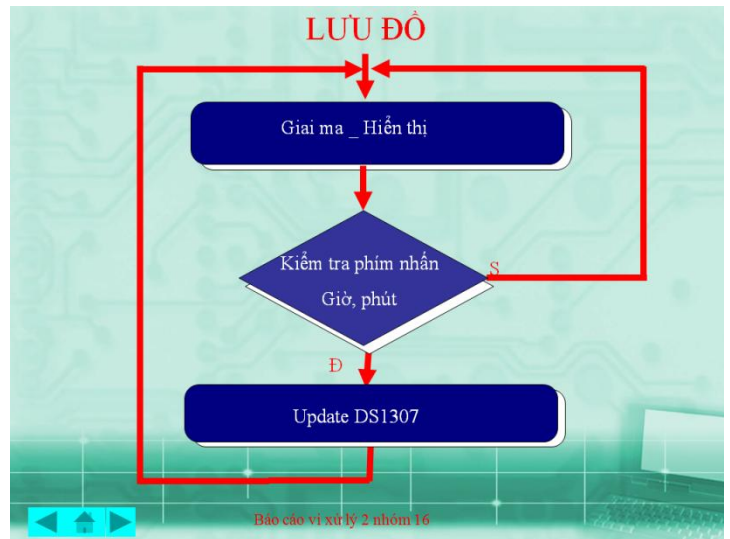
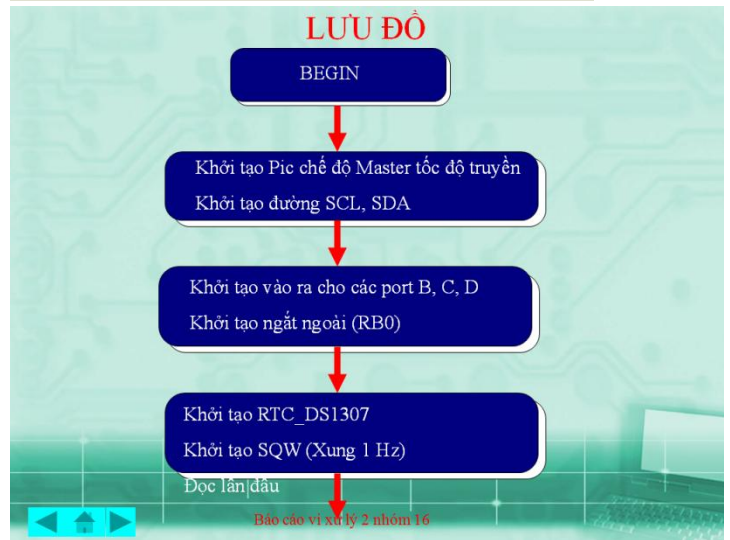
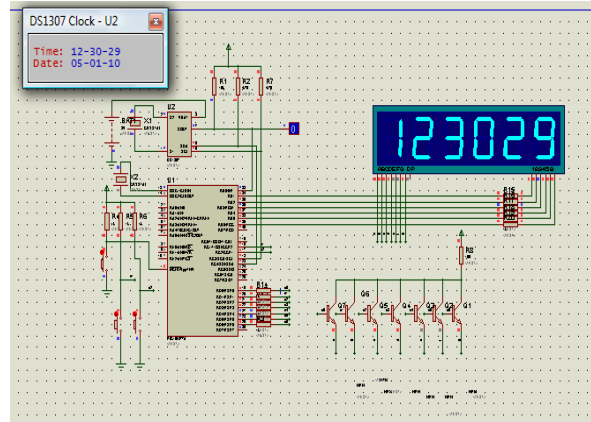
```

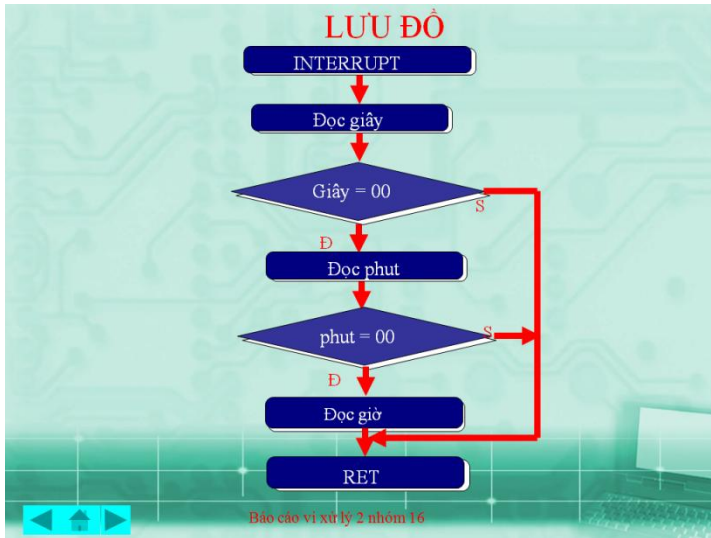
BCF      PORTB,4
CALL    DELAY
;-----HIEN THI PHUT 1
MOVWF   RAM_MIN1,0
MOVWF   PORTD
BSF     PORTB,3
CALL    DELAY
BCF     PORTB,3
CALL    DELAY
;-----HIEN THI PHUT 2
MOVWF   RAM_MIN2,0
MOVWF   PORTD
BSF     PORTB,2
CALL    DELAY
BCF     PORTB,2
CALL    DELAY
;-----HIEN THI GIO 1
MOVWF   RAM_HOU1,0
MOVWF   PORTD
BSF     PORTB,1
CALL    DELAY
BCF     PORTB,1
CALL    DELAY
;-----HIEN THI GIO 2
MOVWF   RAM_HOU2,0
MOVWF   PORTD
BSF     PORTB,0
CALL    DELAY
BCF     PORTB,0
CALL    DELAY
RETURN

;=====
DELAY
MOVLW   D'50'
MOVWF   TEMP
DECFSZ  TEMP
GOTO   $-1
RETLW   0X00

;=====
TABLE
ADDWF   PCL,1
DT
0x40,0x79,0x24,0x30,0x19,0x12,0x02,0x78,0x00,0x10
END
    
```

**BÀI 16: Viết chương trình đồng hồ số bằng ngôn ngữ C, dùng PIC16F877A giao tiếp với RTC\_DS1307. Hiển thị trên 6 led 7 đoạn**

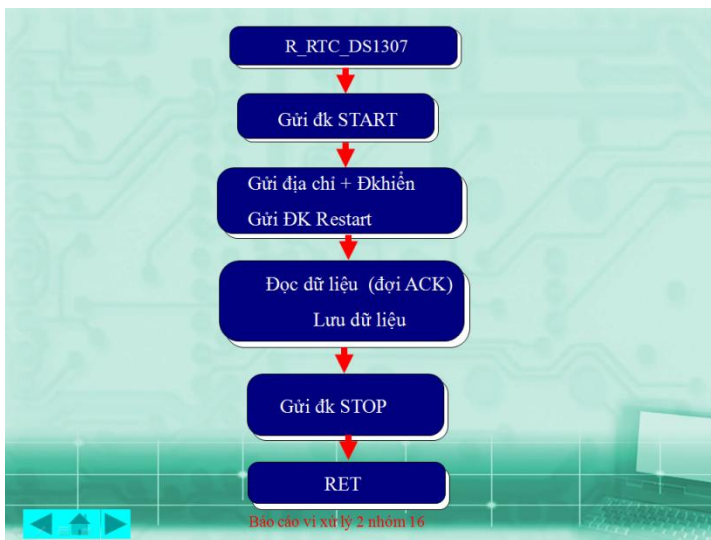
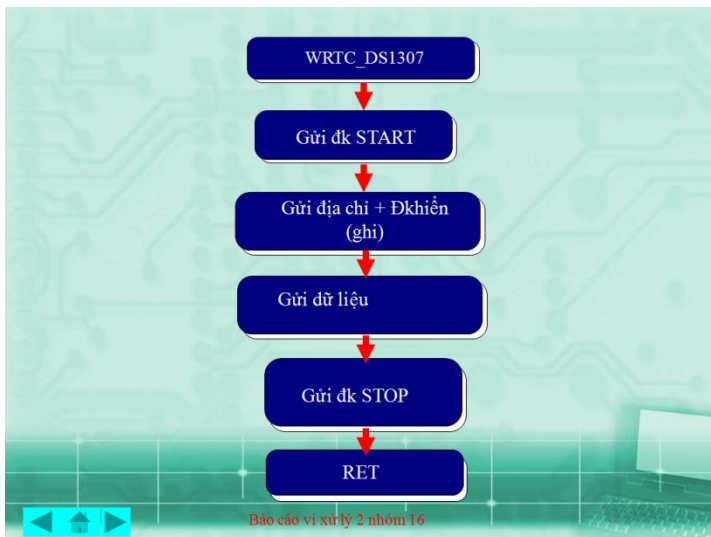




### Chương trình

```

#include "16f877a.h"
#include "def_877a.h"
#fuses
NOPROTECT,NOBROWNOUT,NOLVP,PUT,NOWDT
#use delay(clock=16000000)
#use i2c(Master,Fast,sda=PIN_C4,scl=PIN_C3)
#use fast_io(b)
#use fast_io(d)
#use fast_io(c)
#byte portb=0x06
#byte portd=0x08
#byte portc=0x07
//cac dinh nghia
#bit gio = portc.1
#bit phut = portc.2
#bit led0 = portb.1
#bit led1 = portb.2
#bit led2 = portb.3
#bit led3 = portb.4
#bit led4 = portb.5
#bit led5 = portb.6
int8 sec,min,hour,data;
int8 tam=0;
int8 secdv,secc,mindv,minc,hourdv,hourc;
const int
code_led[]={0x3f,0x06,0x5b,0x4f,0x66,0x6d,0x7d,0x07,0x7f,0x6f};
#int_EXT
void EXT_isr(void)
{
    i2c_start();
    i2c_write(0xD0); // WR to RTC
    i2c_write(0x00); // REG 0
    i2c_start();
    i2c_write(0xD1); // RD from RTC
    sec = i2c_read(0);
    i2c_stop();
    if ( sec == 0x00)
    {
        i2c_start();
        i2c_write(0xD0); // WR to RTC
        i2c_write(0x01); // REG 0
    }
}
  
```





```

    i2c_start();
    i2c_write(0xD1);      // RD from RTC
    min = i2c_read(0);
    i2c_stop();
    if (min == 0x00)
    {
        i2c_start();
        i2c_write(0xD0);  // WR to RTC
        i2c_write(0x02);  // REG 0
        i2c_start();
        i2c_write(0xD1);  // RD from RTC
        hour = i2c_read(0);
        i2c_stop();
    }
}

void write_RTC()
{
    i2c_start();
    i2c_write(0xD0);      // WR to RTC
    i2c_write(0x00);      // REG 0
    i2c_write(0x26);      // Start oscillator with current
    "seconds value
    i2c_write(0x30);      // REG 1
    i2c_write(0x12);      // REG 2
    i2c_stop();
    i2c_start();
    i2c_write(0xD0);      // WR to RTC
    i2c_write(0x07);      // Control Register
    i2c_write(0x10);      // squarewave output pin 1Hz
    i2c_stop();
    i2c_start();
    i2c_write(0xD0);      // WR to RTC
    i2c_write(0x00);      // REG 0
    i2c_stop();
    i2c_start();
    i2c_write(0xD1);      // RD from RTC
    sec = i2c_read();
    min = i2c_read();
    hour = i2c_read();
    i2c_stop();
}

```

```

void hienthi()
{
    secdv = sec & 0x0f;
    secc = (sec & 0x70)>>4;
    portd=code_led[secdv];
    led5=0;
    delay_ms(2);
    led5=1;
    portd=code_led[secc];
    led4=0;
    delay_ms(2);
    led4=1;

    mindv = min & 0x0F;
    minc =(min & 0x70)>>4;
    portd=code_led[mindv];
    led3=0;
    delay_ms(2);
    led3=1;
    portd=code_led[minc];
    led2=0;
    delay_ms(2);
    led2=1;

    hourdv = hour & 0x0F;
    hourc =(hour & 0x30)>>4;
    portd=code_led[hourdv];
    led1=0;
    delay_ms(2);
    led1=1;
    portd=code_led[hourc];
    led0=0;
    delay_ms(2);
    led0=1;
}

void update_ds1307(unsigned int gtri)
{
    if(gtri == 01)
    {
        i2c_start();
        i2c_write(0xd0);
        i2c_write(0x01);      // ghi du lieu bat dau tu vi tri 01
        data=mindv+(minc<<4);
        i2c_stop();
    }
}

```

```

    }
    if(gtri == 02)
    {
        i2c_start();
        i2c_write(0xd0);
        i2c_write(0x02);
        i2c_write(data);
        data=hourdv+(hourc<<4);
        i2c_write(data);
        i2c_stop();
    }
}

void set_incgio(void)
{
    hourdv++;           // tang gio
    if(hourdv == 10)   // khi hang don vi gio = 10
    {
        hourc++;
        hourdv = 0;
    }
    if((hourc == 2)&(hourdv == 4)) // khi gio = 24
    {
        hourc = 0;
        hourdv = 0;
    }
    hour = (hourc<<4)| hourdv;
}

void set_incphut(void)
{
    mindv++;           // tang phut
    if(mindv == 10)   // khi phut don vi = 10
    {
        mindv = 0;
        minc++;
        if(minc == 6) // khi phut chuc = 6
        {
            minc = 0;
            mindv = 0;
        }
    }
    min = (minc<<4)|mindv;
}

```

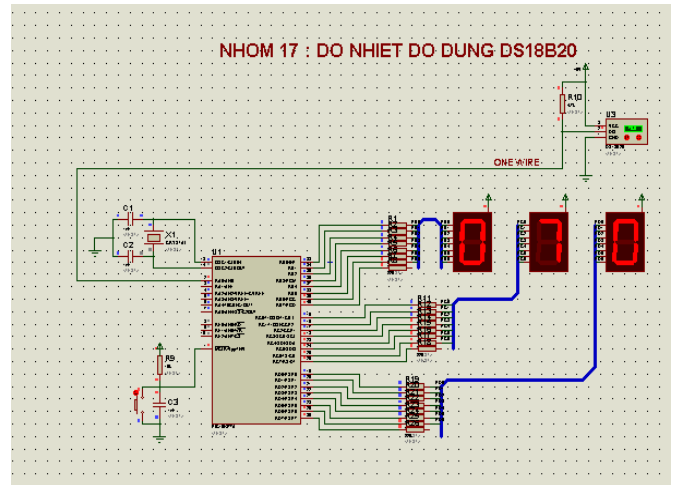
```

void main()
{
    enable_interrupts(INT_EXT); // enable ext interrupt
    ext_int_edge(0,H_TO_L);    // set external interrupt to
    falling edge
    enable_interrupts(GLOBAL);
    set_tris_d(0x00);
    set_tris_c(0x1f);
    set_tris_b(0x01);
    write_RTC();
    while (TRUE)
    {
        hienthi();
        if (phut==0)
        {
            tam++;
        }
        if (tam ==15)
        {
            set_incphut();
            update_ds1307(01);
            tam=0;
        }

        if (gio==0)
        {
            tam++;
        }
    }
    if (tam ==15)
    {
        set_incgio();
        update_ds1307(02);
        tam=0;
    }
}

```

**Bài 17: giao tiếp DS18B20 và 3 led 7 đoạn .viết chương trình đo nhiệt độ bằng ngôn ngữ ASSEMBLY.**



**Chương trình:**

```

PROCESSOR P16F877A
INCLUDE <P16F877A.INC>
__CONFIG __CP_OFF & __WDT_OFF &
_HS_OSC & __PWRTE_ON
#include <P16F877A.INC>
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
        CBLOCK 20H
        PDBYTE
; Kiem tra qua trinh Reset
;-----Lay du lieu tu DS-----
        BYTE0,BYTE1 ; Luu ket qua
        RBYTE0,RBYTE1 ; Xu ly ket qua
        XOAY ; XOAY 4 lan de lay ket qua
;-----Dùng cho Delay-----
        DELAY_TEMP0
        DELAY_TEMP1
        DELAY_TEMP2
;-----Ghi du lieu vao DS-----
        BYTE_8 ; Bien trung gian de ghi lenh vao DS
;-----Hien thi-----
        TRAM,CHUC,DONVI
        TAM
        BDATA
        DAU
        ENDC
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
        ORG 0X000
        GOTO START
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
START
        ORG 0X0005

        BCF STATUS,RP1
        BSF STATUS,RP0 ; Select Bank1

        CLRF TRISA ; PortA as output
        CLRF TRISB ; PortB as output
        CLRF TRISC ; PortC as output
        CLRF TRISD ; PortD as output
        MOVLW B'00000110' ; Set portA as
digital port
        MOVWF ADCON1 ;

```

```

        BCF STATUS,RP0 ;
Select Bank0

        CLRF PORTB
        CLRF PORTC
        CLRF PORTD
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
MAIN
;-----Initate 18B20-----
        CALL RESET_18B20 ; Khoi tao
DS18B20 (Reset and wait for presence pulse)
        BTFSS PDBYTE,0 ; PDBYTE=1 ->
Reset thành công
        GOTO MAIN ; PDBYTE=0 ->
Quay lai tu dau
;-----SKIP ROM-----

        MOVLW 0CCH ; Truy cap thang den
DS18B20
        MOVWF BYTE_8; BYTE_8 làm trung gian
de dich byte 0CCH vào RA0
        CALL WRITE_18B20 ;
;-----CONVERT-----
        MOVLW 44H ; Do và chuyen doi giá trị
nhiệt độ thành số
        MOVWF BYTE_8; BYTE_8 làm trung gian
de dich byte 44H vào RA0
        CALL WRITE_18B20;
        CALL DELAY_762MS; Cho chuyen doi xong
;-----Initate 18B20-----
        CALL RESET_18B20 ; Khoi tao
DS18B20 (Reset and wait for presence pulse)
        BTFSS PDBYTE,0 ; PDBYTE=1 ->
Reset thành công
        GOTO MAIN ; PDBYTE=0 -> Quay lai tu dau
;-----SKIP ROM-----
        MOVLW 0CCH ; Truy cap thang den DS18B20
        MOVWF BYTE_8 ; BYTE_8 làm trung gian de
dich byte 0CCH vào RA0
        CALL WRITE_18B20 ;
;-----READ SCRATCHPAD-----

```

```

    MOVLW 0BEH ; Doc noi dung bo nho nhap
    MOVWF   BYTE_8 ; BYTE_8 lam trung gian
de dich byte 0BEH vào RA0
    CALL  WRITE_18B20      ;
;-----Lay du lieu-----
    CALL  READ_18B20      ; Read 2 byte BDATA (Luu
vao Byte0 & Byte1)
;-----Initate 18B20-----
    CALL  RESET_18B20      ; Reset Ds18B20 ve
trang thai nghi (bo 7 bit còn lai)
    BTFSS PDBYTE,0; PDBYTE=1 -> Reset thành
cong
    GOTO  MAIN ; PDBYTE=0 -> Quay lai tu dau
;-----Xu ly ket qua-----
    MOVF  BYTE0,W      ; RBYTTE0 = BYTE0 ,
BYTE0 BYTE1 co dinh
    MOVWF RBYTE0 ; RBYTTE0 = BYTE0
    MOVF  BYTE1,W      ; RBYTTE1 = BYTE1
    MOVWF RBYTE1; RBYTTE1 = BYTE1
    CALL  LOC_KETQUA ; Loc lay ket qua, luu vào
bien BDATA
;-----Hien thi-----
    CALL  HEXTOBCD
    CALL  HIEN THI
    GOTO  MAIN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
RESET_18B20
    CLRF  PDBYTE      ; Xóa PDBYTE (bit
kiem tra Presence Pulse)
    CALL  OW_LOW
    CALL  DELAY_485    ; 480us MINIMUM
    CALL  OW_HIGH_Z    ; Release the BUS
    CALL  DELAY_62
    BTFSS PORTA,0; RA0=0 -> Có xung Presence
    INCF  PDBYTE
    CALL  DELAY_242
    RETURN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
OW_HIGH_Z
    BSF   STATUS,RP0 ; Chon Bank1 cua bo nho du
lieu
    BSF   TRISA,0 ; RA0 as OUTPUT -> DQ o trang
thai HIGH_Z
    BCF   STATUS,RP0 ; Chon BANK0

```

```

    RETURN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
OW_LOW
    BSF   STATUS,RP0 ; Chon Bank1 cua bo nho du
lieu
    BCF   TRISA,0 ; RA0 as OUTPUT
    BCF   STATUS,RP0 ; Chon BANK0
    BCF   PORTA,0 ; RA0=0
    RETURN ;
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
WRITE_18B20 ; 3 giai doan
;-----Dich 8 bit BYTE_8 vào RA0 de thuc hien lenh-----
    MOVLW 08H ; Dich 8 bit vào RA0
    MOVWF TAM ;
    BCF   STATUS,C ; Co C lam cau noi de dich
LB_WRITE
;-----Giai doan 1: Khoi tao-----
    CALL  OW_LOW ; Kéo QD xuống mức thấp
    CALL  DELAY_17 ; 15us MINIMUM
;-----Giai doan 2: Ghi du lieu-----
    RRF  BYTE_8,1; Dich 1bit LSB của BYTE_8 vào C
    BTFSS STATUS,C; C=0 thì WRITE_0, C=1 thì
WRITE_1
    GOTO  $+2
    BSF   PORTA,0; Neu C=1 -> RA0=1
    CALL  DELAY_47 ; Delay 47 cho ghi xong
;-----Giai doan 3: Release the Bus-----
    BANKSEL TRISA
    BSF   TRISA,0 ; RA0 as INPUT
    BANKSEL PORTA ; 1us
    NOP
    ; Cho thêm 1us
;-----Dich bit tiếp theo-----
    DECFSZ TAM,1
    GOTO  LB_WRITE
    RETURN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
READ_18B20 ; 3 giai doan
    MOVLW D'16' ; Doc 16 bit tu RA0
    MOVWF TAM
LB_READ
;-----Giai doan 1: Khoi tao-----

```

```

CALL OW_LOW
NOP
;-----Giai doan 2: Release the Bus-----
CALL OW_HIGH_Z ; Tu luc RA0 o
trang thai HIGH_Z den khi ket thuc ctr con la 3us
CALL DELAY_11; Cho them 11us de lay
du lieu trong khoang 14us cua TimeSlot
;-----Giai doan 2: Lay du lieu-----
BTFSS PORTA,0; RA0=1 thi C=1
GOTO $+3; RA0=0 thi C giu
nguyên (=0)
BSF STATUS,C
GOTO $+2
BCF STATUS,C ; C=0 khi DQ=0
RRF BYTE1,1 ; Dich C vào BYTE1 và
BYTE0 (16 lan)
RRF BYTE0,1 ; Dich C vào BYTE1 và
BYTE0 (16 lan)
CALL DELAY_47 ; Cho het TimeSlot
;-----Đoc bit tiếp theo-----
DECFSZ TAM,1
GOTO LB_READ
RETURN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
LOC_KETQUA
BTFSS BYTE1,7 ; BYTE1.7 = 1 thì là số âm
GOTO EXIT ; BYTE1.7 = 0 thì là số dương
COMF RBYTE1,F ; Bù 2 RBYTE1
COMF RBYTE0,F ; Bù 2 RBYTE0
MOVLW 0X01 ; Cong thêm 1
ADDWF RBYTE0,F ;
;-----
BTFSS STATUS,C ; Neu C=1 thì phải công 1
cho RBYTE1 do phép toán trước bị tràn
GOTO EXIT; (Chỉ dành cho trường hợp hiển thị số
thập phân)
MOVLW 0X01
ADDWF RBYTE1,F
;-----
EXIT
MOVLW D'4' ; Ket qua nguyên lay trong
BYTE0<4:7> và BYTE1<0:3>
MOVWF XOAY ; Do đó phải xoay 4 lan
LOOP

```

```

RRF RBYTE1,1
RRF RBYTE0,1
DECFSZ XOAY,1; Xoay du 4 lan? (Bo 4 bit thap)
GOTO LOOP
MOVF RBYTE0,0 ; Ket qua nam trong BYTE0
MOVWF BDATA; Đưa ket qua vào BDATA
BCF BDATA,7 ; Chi lay 7 bit du lieu
RETURN
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
HEXTOBCD
CLRF TRAM ; TRAM=0
CLRF CHUC ; CHUC=0
CLRF DONVI ; DON VI=0
XET1
MOVLW .100 ; W=100
SUBWF BDATA,0; XET BDATA-W
BTFSS STATUS,C ; BANG CACH XET CO C=1 -
> BDATA>100
GOTO XET2 ; BDATA<100 THI DI DEN XET2
MOVLW .100; CON NEUBDATA >= 100 THI
SUBWF BDATA,1; BDATA=DATA-W (VOI
W=100)
INCF TRAM,1; TRAM=TRAM+1 (DATA SO
LAN TAM LON HON 100)
GOTO XET1 ; TIEP
TUC QUAY LAI XET1 NHU TREN
XET2
MOVLW .10
; W=10
SUBWF BDATA,W
; XETBDATA-W
BTFSS STATUS,C ; BANG
CACH XET CO C=1 -> BDATA>10
GOTO THOATXET ; NEU
KHONG TRU HET TUC LA TAM<10 THI DI DEN
THOATXET
MOVLW .10
; CON NEUBDATA >= 100 THI
SUBWF BDATA,1
; BDATA=DATA-W (VOI W=10)
INCF CHUC,1 ;
CHUC=CHUC+1 (DATA SO LAN TAM LON HON 10)

```

GOTO XET2 ; TIEP TUC QUAY LAI XET2 NHU  
TREN

**THOATXET**

MOVF BDATA,0 ; SAU CUNG  
THIBDATA<10 THI TA CHUA VAO DONVI  
MOVWF DONVI ; DONVI=W  
RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**HIENTHI**

BTFSS BYTE1,7; BYTE1.7 =1 -> So âm  
GOTO DUONG; BYTE1.7 =0 -> So duong  
MOVLW 0XBF; Mã dau tru (common anode)  
MOVWF PORTB ; Đưa vào PORTB  
GOTO AM ; Không hiện thi TRAM

**DUONG**

MOVF TRAM,W ; W=TRAM  
CALL TABLE ; Giai mã TRAM sang LED 7 doan  
MOVWF PORTB ; Xuat ra PORTB

**AM**

MOVF CHUC,W ; W=CHUC  
CALL TABLE ; Giai mã CHUC sang LED 7 doan  
MOVWF PORTC ; Xuat ra PORTC  
  
MOVF DONVI,W ; W=DONVI  
CALL TABLE; Giai mã DONVI sang LED 7 doan  
MOVWF PORTD ; Xuat ra PORTD  
RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_242**

MOVLW D'79'  
MOVWF DELAY\_TEMP0  
DECFSZ DELAY\_TEMP0,1  
GOTO \$-1  
RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_62**

MOVLW D'19'  
MOVWF DELAY\_TEMP0  
DECFSZ DELAY\_TEMP0,1  
GOTO \$-1  
RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_47**

MOVLW D'14'

MOVWF DELAY\_TEMP0  
DECFSZ DELAY\_TEMP0,1

GOTO \$-1

RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_17**

MOVLW D'4'  
MOVWF DELAY\_TEMP0

DECFSZ DELAY\_TEMP0,1

GOTO \$-1

RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_11**

MOVLW D'2'  
MOVWF DELAY\_TEMP0

DECFSZ DELAY\_TEMP0,1

GOTO \$-1

RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_485**

MOVLW D'160'  
MOVWF DELAY\_TEMP0

DECFSZ DELAY\_TEMP0,1

GOTO \$-1

RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY\_762MS**

;(762.242MS)

MOVLW D'50'  
MOVWF DELAY\_TEMP2

MOVWF DELAY\_TEMP1

MOVWF DELAY\_TEMP0

DECFSZ DELAY\_TEMP0,1

GOTO \$-1

DECFSZ DELAY\_TEMP1,1

GOTO \$-4

DECFSZ DELAY\_TEMP2,1

GOTO \$-7

RETURN

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

**DELAY300MS**

MOVLW D'40'

MOVWF DELAY\_TEMP2

MOVWF DELAY\_TEMP1

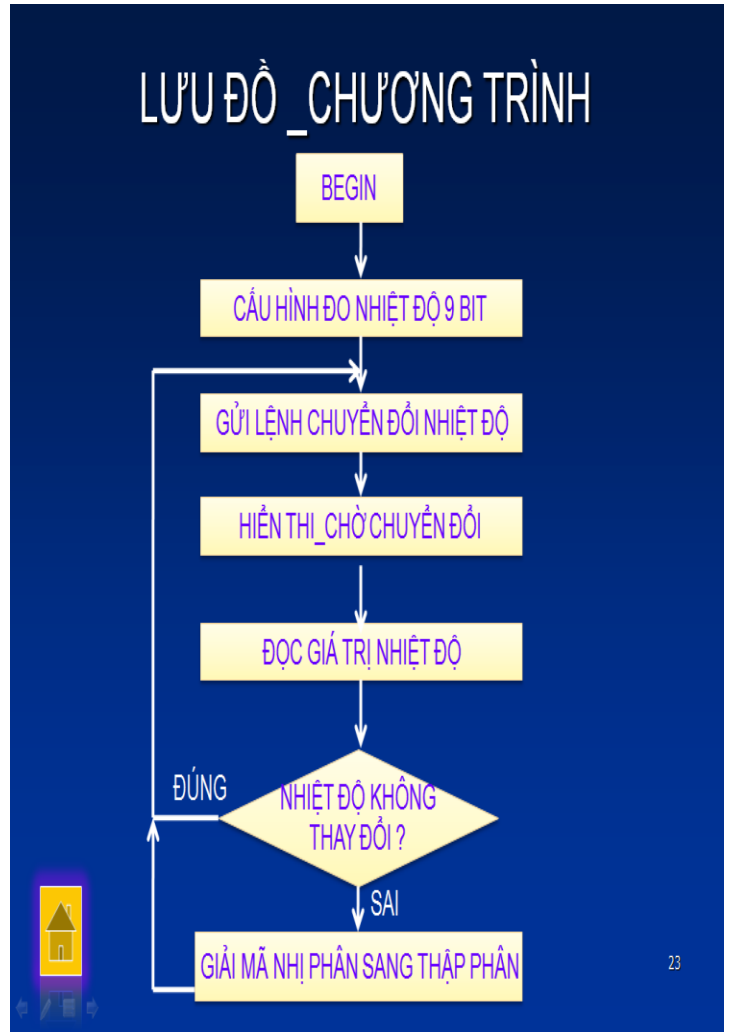
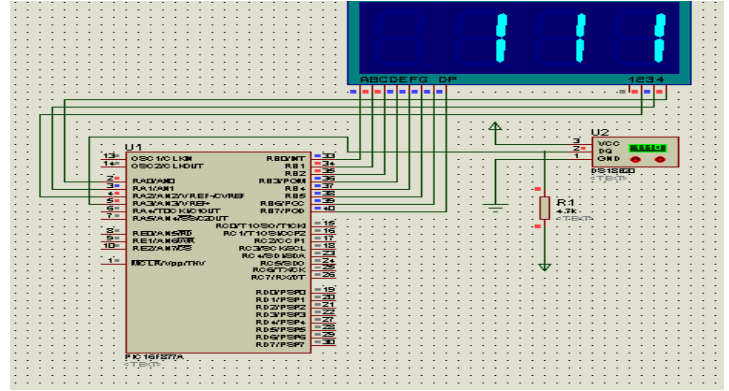
```

MOVWF    DELAY_TEMP0
DECFSZ   DELAY_TEMP0,1
GOTO    $-1
DECFSZ   DELAY_TEMP1,1
GOTO    $-4
DECFSZ   DELAY_TEMP2,1
GOTO    $-7
RETURN
    
```

```

;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
TABLE
    ADDWF    PCL,1
    DT
    0C0H,0F9H,0A4H,0B0H,99H,92H,82H,0F8H,80H,
90H ;common anode
;XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
END
    
```

**Bài 18: Dùng PIC16F877A giao tiếp với cảm biến nhiệt độ DS18B20 đo nhiệt độ hiển thị ra Led 7 đoạn , dùng C**





**Chương trình**

```
#include <16F877.h>
#fuses HS,NOPROTECT,NOLVP
#use delay(clock=2000000)
#define TOUCH_PIN pin_a3
#include <touch.c>
void hienthi(int8 a,int8 b,int8 c);
int8 const seg7[11] =
{0x3f,0x06,0x5b,0x4f,0x66,0x6d,0x7d,0x07,0x7f,0x6f,0x40
};
```

**//chương trình chính**

```
=====
void main() {
    int8 tam1=0,tam2,ss,i;
    int8 led1,led2,led3;
    int16 nd;
//cài đặt chuyển đổi nhiệt độ 9 bit
    =====
    touch_present();
    touch_write_byte(0xcc); // Phát lệnh skip ROM
    touch_write_byte(0x4e); // Phát lệnh ghi 3byte
    du lieu to Scratchpad
    touch_write_byte(0x0); // ghi 2 byte rong
    touch_write_byte(0x0); //
    touch_write_byte(0x1f); //Cau hình cho thanh
    ghi nhiệt độ(do phân giai 9 bit)

    touch_present();
    touch_write_byte(0xCC); // skip ROM
    touch_write_byte(0x48); // Sao chép Scratchpad
```

vào Eeprom

**//vòng lặp chương trình chính=====**

```
while (1) {
    do {
        if(touch_present())
        {
            touch_write_byte(0xCC);
            touch_write_byte (0x44); //xuất lệnh
            chuyển đổi nhiệt độ
            for(i=0;i<7;++i) {
                hienthi(led1,led2,led3);
            }
        }
    }
}
```

```
touch_present();
touch_write_byte(0xCC);
touch_write_byte (0xBE);
//lệnh đọc bỏ nhớ nhập
tam1 = touch_read_byte();
//đọc 2 byte nhiệt độ
tam2 = touch_read_byte();
}
}
while (tam1==ss); //so sánh giá trị
nhiệt độ đọc được với giá trị trước đó
ss=tam1;
```

**//==chuyển đổi nhiệt độ sang số thập phân==**

```
nd=make16(tam2,tam1);
nd=nd>>4; //dịch phải 4 bit
nd=nd&0x0ff; //lay 8 bit thập
if(bit_test(nd,7)) //nếu giá trị nhiệt độ là âm
{
    led3=10; //led3 hiển thị dấu "-"
    nd=~(--nd); //lấy bù 2 giá trị nhiệt độ
    nd=nd&0x0ff; //xóa byte cao
}
else //nếu giá trị nhiệt độ dương
{
    led3=nd/100; //led3 hiển thị số hàng trăm
    nd=nd%100;
}
led2=nd/10; //led2 hiển thị số hàng chục
led1=nd%10; //led1 hiển thị số hàng đơn vị
}
}
```

**//chương trình hiển thị quét led===**

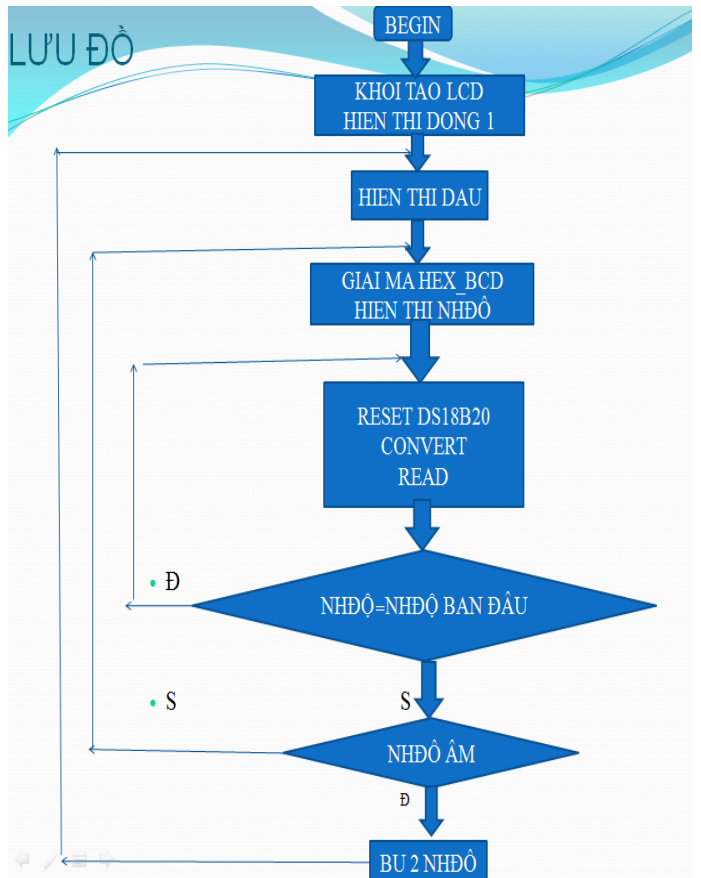
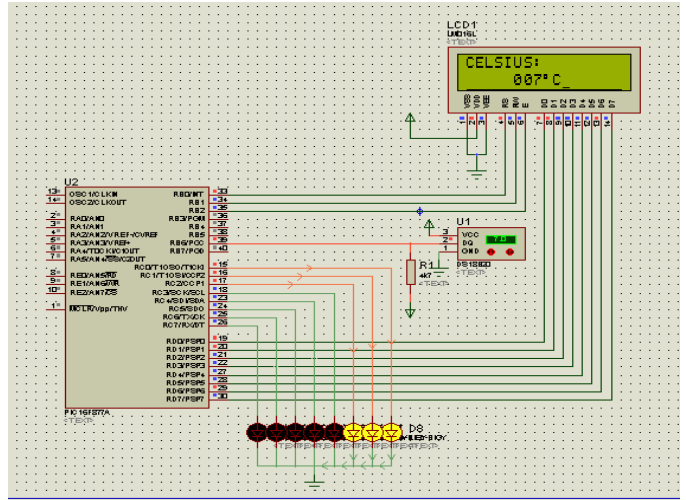
**void hienthi(int8 a,int8 b,int8 c)**

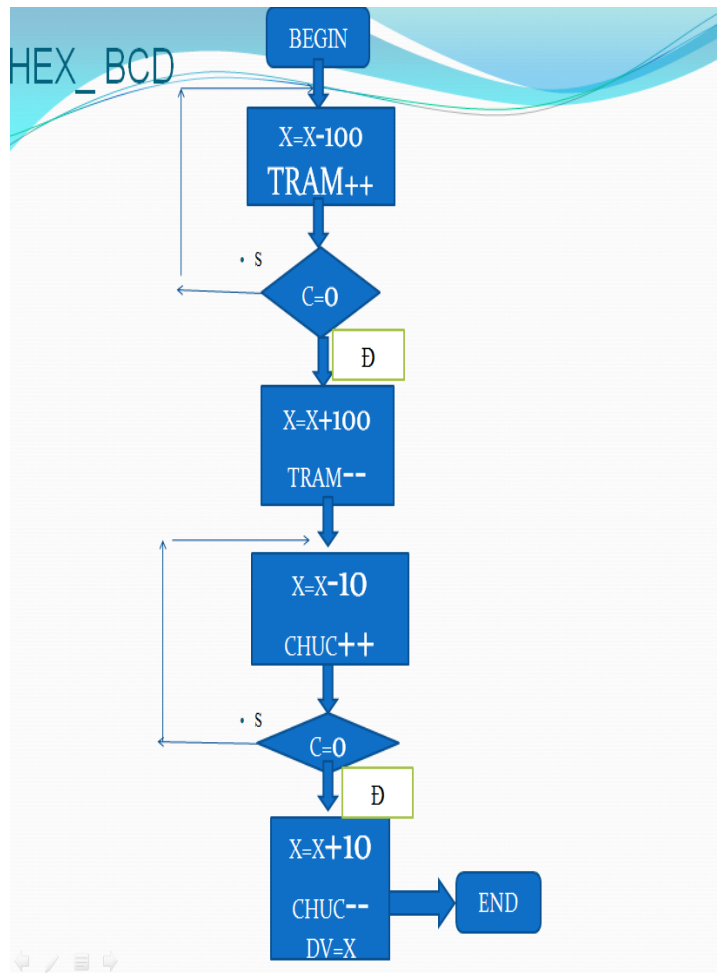
```
{
    output_b(seg7[a]);
    output_low(pin_a0);
    delay_ms(6);
    output_high(pin_a0);
    output_b(seg7[b]);
    output_low(pin_a1);
    delay_ms(6);
    output_high(pin_a1);
}
```

```

output_b(seg7[c]);
output_low(pin_a2);
delay_ms(6);
output_high(pin_a2);
}
    
```

**Bài 19: Sử dụng PIC 16F877A đọc nhiệt độ từ cảm biến DS 18B20, hiển thị LCD HD 44780. Ngôn ngữ ASSEMBLY**





**Chương trình:**

```

processor    p16f877a
include     <p16f877a.inc>
__CONFIG    _CP_OFF & _PWRTE_OFF &
            _WDT_OFF & _HS_OSC & _LVP_OFF
    
```

```

constant    SKIPROM=0xCC
constant    CONVERT=0x44
constant    READ=0xBE

constant    MODE=0x38
constant    DISPLAY=0xF
constant    CEL=0XDF
constant    DQ=6
constant    RS=0
constant    RW=1
constant    E=2
    
```

```

LCD         EQU         PORTD
cblock
COUNT
IOBYTE
BYTE0
BYTE1
NEWTEMPER
TEMPER
TMP0
TRAM
CHUC
DV
TAM
TAM2
count
TEMP1
    
```

```

endc
org         0x000
bcf        STATUS,RP1
bsf        STATUS,RP0
clrf       TRISD
clrf       TRISC
bcf        TRISB,RS
bcf        TRISB,RW
bcf        TRISB,E
bcf        STATUS,RP0
    
```

```

BCF        PORTB,RS
BCF        PORTB,RW
MOVLW     MODE
CALL      EXEC_DLAY
MOVLW     DISPLAY
CALL      EXEC_DLAY
    
```

```

BSF        PORTB,RS
MOVLW     D'0'
MOVWF     TAM2
    
```

```

LOOP MOVF  TAM2,0
CALL  TABLE2
CALL  EXEC_DLAY
INCF  TAM2,1
MOVF  TAM2,0
SUBLW D'8'
BTFSS STATUS,Z
    
```

```

GOTO LOOP
GOTO DL
DLSIGBCF PORTB,RS
MOVLW 0xC4
CALL EXEC_DLAY
BSF PORTB,RS
MOVLW D'10'
CALL TABLE1
CALL EXEC_DLAY
GOTO DL2
DL BCF PORTB,RS
MOVLW 0xC4
call EXEC_DLAY
BSF PORTB,RS
MOVLW ''
call EXEC_DLAY
DL2 CALL DECODE

MAIN CALL RESET
movlw SKIPROM

CALL WRITE
movlw CONVERT
CALL WRITE
MOVLW D'50'
MOVWF TEMP1
AA CALL WAIT5000U
DECFSZ TEMP1,F
GOTO AA

CALL RESET
movlw SKIPROM
CALL WRITE
movlw READ
CALL WRITE
CALL READDS
MOVF IOBYTE,0
MOVWF BYTE0
CALL READDS
MOVF IOBYTE,0
MOVWF BYTE1
CALL RESET

MOVLW 0xF0
ANDWF BYTE0,1
SWAPF BYTE0,0
MOVWF NEWTEMPER
MOVLW 0X0F
ANDWF BYTE1,1
SWAPF BYTE1,0
IORWFNEWTEMPER,1
MOVF NEWTEMPER,0
MOVWF PORTC
XORWF TEMPER,0
BTFSC STATUS,Z
GOTO MAIN
MOVF NEWTEMPER,0
MOVWF TEMPER
MOVWF TAM
RLF TAM,0
BTFSC STATUS,C
GOTO SIG
GOTO DL
SIG COMF TAM,F
MOVLW D'1'
ADDWF TAM,1
GOTO DLSIG
;-----
OW_HIZ:MACRO
BSF STATUS,RP0
BSF TRISB,DQ
BCF STATUS,RP0
ENDM
;-----
OW_LO:MACRO
BSF STATUS,RP0
BCF TRISB,DQ
BCF STATUS,RP0
BCF PORTB,DQ
ENDM
;-----
WAIT:MACRO TIME
MOVLW (TIME/5) - 1 ;1μs to process
MOVWF TMP0 ;1μs to process
CALL WAIT5U ;2μs to process
ENDM
WAIT5U:

```

```

NOP          ;1µs to process
NOP          ;1µs to process
DECFSZ  TMP0,F  ;1µs if not zero or
GOTO    WAIT5U  ;2µs to process
RETLW   0        ;2µs to process

```

**WAIT5000U:**

```

WAIT .1000
WAIT .1000
WAIT .1000
WAIT .1000
WAIT .1000
RETLW 0

```

; -----

**RESET**

```

TRY  OW_LO
      WAIT      .500
      OW_HIZ
      WAIT      .60
      BTFSC  PORTB,DQ
      GOTO    TRY
      WAIT    .240
      BTFSS  PORTB,DQ
      GOTO    TRY
      WAIT    .180
      RETLW  0

```

; -----

**READDS**

```

      MOVLW      d'8'
      MOVWF     COUNT
RER  OW_LO

      NOP
      OW_HIZ
      NOP
      NOP

      BTFSS  PORTB,DQ
      BCF   STATUS,C
      BTFSC  PORTB,DQ
      BSF   STATUS,C
      RRF   IOBYTE,1
      WAIT .80
      DECFSZ  COUNT,1

```

```

GOTO  RER
      RETLW 0

```

**WRITE**

```

      MOVWF  IOBYTE
      MOVLW  D'8'
      MOVWF  COUNT
GHI
      OW_LO
      WAIT  .10
      BTFSC  IOBYTE,0
      GOTO  MUCCAO
      GOTO  MUCTHAP

```

**MUCCAO**

```

      OW_HIZ
      WAIT  .50
      RRF   IOBYTE,1
      DECFSZ  COUNT,1
      GOTO  GHI
      RETURN

```

**MUCTHAP**

```

      BCF   PORTB,6
      WAIT  .50
      OW_HIZ
      RRF   IOBYTE,1
      DECFSZ  COUNT,1
      GOTO  GHI
      RETURN

```

; -----

```

DECODE  MOVLW      D'0'
          MOVWF     TRAM
          MOVWF     CHUC
          MOVWF     DV
          MOVLW     d'100'
LB1    SUBWF     TAM,1
          INCF     TRAM,1
          BTFSC  STATUS,C
          GOTO  LB1
          DECF  TRAM,1
          ADDWF     TAM,1
          MOVLW     d'10'
LB2    SUBWF     TAM,1
          INCF     CHUC,1
          BTFSC  STATUS,C

```

```

GOTO LB2
DECF CHUC,1
ADDWF    TAM,0
MOVWF   DV
movf    TRAM,0
call   TABLE1
call   EXEC_DLAY
movf    CHUC,0
call   TABLE1
call   EXEC_DLAY
movf    DV,0
call   TABLE1
call   EXEC_DLAY
MOVLW   CEL
call   EXEC_DLAY
MOVLW   'C'
call   EXEC_DLAY
RETLW 0

```

```

EXEC_DLAY    movwf LCD
              bsf      PORTB,E
              bcf      PORTB,E
              movlw d'7'
              movwf count
delal        WAIT .200
              decfsz count,1
              goto  delal
              return

```

```

;-----
TABLE2      ADDWF    PCL,1
            DT      "CELSIUS:"

```

```

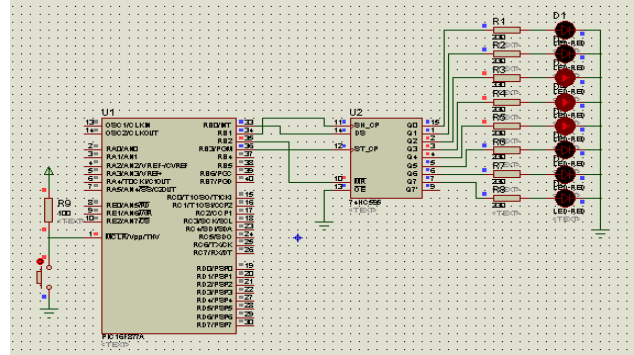
TABLE1      addwf    PCL,1
            DT      "0123456789-"
end

```

## Bài 20: pic 16f877a giao tiếp với ic 74HC595

### A. SỬ DỤNG NGÔN NGỮ ASSEMBLY

#### 1.test ic 74CH595:



#### title "giao tiep voi 74HC595"

```

;-----
processor 16f877a
include <p16f877a.inc>
;-----
; khai bao bien
;-----

sendreg EQU 0X20 ;chua du lieu can xuat ra ic 74hc595
count EQU 0X21 ;can de dem so bit du lieu can xuat ra
tam equ 0x22
;-----
; dinh nghia phan cung
;-----
#define dataa PORTB,0
#define clock PORTB,1
#define clear PORTB,2
#define latch PORTB,3
;-----
; Chuong trinh chinh
;-----
ORG 0x000
GOTO start

start      ;chuong trinh chinh
          BCF STATUS,RP1
          BCF STATUS,RP0 ;chon bank 0
          CLRF PORTB
          BSF STATUS,RP0 ;chon bank 1

```

```

MOVLW 0xF0    ;cac pin RB3,RB0 la output
MOVWF TRISB   ;cac pin RB7,RB3 la input

BCF STATUS,RP0 ;chon bank 0

MOVLW 0x04
MOVWF PORTB   ;dua sclr\ len mua logic cao

BCF clear    ;reset du lieu trong 74hc595

NOP           ;clear tac dong canh xuong

BSF clear
    movlw 0xff
    movf tam,1

lb
    MOVf tam,0
    CALL serout
    BSF latch
    NOP
    BCF latch
decf tam
    GOTO lb

serout
    MOVWF sendreg
    MOVLW 0x08
    MOVWF count

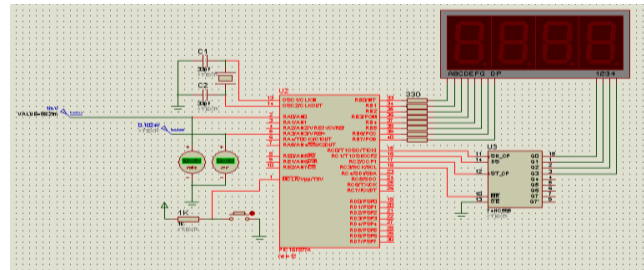
testbit
    BCF dataa
    BTFSC sendreg,7
    BSF dataa
    BSF clock
    NOP

    BCF clock
    RLF sendreg,0
    MOVWF sendreg
    DECFSZ count,1
    GOTO testbit

    RETURN
END

```

## 2. do nhiet do dung adc quet 74595



```

=====
TITLE      "ADC CONVERTER"
PROCESSOR  PIC16F877A
INCLUDE<P16F877A.INC>
    _CONFIG_CP_OFF & _WDT_OFF &
    _BODEN_OFF & _PWRTE_ON & _HS_OSC &
    _WRT_OFF & _CPD_OFF & _LVP_OFF
=====

```

### ;**KHAI BAO BIEN**

```

=====
CBLOCK    0X020
TR
CH
DV
TP

```

```

CAO
THAP

```

```

COUNT
TIME
ENDC

```

### ;**BAT DAU CHUONG TRINH CHINH**

```

=====
ORG 0X0000
START

```

### ;**KHOI TAO CAC PORT**

```

=====
BANKSEL   TRISB
CLRF TRISB ;KHOI TAO PORT B,C
CLRF TRISC
CLRF TRISD

```

### ;**KHOI TAO ADC**

```

=====
MOVLW B'10000101'; KHOI TAO THANH GHI ADCON1
MOVWF ADCON1; CANH LE PHAI, 2 NGO IN ANALOG,
VREF+=AN3
=====
;START GAME ^ _____ ^
=====
MAIN
    CALL DOC_ADC
    CALL BYTE_BCD
    CALL BCD_7DOAN
    CALL HIEN THI
    GOTO MAIN
=====
;CHUONG TRINH CON DOC ADC
=====
DOC_ADC
    BANKSEL    ADCON0           ;CHUYEN
DEN BANK 0 DEN SU DUNG THANH GHI ADCON0
    MOVLW      B'10000001'      ;CAP
NGUON CHUYEN DOI ADC,FOSC/32,IN ANALOG=AN0
    MOVWF     ADCON0
    MOVLW     .20
    MOVWF     TIME
TG_TRE
    DECFSZ    TIME,F
    GOTO TG_TRE
    BSF       ADCON0,2
GODONE
    BTFSC    ADCON0,2           ;BAT DAU CHUYEN DOI ADC
    GOTO GODON ;CHO CHUYEN ADC KET THUC
    MOVF     ADRESH,W
    MOVWF    CAO
;LUU DU LIEU CHUYEN DOI VAO BIEN ADC
    BANKSEL  ADRESL
    MOVF     ADRESL,W
    BANKSEL  THAP
    MOVWF    THAP
    RETURN
=====
;CHUONG TRINH CON CHUYEN DU LIEU ADC
SANG SO BCD
=====
BYTE_BCD
    CLRF    TR

```

```

    CLRF    CH
    CLRF    DV
SCH
    MOVLW   .100
    SUBWF   THAP,F
    BTFSS   STATUS,C
    GOTO    RDV
    INCF    CH
    GOTO    SCH
RDV
    ADDWF   THAP,F
SDV
    MOVLW   .10
    SUBWF   THAP,F
    BTFSS   STATUS,C
    GOTO    RTP
    INCF    DV
    GOTO    SDV
RTP
    ADDWF   THAP,W
    MOVWF   TP
    MOVF    CAO,W
    XORLW   0X01
    BTFSS   STATUS,Z
    GOTO    XET10
    MOVLW   .2
    ADDWF   CH,F
    MOVLW   .5
    ADDWF   DV,F
    MOVLW   .6
    ADDWF   TP,F
XET10
    MOVF    CAO,W
    XORLW   0X02
    BTFSS   STATUS,Z
    GOTO    XET11
    MOVLW   .5
    ADDWF   CH,F
    MOVLW   .1
    ADDWF   DV,F
    MOVLW   .2
    ADDWF   TP,F

```



**XET11**

```

MOVF CAO,W
XORLW    0X03
BTFSS STATUS,Z
GOTO NEXT
MOVLW    .7
ADDWF    CH,F
MOVLW    .6
ADDWF    DV,F
MOVLW    .8
ADDWF    TP,F

```

**NEXT**

```

MOVLW    .10
SUBWF    TP,F
BTFSS STATUS,C
GOTO PTP
INCF    DV
GOTO XETDV

```

**PTP**

```

ADDWF    TP,F

```

**XETDV**

```

MOVLW    .10
SUBWF    DV,F
BTFSS STATUS,C
GOTO PDV
INCF    CH
GOTO XETCH

```

**PDV**

```

ADDWF    DV,F

```

**XETCH**

```

MOVLW    .10
SUBWF    CH,F
BTFSS STATUS,Z
GOTO PCH
INCF    TR
GOTO THOAT

```

**PCH**

```

ADDWF    CH,F

```

```

THOAT

```

```

RETURN

```

```

;=====
;CHUONG TRINH CON CHUYEN MA BCD SANG 7 DOAN

```

**BCD\_7DOAN**

```

MOVF TR,W
CALL TABLE
MOVWF    TR

```

```

MOVF CH,W
CALL TABLE
MOVWF    CH

```

```

MOVF DV,W
CALL TABLE

```

```

MOVWF    DV
MOVLW    0X80
XORWF    DV,F

```

```

MOVF TP,W
CALL TABLE
MOVWF    TP

```

```

RETURN

```

```

;=====
;CHUONG TRINH CON HIEN THI

```

**HIEN THI**

```

MOVLW    0X0F
MOVWF    COUNT

```

**XUAT**

```

MOVF TR,W ;XUAT GIA TRI HANG TRAM
MOVWF    PORTB

```

```

CALL SH1
CALL DELAY
MOVLW    0XFF
MOVWF    PORTB

```

```

MOVF CH,W ;XUAT GIA TRI HANG CHUC
MOVWF    PORTB

```

```

CALL SH0
CALL DELAY
MOVLW    0XFF
MOVWF    PORTB

```

```

MOVF DV,W ;XUAT GIA TRI DON VI
MOVWF    PORTB

```

```

CALL SH0
CALL DELAY
MOVLW    0XFF
MOVWF    PORTB

MOVF TP,W ;XUAT GIA TRI THAP PHAN
MOVWF    PORTB
CALL SH0
CALL DELAY
MOVLW    0XFF
MOVWF    PORTB
CALL RST

DECFSZ   COUNT,F
GOTO XUAT
RETURN
    
```

=====

**;RESET DE CHO DAU RA QUET VE 0 CHUAN BI CHO CHU KY QUET MOI**

**;PLEASE READ DATASHEET FOR DETAIL OPERATION ^ \_\_\_\_\_ ^**

=====

```

RST
    BCF    PORTC,3
    BSF    PORTC,2
    BCF    PORTC,2
    BSF    PORTC,3
    
```

RETURN

=====

**;DICH RA BIT 1 O VI TRI BIT DAU**

**;READ DATASHEET FOR DETAIL OPERATION AGAIN ^ \_\_\_\_\_ ^ LOLOLOLOOLOLO**

=====

```

SH1
    BSF    PORTC,1
    BSF    PORTC,0
    BCF    PORTC,0
    BSF    PORTC,2
    BCF    PORTC,2
    
```

RETURN

=====

**;DICH RA BIT 0 DE DAY 1 CHAY**

**;SAME HERE,LOLOLOLOOLOLOLO .. READ THE DATASHEET ^ \_\_\_\_\_ ^**

```

=====
SH0
    BCF    PORTC,1
    BSF    PORTC,0
    BCF    PORTC,0
    BSF    PORTC,2
    BCF    PORTC,2
RETURN
    
```

=====

**;CHUONG TRINH CON DELAY**

=====

```

DELAY
    MOVLW    0XFF
    MOVWF    TIME
    DECFSZ   TIME
    GOTO $-1
RETURN
    
```

=====

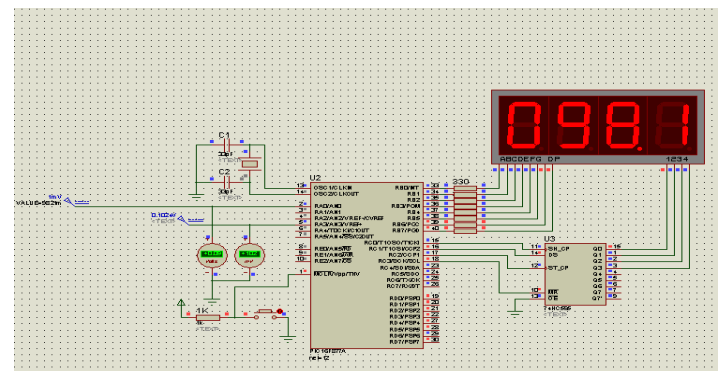
**;THU VIEN MA 7 DOAN**

=====

```

TABLE
    ADDWF   PCL,1
    DT
    0XC0,0XF9,0XA4,0XB0,0X99,0X92,0X82,0XF8,0
    X80,0X90
END
    
```

**B.SỬ DỤNG NGÔN NGỮ C**



```

#include <16F877A.H>
#include <KhaiBaoTGhi_16F877A.H>
#FUSES NOWDT,NOPROTECT,NOLVP,PUT,HS
#USE DELAY(CLOCK=2000000)
#DEFINE SCK RC0
    
```

```

#define SER RC1
#define RCK RC2
#define RESET RC3

UNSIGNED INT16 TAM=0;
INT8 TP,DV,CHUC,TRAM;
CONST UNSIGNED
MALED[10]={0XC0,0XF9,0XA4,0XB0,0X99,0X9
2,0X82,0XF8,0X80,0X90};

VOID HEX_BCD()
{
    TAM=(INT16) ADRESH;
    TAM=(INT16)(TAM<<2)+(INT16)(ADRE
SL>>6);
    TRAM= MALED[(INT8)(TAM/1000)];
    TAM=TAM% 1000;
    CHUC= MALED[(INT8)(TAM/100)];
    TAM=TAM% 100;
    DV= MALED[(INT8)(TAM/10)];
    TP=MALED[(INT8)(TAM% 10)];
}

VOID DICH1(VOID)
{
    RESET=1;
    SER=1;
    SCK=1;
    SCK=0;
    RCK=1;
    RCK=0;
}

VOID DICH0(VOID)
{
    RESET=1;
    SER=0;
    SCK=1;
    SCK=0;
    RCK=1;
    RCK=0; }

VOID RSOUT(VOID)
{
    RESET=0;
    RCK=1;
    RCK=0;
}

}

VOID HIEN THI()
{
    TAM=0;
    WHILE(TAM<100)
//SE XUAT RA 100 LAN TUONG UNG THOI GIAN
    {
        OUTPUT_B(TRAM);//DUA MA LED RA PORT B
        DICH1();
        DELAY_US(100);
        OUTPUT_B(0XFF);//DUA CAC CHAN CUA PORT B
        LEN TRANG THAI CHUAN BI NHAN INPUT

        OUTPUT_B(CHUC);//DUA MA LED RA PORT B
        DICH0();
        DELAY_US(100);
        OUTPUT_B(0XFF);//DUA CAC CHAN CUA PORT B
        LEN TRANG THAI CHUAN BI NHAN INPUT

        OUTPUT_B(DV);//DUA MA LED RA PORT B
        OUTPUT_BIT( PIN_B7, 0);
        DICH0();
        DELAY_US(100);
        OUTPUT_B(0XFF);//DUA CAC CHAN CUA PORT B
        LEN TRANG THAI CHUAN BI NHAN INPUT

        OUTPUT_B(TP);//DUA MA LED RA PORT B
        DICH0();
        DELAY_US(100);
        OUTPUT_B(0XFF);//DUA CAC CHAN CUA PORT B
        LEN TRANG THAI CHUAN BI NHAN INPUT
        RSOUT();
        TAM++;//TANG LAN DA XUAT GIO PHUT DAY
    }
}

VOID MAIN()
{
    TRISB=0;
    TRISC=0;
    TRISD=0;
    SETUP_ADC(ADC_CLOCK_INTERNAL);
    SETUP_ADC_PORTS(AN0_VREF_VREF);
    WHILE(1)
    {

```

```
    SET_ADC_CHANNEL(0);  
    DELAY_US(10);  
    READ_ADC();  
    HEX_BCD();  
    HIEN THI();  
}  
}
```